

MA/AMA 514

Today: TU matrices from graphs (§8.3, §8.4)

From last time:

A matrix $A \in \mathbb{R}^{m \times n}$ is totally unimodular (TU) if every square submatrix has determinant $0, \pm 1$.

Ex: $A = \begin{pmatrix} 1 & 1 \end{pmatrix}$ $A = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix}$ Non-ex: $A = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix}$ $\text{Det}(A) = -2!$

Prop: Let $A \in \{0, \pm 1\}^{n \times m}$ be a matrix with at most one "1" and at most one "-1" in each column. Then A is TU.

Cor: The node-edge incidence matrix of any directed graph is totally unimodular.

incidence matrix $A \in \{0, \pm 1\}^{V \times E}$ of a directed graph:

$$A_{ve} = \begin{cases} 1 & \text{if } e \in \delta^{\text{out}}(v) & e = (v, w) \text{ for some } w & \begin{array}{c} v \xrightarrow{e} w \end{array} \\ -1 & \text{if } e \in \delta^{\text{in}}(v) & e = (w, v) \text{ for some } w & \begin{array}{c} w \xrightarrow{e} v \end{array} \\ 0 & \text{otherwise} & & \end{cases}$$

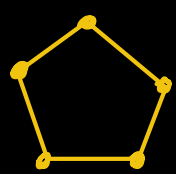
§8.3 Connections with bipartite graphs

The incidence matrix A of a graph $G = (V, E)$

is a $|V| \times |E|$ matrix with $(A)_{ve} = \begin{cases} 1 & \text{if } v \in e \\ 0 & \text{if } v \notin e \end{cases}$

Thm 8.3 G is bipartite $\Leftrightarrow A$ is totally unimodular

(Proof) (\Leftarrow) G not bipartite $\Rightarrow G$ has an odd circuit.



$$\begin{pmatrix} 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 0 & 1 \end{pmatrix}$$

Corresponding submatrix has determinant $\neq 2$.

subgraph \leftrightarrow

submatrix

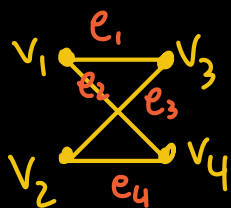
$\Rightarrow A$ not TU

(\Rightarrow) Suppose G is bipartite with $V = U \cup W$.

Consider directed graph D obtained by orienting all edges from $U \rightarrow W$. The incidence matrix of D is obtained from that of G by multiplying rows indexed by $w \in W$ by -1 .

A_D is TU $\Rightarrow A_G = \begin{pmatrix} I_U & 0 \\ 0 & -I_W \end{pmatrix} A_D$ is TU.

Ex:



$$\begin{matrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{matrix} \begin{pmatrix} e_1 & e_2 & e_3 & e_4 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ -1 & 0 & -1 & 0 \\ 0 & -1 & 0 & -1 \end{pmatrix} \begin{matrix}] U \\] W \end{matrix}$$

Cor: For any bipartite graph G , the polyhedra are integer:

$$\{x \in \mathbb{R}_{\geq 0}^E : Ax \leq \mathbb{1}_V\}$$

$$\{y \in \mathbb{R}_{> 0}^V : y^T A \geq \mathbb{1}_E^T\}$$

$$\{x \in \mathbb{R}_{\geq 0}^E : Ax \geq \mathbb{1}_V\}$$

$$\{y \in \mathbb{R}_{\geq 0}^V : y^T A \leq \mathbb{1}_E^T\}$$

Cor: For bipartite graphs, $\{x \in \mathbb{R}_{\geq 0}^E : Ax \leq \mathbb{1}_V\} = \text{Conv} \{ \mathbb{1}_M : M \subseteq E \text{ matching} \}$

(\supseteq) Clear.

(\subseteq) All vertices integer \Rightarrow equal to $\mathbb{1}_M$ for some matching M

Cor: For bipartite graphs, $\alpha(G) = \max \{ \sum_{e \in E} x_e : x \in \mathbb{R}_{\geq 0}^E, Ax \leq \mathbb{1}_V \}$

Similar results for $\nu(G), \tau(G), \rho(G)$.

Cor: For any bipartite graph G , $\nu(G) = \tau(G)$ and $\alpha(G) = \rho(G)$

(By linear programming duality!)

Applications to interval scheduling

Call $A \in \{0,1\}^{m \times n}$ an interval matrix if the 1's in each row are consecutive (transposed version also used: consecutive 1's in each column).

Prop: If $A \in \{0,1\}^{m \times n}$ is an interval matrix then A is totally unimodular.

(Proof) Let M be a $k \times k$ submatrix of A^T . $\Rightarrow M$ has consec. 1's.

$$\begin{pmatrix} 1 & 0 & 1 & 0 & 0 \\ 1 & 1 & 1 & 0 & 1 \\ 1 & 1 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 & 0 \end{pmatrix}$$

Take $U \in \mathbb{R}^{k \times k}$ with $U_{ij} = \begin{cases} 1 & \text{if } j=i \\ -1 & \text{if } j=i-1 \\ 0 & \text{o.w.} \end{cases}$ $U = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & -1 & 1 \end{pmatrix}$

$\Rightarrow \det(U) = 1$ and UM has i^{th} row $m_i - m_{i-1}$ where $m_i = i^{\text{th}}$ row of M

Since M had consecutive ones, UM has at most one 1

and at most one -1 in each column $\Rightarrow UM$ totally unimod

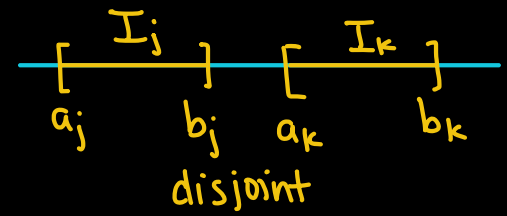
$\Rightarrow \det(M) = \det(UM) \in \{0, \pm 1\}$

$$\text{Ex: } \begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 & 0 \\ 0 & -1 & 1 & 0 & 0 \\ 0 & 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & -1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 \\ 1 & 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & -1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & -1 & 1 \end{pmatrix}$$

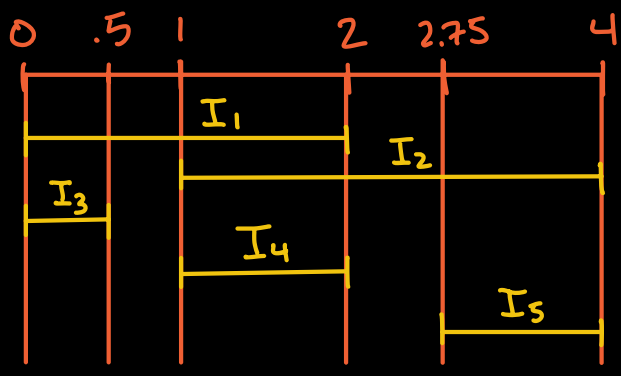
Cor: All vertices of $\{x \in \mathbb{R}^n : Ax \leq 1, 0 \leq x \leq 1\}$ are integer.

Interval Scheduling
Input: intervals I_1, \dots, I_n with values $c_1, \dots, c_n \in \mathbb{R}$
Goal: Select a disjoint subset of intervals I_{i_1}, \dots, I_{i_k} to maximize value $c_{i_1} + \dots + c_{i_k}$

$$I_j = [a_j, b_j] \subseteq \mathbb{R}$$



Ex: $I_1 = [0, 2], I_2 = [1, 4], I_3 = [0, .5], I_4 = [1, 2], I_5 = [2.75, 4]$
 $c_1 = 4, c_2 = 5, c_3 = 1, c_4 = 2, c_5 = 3$



Some feas. sol. and values
 $\{I_1, I_5\} \rightarrow c_1 + c_5 = 7$
 $\{I_2, I_3\} \rightarrow c_2 + c_3 = 6$
 $\{I_3, I_4, I_5\} \rightarrow c_3 + c_4 + c_5 = 6$

Interval scheduling IP:

variables $x_1, \dots, x_n \in \{0, 1\}$ $x_j = \begin{cases} 1 & \leftrightarrow \text{pick } I_j \\ 0 & \leftrightarrow \text{don't pick } I_j \end{cases}$

How to encode disjointness of chosen intervals?

Let $t_1 < t_2 < \dots < t_m$ be the set of all endpoints $\bigcup_{j=1}^n \{a_j, b_j\}$.

Claim: $\{I_{i_1}, \dots, I_{i_k}\}$ are disjoint

\Leftrightarrow for all $j=1, \dots, m$, at most one I_{i_ℓ} contains t_j

(Proof) (\Rightarrow) $t_j \in I_{i_1} \cap I_{i_2} \Rightarrow I_{i_1}, I_{i_2}$ not disjoint!

(\Leftarrow) If $I_{i_1} \cap I_{i_2}$ not disjoint, $\max(I_{i_1} \cap I_{i_2}) = b_{i_1}$ or $b_{i_2} = t_j$ for some j

Interval scheduling solved by

(IP) $\max c^T x$ s.t. $0 \leq x \leq 1, x \in \mathbb{Z}^n$

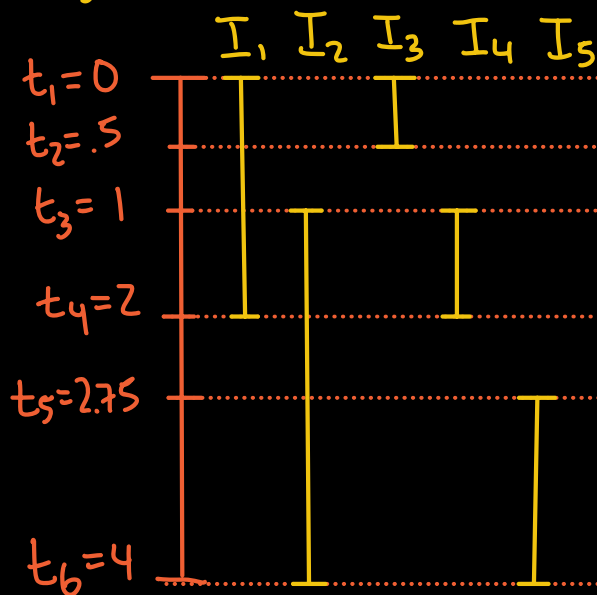
$$\sum_{i \text{ s.t. } t_j \in I_i} x_i \leq 1 \quad \text{for all } j=1, \dots, m$$

Encode as $Ax \leq 1$

with $A \in \{0, 1\}^{m \times n}$, $A_{ji} = \begin{cases} 1 & \text{if } t_j \in I_i \\ 0 & \text{if } t_j \notin I_i \end{cases}$

Ex (above)

$$A = \begin{matrix} & I_1 & I_2 & I_3 & I_4 & I_5 \\ \begin{matrix} t_1 \\ t_2 \\ t_3 \\ t_4 \\ t_5 \\ t_6 \end{matrix} & \begin{pmatrix} 1 & 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 \\ 1 & 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 1 \end{pmatrix} \end{matrix}$$



Note: since $t_1 < t_2 < \dots < t_m$, $t_j \in I_i, t_k \in I_i \Rightarrow t_l \in I_i, \forall j \leq l \leq k$
 \Rightarrow the ones in each column of A are consecutive

Cor: The LP relaxation

$$(LP) \max c^T x \text{ s.t. } 0 \leq x \leq 1, Ax \leq 1$$

Solves interval scheduling (in polynomial time).

(Proof) Opt. val. attained at a vertex x^*

$$\Rightarrow x^* \text{ integer} \Rightarrow x^* \in \{0, 1\}^n$$

$$\Rightarrow \text{take } I_{i_1}, \dots, I_{i_k} \text{ where } \{i_1, \dots, i_k\} = \{i : x_i^* = 1\}$$