

Math 407

Today: Sensitivity Analysis for Tableaux

In equational form: $\max c^T x$ s.t. $Ax=b, x \geq 0$

Recall, the simplex tableau of a feasible basis B is

$$\begin{aligned} x_B &= p + Qx_N & p &= A_B^{-1}b & Q &= -A_B^{-1}A_N \\ z &= z_0 + r^T x_N & z_0 &= c_B^T A_B^{-1}b & r^T &= c_N^T - c_B^T A_B^{-1}A_N \end{aligned}$$

Same sol as $A_B x_B + A_N x_N = b, z = c_B^T x_B + c_N^T x_N$

$$\begin{aligned} \Rightarrow x_B &= A_B^{-1}b - A_B^{-1}A_N x_N, \\ z &= c_B^T (A_B^{-1}b - A_B^{-1}A_N x_N) + c_N^T x_N \end{aligned}$$

Recall: B corresponds to the point given by $Ax=b, x_N=0$
namely $x_B = A_B^{-1}b = p, x_N = 0$
 $z_0 =$ value of $c^T x$ at this point.

Similar in the dual space B corresponds to the solution of $A^T y - s = c$ with $s_B = 0$,

namely $s_B = 0, s_N = -r, y =$ solution to $A^T y = s + c$
 $z_0 =$ value of $b^T y$ at this point

Suppose a basis B is feasible and dual feasible (p ≥ 0) (r ≤ 0)

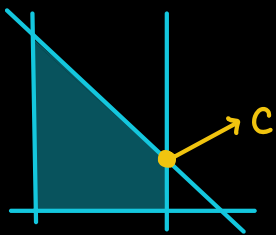
Changing $c \rightarrow \tilde{c}$: only r changes

$\Rightarrow B$ always remains feasible

$$B \text{ remains dual feasible} \Leftrightarrow \tilde{c}_N^T - \tilde{c}_B^T A_B^{-1} A_N \leq 0.$$

Reasonable hope: If B is no longer dual feasible after changing $c \rightarrow \tilde{c}$, then it should only be a few pivot steps away from the (new) optimal basis (if the problem remains bounded)

Ex: $\max 5x_1 + 4x_2$ s.t. $x_1 + x_2 + x_3 = 3$ $\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} \geq 0$
 $x_1 + x_4 = 2$



$$A = \begin{pmatrix} 1 & 1 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{pmatrix} \quad b = \begin{pmatrix} 3 \\ 2 \end{pmatrix} \quad c = \begin{pmatrix} 5 \\ 4 \\ 0 \\ 0 \end{pmatrix}$$

Opt sol: $x^* = \begin{pmatrix} 2 \\ 1 \\ 0 \\ 0 \end{pmatrix}$ $A_B = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}$ $A_N = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$

Opt. basis: $\{1, 2\}$ $A_B^{-1} = \begin{pmatrix} 0 & 1 \\ 1 & -1 \end{pmatrix}$ $c_B = \begin{pmatrix} 5 \\ 4 \end{pmatrix}$ $c_N = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

$\tilde{c} = c + t e_2$ $\tilde{c}_B = \begin{pmatrix} 5 \\ 4+t \end{pmatrix}$ $\tilde{c}_N = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

$\tilde{c}_N^T - \tilde{c}_B^T A_B^{-1} A_N = -(5 \ 4+t) \begin{pmatrix} 0 & 1 \\ 1 & -1 \end{pmatrix} = (-4-t, -1+t)$

$B = \{1, 2\}$ remains dual feasible $\Leftrightarrow -4 \leq t \leq 1$

$$T(\{1, 2\}) \quad x_1 = 2 \quad -x_4$$

$$x_2 = 1 \quad -x_3 + x_4$$

$$z = 14 + t - (4+t)x_3 + (-1+t)x_4$$

$t = 2$

$T(\{1, 2\})$

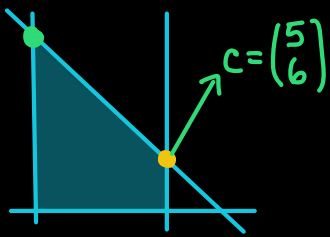
$$x_1 = 2 \quad -x_4$$

$$x_2 = 1 \quad -x_3 + x_4$$

$$z = 16 - 6x_3 + x_4$$

no longer
dual feasible
 \rightarrow pivot!

x_4 enters, x_1 leaves



$$T(\{2, 4\}): \begin{aligned} x_2 &= 3 - x_1 - x_3 \\ x_4 &= 2 - x_1 \\ z &= 18 - x_1 - 6x_3 \end{aligned} \quad \text{new opt sol: } \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 3 \\ 0 \\ 2 \end{pmatrix}$$

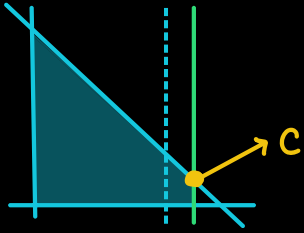
Changing $b \rightarrow \tilde{b}$: only p changes

$\Rightarrow B$ always remains dual feasible

B remains feasible $\Leftrightarrow A_B^{-1}b \geq 0$

Reasonable hope: If B is no longer feasible after changing $b \rightarrow \tilde{b}$, then it should only be a few dual pivot steps away from the (new) optimal basis (if the problem remains feasible)

Ex: $\max 5x_1 + 4x_2$ s.t. $x_1 + x_2 + x_3 = 3$ $\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} \geq 0$
 $x_1 + x_4 = 2 + t$



$B = \{1, 2\}$ remains dual feasible

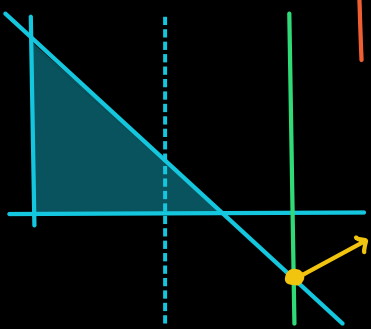
$$\Leftrightarrow 0 \leq A_B^{-1} \tilde{b} = \begin{pmatrix} 0 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 3 \\ 2+t \end{pmatrix} = \begin{pmatrix} 2+t \\ 1-t \end{pmatrix}$$

$$\Leftrightarrow -2 \leq t \leq 1$$

$$\begin{aligned} \mathcal{T}(\{1, 2\}) : \quad & x_1 = 2+t && -x_4 \\ & x_2 = 1-t && -x_3 + x_4 \\ & z = \underline{14+t} && -4x_3 - x_4 \end{aligned}$$

\uparrow = val of $c^T x$ at $x = (2+t, 1-t, 0, 0)$

$t=2$



$$\begin{aligned} \mathcal{T}(\{1, 2\}) : \quad & x_1 = 4 && -x_4 && \text{no longer feasible} \\ & x_2 = \underline{-1} && -x_3 + x_4 && \rightarrow \text{dual pivot} \\ & z = 16 && -4x_3 - x_4 && x_2 \text{ leaves} \\ & && && x_4 \text{ enters} \end{aligned}$$

$$\begin{aligned} \mathcal{T}(\{1, 4\}) : \quad & x_1 = 3 - x_2 - x_3 \\ & x_4 = 1 + x_2 + x_3 \\ & z = 15 - x_2 - 5x_3 \end{aligned}$$

new opt solution: $\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 3 \\ 0 \\ 0 \\ 1 \end{pmatrix}$

What happens for $t = -3$?