

Math 407 - Linear Optimization

LP: $\max c^T x$ s.t. $Ax=b, x \geq 0$

where $c \in \mathbb{R}^n, A \in \mathbb{R}^{m \times n}, b \in \mathbb{R}^m, \text{rank}(A)=m$

Recall: $B \subseteq \{1, \dots, n\}$ with $|B|$ is a basis if A_B is invertible

\Leftrightarrow unique $v \in \mathbb{R}^n$ with $Av=b$ with $v_j=0$ for $j \notin B$

B is a feasible basis if $v \geq 0$ $\nearrow v_B = A_B^{-1}b$

$\Leftrightarrow v$ is a basic feasible solution of the LP

$x_B = (x_j : j \in B)$ "basic variables"

$|B|=m$

$x_N = (x_j : j \in N)$ "non-basic variables" $N = \{1, \dots, n\} \setminus B$

$|N|=n-m$

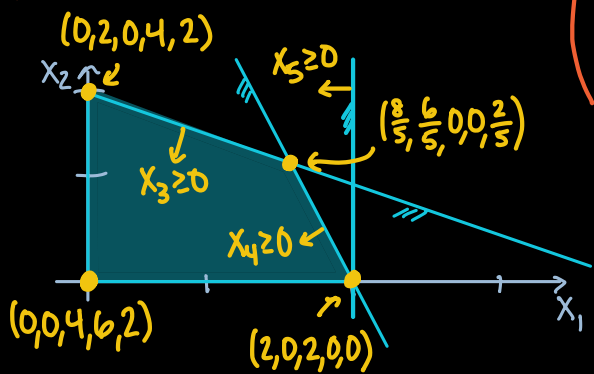
Non-basic variables as coordinates

We can parametrize $\{x \in \mathbb{R}^n : Ax=b\}$ with non-basic var x_N :

$Ax = A_B x_B + A_N x_N = b \Leftrightarrow x_B + A_B^{-1} A_N x_N = A_B^{-1} b$

$\Leftrightarrow x_B = A_B^{-1} b - A_B^{-1} A_N x_N$

Ex: $\max x_1 - x_2$ s.t. $\begin{pmatrix} 1 & 2 & 1 & 0 & 0 \\ 3 & 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{pmatrix} = \begin{pmatrix} 4 \\ 6 \\ 2 \end{pmatrix} \quad \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{pmatrix} \geq \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$



$B = \{3, 4, 5\}$

$x_3 = 4 - x_1 - 2x_2$

$x_4 = 6 - 3x_1 - x_2$

$x_5 = 2 - x_1$

basic feas. sol. given by $B : (0, 0, 4, 6, 2)$

non basic var $x_1=0, x_2=0$

Def: The simplex tableau, $T(B)$, of a feasible basis $B \subseteq \{1, \dots, n\}$ is a system of $m+1$ equations in the $n+1$ variables x_1, \dots, x_n, z with

1) the same set of solutions as $Ax=b, z=c^T x$

2) the form $X_B = p + Q X_N$

$$z = z_0 + r^T X_N$$

with $p \in \mathbb{R}^m, r \in \mathbb{R}^{n-m}, Q \in \mathbb{R}^{m \times (n-m)}, z_0 \in \mathbb{R}$

Idea: $Ax=b \Leftrightarrow X_B = \underbrace{A_B^{-1}b}_p - \underbrace{A_B^{-1}A_N}_{Q} X_N$

$$c^T x = c_B^T X_B + c_N^T X_N = c_B^T (A_B^{-1}b - A_B^{-1}A_N X_N) + c_N^T X_N$$

$$\Rightarrow z_0 = c_B^T A_B^{-1}b \quad r = c_N - (c_B^T A_B^{-1}A_N)^T$$

Basic feas. sol. corresponding to $B: (x_B, x_N) = (p, 0)$

Value of $c^T x$ at this point: z_0 \leftarrow Why? $z = c^T x = z_0 + r^T x_N = z_0$ when $x_N=0$

In Ex: $T(\{3,4,5\})$

$$x_3 = 4 - x_1 - 2x_2$$

$$x_4 = 6 - 3x_1 - x_2$$

$$x_5 = 2 - x_1$$

$$z = 0 + x_1 - x_2$$

$$X_B = \begin{pmatrix} x_3 \\ x_4 \\ x_5 \end{pmatrix}$$

$$p = \begin{pmatrix} 4 \\ 6 \\ 2 \end{pmatrix}$$

$$Q = \begin{pmatrix} -1 & -2 \\ -3 & -1 \\ -1 & 0 \end{pmatrix}$$

$$X_N = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$z_0 = 0$$

$$r = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$T(\{3,4,5\})$$

$$x_3 = 4 - x_1 - 2x_2$$

$$x_4 = 6 - 3x_1 - x_2 \xrightarrow{x_1 \rightarrow 2-x_5}$$

$$x_5 = 2 - x_1$$

$$z = 0 + x_1 - x_2$$

$$T(\{1,3,4\})$$

$$x_1 = 2 - x_5$$

$$x_3 = 4 - (2 - x_5) - 2x_2$$

$$x_4 = 6 - 3(2 - x_5) - x_2$$

$$z = 0 + (2 - x_5) - x_2$$

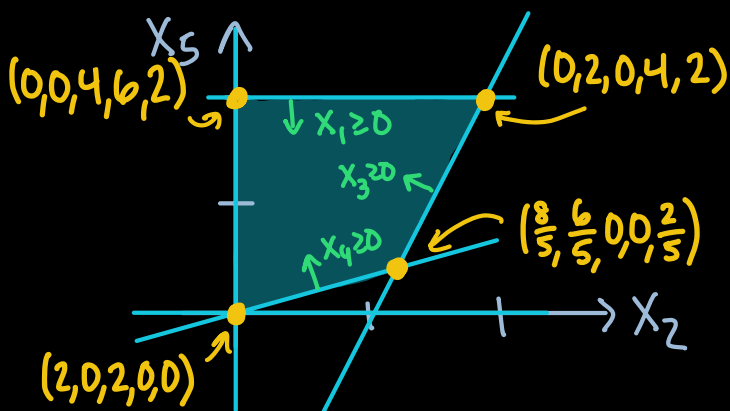
(use x_2, x_5 as parameters)

$$x_1 = 2 - x_5$$

$$x_3 = 2 - 2x_2 + x_5$$

$$x_4 = 0 - x_2 + 3x_5$$

$$z = 2 - x_2 - x_5$$



Corresp. basic feas. sol: $(2, 0, 2, 0, 0)$ $\left. \begin{matrix} x_2=0 \\ x_5=0 \end{matrix} \right\}$

val. of $c^T x$ at \uparrow : 2 (plug $x_2=0, x_5=0$ into z)

Obj function: $2 - x_2 - x_5$

Since $x_2 \geq 0, x_5 \geq 0$, this is ≤ 2

\Rightarrow basic feas. sol. $(2, 0, 2, 0, 0)$ is optimal

More generally, if B is a feasible basis and $r \leq 0$ in $T(B)$, then

$z_0 = \text{opt. value}$

$(x_B, x_N) = (p, 0)$ an opt. solution

$$\left(\begin{array}{l} T(B): x_B = p + Q x_N \\ z = z_0 + r^T x_N \end{array} \right)$$

Why? obj function takes value z_0 at $(x_B, x_N) = (p, 0)$

\Rightarrow opt. value $\geq z_0$

$x_N \geq 0$ on feas. region $\Rightarrow r^T x_N \leq 0$

$\Rightarrow c^T x = z_0 + r^T x_N \leq z_0$

\Rightarrow opt. value $\leq z_0$

Subtlety: Different bases can give the same basic feasible solution! (when $> n-m$ coordinates are zero)

In Ex: $\{1,3,4\} \xrightarrow{x_2=x_5=0} v = (2,0,2,0,0)$
 $\{1,3,5\} \xrightarrow{x_2=x_4=0}$
 $\{1,2,3\} \xrightarrow{x_4=x_5=0}$

These all correspond to the same basic feas. sol. v but their tableaux will look different!

$\mathcal{T}(\{1,2,3\})$

$$x_1 = 2 - x_5$$

$$x_2 = 0 - x_4 + 3x_5$$

$$x_3 = 2 + 2x_4 - 5x_5$$

$$z = 2 + x_4 - 4x_5$$

basic feas. solution $v = (2,0,2,0,0)$ is optimal, but we can't see it from $\mathcal{T}(\{1,2,3\})$!