The Cauchy problem for Schrödinger flows into Kähler manifolds

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Abstract. We prove local well-posedness of the Schrödinger flow from $\mathbb{R}^n$ into a compact Kähler manifold $N$ with initial data in $H^{s+1}(\mathbb{R}^n, N)$ for $s \geq \left[ \frac{n}{2} \right] + 4$.

1. Introduction

We consider maps

$$u : \mathbb{R}^n \to N$$

where $N$ is a $k$-dimensional compact Kähler manifold with complex structure $J$ and Kähler form $\omega$ (so that $\omega$ is a nondegenerate, skew-symmetric two-form). Thus $N$ is a complex manifold and $J$ is an endomorphism of the tangent bundle whose square, at each point, is minus the identity. $N$ has a Riemannian metric $g$ defined by

$$g(\cdot, \cdot) = \omega(\cdot, J \cdot).$$

The condition that $N$ is Kähler is equivalent to assuming that $\nabla J = 0$ where $\nabla$ is the Levi-Civita covariant derivative with respect to $g$. The energy of a map $u$ is defined by

$$E(u) = \frac{1}{2} \int_{\mathbb{R}^n} |du|^2 dx$$

where the energy density $|du|^2$ is simply the trace with respect to the Euclidean metric of the pullback of the metric $g$ under $u$, $|du|^2 = \text{Tr} u^*(g)$. In local coordinates we have

$$|du|^2(x) = \sum_{\alpha=1}^n g_{ij}(u(x)) \frac{\partial u^i}{\partial x^\alpha} \frac{\partial u^j}{\partial x^\alpha}.$$

(We use the Einstein summation convention and sum over repeated indices.)

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The $L^2$-gradient of $E(u)$ is given by minus the tension of the map, $-\tau(u)$, $\tau(u)$ is a vector field on $N$ which can be expressed in local coordinates as $\tau(u) = (\tau(u)^1, \ldots, \tau(u)^k)$ with

$$\tau^i(u) = \Delta u^i + \sum_{\alpha=1}^{n} \Gamma_{jk}^{i}(u) \frac{\partial u^j}{\partial x^\alpha} \frac{\partial u^k}{\partial x^\alpha} \quad \text{for} \quad i = 1, \ldots, k$$

where $\Gamma_{jk}^{i}(u)$ are the Christoffel symbols of the metric $g$ at $u(x)$. Critical points of the energy are Harmonic maps and are characterized by the equation $\tau(u) = 0$. The foundational result on the existence of harmonic maps is due to Eells and Sampson \[14\] and is achieved by studying the harmonic map flow

$$\frac{\partial u}{\partial t} = \tau(u)$$

which is simply the gradient flow for the energy functional on the space of maps. Eells and Sampson proved the existence of harmonic maps as stationary points of this flow when the domain is a compact manifold and the target is a compact manifold of non-positive curvature. In our setting, the symplectic structure on $N$ induces a symplectic structure on the space of maps. Let $X_s = H^s(\mathbb{R}^n, N)$ be the Sobolev space of maps between $\mathbb{R}^n$ and $N$ as defined below. For $s \geq \frac{n}{2} + 1$, $X_s$ is a Banach manifold with a symplectic structure $\Omega$ induced from that of $(N, \omega)$ as follows. The tangent space to $X_s$ at a map $u$ is identified with sections of the pull-back tangent bundle over $\mathbb{R}^n$. We let $\Gamma(V)$ denote the space of sections of the bundle $V$, for example $du \in \Gamma(T^*\mathbb{R}^n \otimes u^{-1}(TN))$. For $\sigma, \mu \in \Gamma(u^{-1}(TN)) = T_uX_s$ we define

$$\Omega(\sigma, \mu) = \int_{\mathbb{R}^n} \omega(\sigma, \mu) dx.$$ 

In this setting we are interested in the Hamiltonian flow for the energy functional $E(\cdot)$ on $(X_s, \Omega)$. This is the Schrödinger flow which takes the form

$$\frac{\partial u}{\partial t} = J(u)\tau(u).$$

This natural geometric motivation for the flow (1.2) was elucidated in \[12\].

A key aspect of our approach to understanding the flow (1.2) is to isometrically embed $N$ in some Euclidean space $\mathbb{R}^p$ and study “ambient” flows of maps from $\mathbb{R}^n$ to $\mathbb{R}^p$ which are related to (1.2). This is also central to the Eells-Sampson treatment of the harmonic map flow. Toward this end we use the Nash embedding theorem to assume that we have an isometric embedding

$$w : (N, g) \to (\mathbb{R}^p, \delta).$$

Using this we can now define $H^s(\mathbb{R}^n; N)$, the $L^2$-based Sobolev spaces of maps from $\mathbb{R}^n$ to $N$ as follows. Note that since the domain is noncompact some care must be taken even when $s = 0$.

**Definition 1.1.** For $s \geq 1$ let

$$H^s(\mathbb{R}^n; N) = \{ u : \mathbb{R}^n \to \mathbb{R}^p : u(x) \in N \text{ a.e. and } \exists y_u \in N \text{ such that } v - w(y_u) \in L^2(\mathbb{R}^n; \mathbb{R}^p), \partial v \in H^{s-1}(\mathbb{R}^n; \mathbb{R}^p), \text{ where } v = w \circ u \}.$$ 

With this definition in mind we can state our main result.
Theorem 1.2. Given $\beta \geq 0$, the initial value problem
\begin{equation}
\begin{cases}
\frac{\partial u}{\partial t} = J(u)\tau(u) + \beta \tau(u) \\
u(0) = u_0
\end{cases}
\end{equation}
for the generalized Schrödinger flow has a solution whenever the initial data $u_0 \in H^{s+1}(\mathbb{R}^n, N)$ for $s \geq \left[\frac{n}{2}\right] + 4$. Moreover (1.4) is locally well posed in $H^{s+1}(\mathbb{R}^n, N)$ for $s \geq \left[\frac{n}{2}\right] + 4$.

The question of the local and global well-posedness of equation (1.4) with data in Sobolev spaces has been previously studied by many authors (see [12, 13, 11, 35, 36, 42, 10, 33, 34, 43, 44, 31, 32, 20, 23, 21]). A common feature in most existence results for smooth solutions of Schrödinger maps is that they are obtained by using the energy method. This method consists in finding an appropriate regularizing equation which approximates the Schrödinger flow, and for which smooth solutions exist. One then proves that the regularizing equations satisfy a priori bounds in certain Sobolev norms, independent of the approximation, and that they converge to a solution of the original equation. The differences in the distinct results and proofs lie in the type of regularization used.

Ding and Wang [13] established a similar result to Theorem 1.2 for $s \geq \left[\frac{n}{2}\right] + 3$. Their work proceeds by direct study of equation (1.4) with $\beta > 0$, with a passage to the limit for $\beta = 0$. Thus the regularizing equation they use is obtained by adding the second order dissipative term $\beta \tau(u)$. In this paper we analyze equation (1.4) by adding a fourth order dissipative term (note that we allow the case $\beta = 0$ from the start). This term arises naturally in the geometric setting as the first variation of the $L^2$-norm of the tension. We believe that our regularization of (1.4) by a fourth order equation, which is geometric in nature, is of intrinsic and independent interest. H. McGahagan [31, 32] in her doctoral dissertation also proved a version of Theorem 1.2. Her work proceeds by a different regularization, this time hyperbolic, implemented by adding a term of the form $-\epsilon \frac{\partial^2 u}{\partial t^2}$ which transforms the equation into one whose solutions are wave maps.

We note that while our existence proof in Theorem 1.2 is different from the ones in [13] and [31, 32], our proof of uniqueness is the same, using parallel transport. In fact, in Appendix A we extend the uniqueness argument in [32], carried out there in the case when $\beta = 0$ to the case $\beta \geq 0$, which gives the uniqueness statement in Theorem 1.2.

Our proof of Theorem 1.2 actually only shows that the mapping $u_0 \mapsto u \in C([0, T], H^{s+1}(\mathbb{R}^n, N))$, with $s' < s$, is continuous. However, one can show, by combining the parallel transport argument with the standard Bona-Smith regularization procedure ([8, 19, 22]) that the statement in Theorem 1.2 also holds.

Equations of the type (1.4), but with $N$ being Euclidean space are generally known as derivative Schrödinger equations and have been the object of extensive study recently (see for instance [26, 16, 9, 15, 27, 28, 24, 25]). The results in these investigations however do not apply directly to (1.4) for two reasons. The first one is the constraint imposed by the target being the manifold $N$. The second one is that in these works one needs to have data $u_0$ in a weighted Sobolev space, a condition that we would like to avoid in the study of (1.4).

It turns out that for special choices of the target $N$, the equations (1.4) are related to various theories in mechanics and physics. They are examples of gauge theories which are abelian in the case of Riemann surfaces (Kähler manifolds of
dimension 1 such as the 2-sphere $S^2$ or hyperbolic 2-space $H^2$. In the case of the 2-sphere $S^2$, Schrödinger maps arise naturally from the Landau-Lifschitz equations (a $U(1)$-gauge theory) governing the static as well as dynamical properties of magnetization \cite{30,38}. More precisely, for maps $s : \mathbb{R} \times \mathbb{R}^n \to S^2 \hookrightarrow \mathbb{R}^3$, equation (1.4) takes the form

\begin{equation}
\partial_t s = s \times \Delta s, \quad |s| = 1
\end{equation}

which is the Landau-Lifschitz equation at zero dissipation, when only the exchange field is retained \cite{29,38}. When $n = 2$ this equation is also known as the two-dimensional classical continuous isotropic Heisenberg spin model (2d-CCIHS); i.e. the long wave length limit of the isotropic Heisenberg ferromagnet (\cite{29,38,42}). It also occurs as a continuous limit of a cubic lattice of classical spins evolving in the magnetic field created by their close neighbors \cite{42}. The paper \cite{42} contains, in fact, for the cases $n = 1, 2, N = S^2$ the first local well-posedness results for equation (1.4) or (1.5) that we are aware of. In \cite{10}, Chang-Shatah-Uhlenbeck showed that, when $n = 1$, (1.5) is globally (in time) well-posed for data in the energy space $H^1(\mathbb{R}^1; S^2)$. When $n = 2$, for either radially symmetric or $S^1$-equivariant maps, they show that small energy implies global existence. For global existence results see also \cite{39}. In \cite{33,34}, the authors show that, when $n = 2$, the problem is locally well-posed in the space $H^{2+\epsilon}(\mathbb{R}^2; S^2)$, while the existence was extended to the space $H^{3/2+\epsilon}(\mathbb{R}^2; S^2)$ in \cite{20} and \cite{23}, and the uniqueness to the space $H^{7/4+\epsilon}(\mathbb{R}^2; S^2)$ in \cite{21}.

More recently, in \cite{3,17}, a direct method, in the case of small data, using fixed point arguments in suitable spaces was introduced. The first global well-posedness result for (1.5) in critical spaces (precisely, global well-posedness for small data in the critical Besov spaces in dimensions $n \geq 3$) was proved, independently in \cite{18} and \cite{4}. This was later improved to global regularity for small data in the critical Sobolev spaces in dimensions $n \geq 4$ in \cite{5}. Finally, in \cite{6}, the global well-posedness of (1.5), for “small data” in the critical Sobolev space $H^{\frac{n}{2}}(\mathbb{R}^n, S^2)$, $n \geq 2$, was proved.

Remark 1.3. A first version of this paper was posted on arxiv:0511701, in November 2005, by C.K., D.P., G.S. and T.T. The paper was withdrawn in May 2007. The reason for this was that Jesse Holzer, at the time a graduate student of Alex Ionescu at the University of Wisconsin, Madison, discovered an error in the original argument. The source of the error was in the construction of the ambient flow equations, which were introduced in the first version of the paper. The construction of the ambient flow equations resulted in equations of quasilinear type in the leading order term, which could not be solved by the Duhamel principle as was pointed out by Holzer.

C.K., D.P., G.S. and T.T. are indebted to Jesse Holzer for pointing out this error and to T.L., who constructed new ambient flow equations, whose leading order terms are $\varepsilon \Delta^2$, which can then be dealt with directly by Duhamel’s principle. The price one pays for this change in the ambient flow equation, is that it turns out to be more difficult to show that if the initial value takes values in the manifold, so does the whole flow. All of this is carried out in Lemma 2.5 and Lemma 2.10.

Notation We will use $C, c$ to denote various constant, usually depending only on $s, n$ and the manifold $N$. In case a constant depends upon other quantities, we
will try to make that explicit. We use \( A \lesssim B \) to denote an estimate of the form \( A \leq CB \).

2. A fourth order parabolic regularization

The method we employ in order to establish short-time existence to (1.4) is in part inspired by the work of Ding and Wang [12]. We seek to approximate equation (1.4) by a family (parametrized by \( 0 < \varepsilon < 1 \)) of parabolic equations. We establish short time existence for these systems and use energy methods to show that the time of existence is independent of \( \varepsilon \) and obtain \( \varepsilon \) independent bounds which allow us to pass to the limit as \( \varepsilon \to 0 \) and thus obtain a solution to (1.4). The regularization we use differs substantially from that of Ding and Wang because we wish to view the right hand side of (1.4) as a lower order term (in the regularization) so that we can use Duhamel’s principle and a contraction mapping argument to establish and study the existence of our derived parabolic system.

The energy method we employ ultimately depends on establishing \( \varepsilon \) independent \( L^2 \)-estimates for the tension, \( \tau(u) \) and its derivatives. This suggests that we regularize (1.2) by \( \varepsilon \) times the gradient flow for the functional

\[
G(u) = \frac{1}{2} \int_{\mathbb{R}^n} |\tau(u)|^2 dx.
\]

2.1. Geometric Preliminaries. We perform many of our computations in the appropriate pull-back tensor bundles over \( \mathbb{R}^n \). We begin by recalling alternative formulations of the tension \( \tau(u) \) in this setting (see [14]). First note that \( du \) is a closed 1-form with values in \( u^{-1}(TN) \). The tension is simply minus the divergence of the differential of \( u \)

\[
\tau(u) = -\delta du \in \Gamma(u^{-1}(TN))
\]

where \( \delta \) denotes the divergence operator with respect to the metric \( g \). In particular, this shows that a map \( u \) is harmonic if and only if its differential is a harmonic 1-form. Let \( \nabla \) denote the covariant derivative on \( T^*\mathbb{R}^n \otimes u^{-1}(TN) \) defined with respect to the Levi-Civita connection of the Euclidean metric on \( \mathbb{R}^n \) (i.e. the ordinary directional derivative) and the Riemannian metric \( g \) on \( N \). For \( \alpha = 1, \ldots, n \) we let \( \nabla_{\alpha} u \in \Gamma(u^{-1}(TN)) \) be the vector field given by

\[
\nabla_{\alpha} u = \partial_{\alpha} u = \frac{\partial u^i}{\partial x^\alpha} \frac{\partial}{\partial u^i}
\]

where \( (u^1, \ldots, u^k) \) are coordinates about \( u(x) \in N \). In particular

\[
du = \frac{\partial u^i}{\partial x^\alpha} dx^\alpha \otimes \frac{\partial}{\partial u^i} = (\nabla_{\alpha} u)^i dx^\alpha \otimes \frac{\partial}{\partial u^i}.
\]

The second fundamental form of the map \( u \) is defined to be the covariant derivative of \( du, \nabla du \in \Gamma((T^2\mathbb{R}^n) \otimes u^{-1}(TN)) \). In local coordinates we have for \( i = 1, \ldots, k \) and \( \alpha, \beta \in 1, \ldots, n \),

\[
(\nabla du)^i_{\alpha\beta} = \nabla_{\alpha} \nabla_{\beta} u^i
\]

\[
= \frac{\partial^2 u^i}{\partial x^\alpha \partial x^\beta} + \Gamma^i_{jk}(u) \frac{\partial u^j}{\partial x^\alpha} \frac{\partial u^k}{\partial x^\beta}.
\]
Note that here the subscript $\alpha$ actually denotes covariant differentiation with respect to the vector field $\nabla_{\alpha}u$ as defined in (2.1) and we have $\nabla_{\alpha}\nabla_{\beta}u = \nabla_{\beta}\nabla_{\alpha}u$.

The tension is simply the trace of $\nabla du$ with respect to the Euclidean metric, $\delta = \delta_{\alpha\beta}$

\begin{equation}
\tau(u)^{i} = \nabla_{\alpha}\nabla_{\alpha}u^{i} = \frac{\partial^{2}u^{i}}{\partial x^{\alpha}\partial x^{\alpha}} + \Gamma_{jk}^{i}(u)\frac{\partial u^{j}}{\partial x^{\alpha}}\frac{\partial u^{k}}{\partial x^{\alpha}}
\end{equation}

from which we recover (1.1).

2.2. The gradient flow for $G(u)$. For a given vector field $\xi \in \Gamma(u^{-1}(TN))$, we construct a variation of $u : \mathbb{R}^{n} \to N$ with initial velocity $\xi$ as follows. Define the map

$$U : \mathbb{R}^{n} \times \mathbb{R} \to N$$

by setting

$$U(x,s) = \exp_{u(x)} s\xi(x)$$

where $\exp_{u(x)} : T_{u(x)}N \to N$ denotes the exponential map. Set $u_{s}(x) = U(x,s)$ and now let $\nabla$ denote the natural covariant derivative on $T^{*}(\mathbb{R}^{n} \times \mathbb{R}) \otimes U^{-1}(TN)$. Then

$$\left.\frac{d}{ds}G(u_{s})\right|_{s=0} = \frac{1}{2} \left.\frac{d}{ds} \int_{\mathbb{R}^{n}} |\tau(u_{s})|^{2}dx\right|_{s=0}$$

$$= \frac{1}{2} \left.\int_{\mathbb{R}^{n}} \frac{\partial}{\partial s} (\tau(u_{s}),\tau(u_{s}))dx\right|_{s=0}$$

$$= \left.\int_{\mathbb{R}^{n}} \langle \nabla_{s}\tau(u_{s}),\tau(u_{s})\rangle dx\right|_{s=0}$$

where the inner products are taken with respect to $g$ and we have used the metric compatibility of $\nabla$. Let $R = R(\cdot,\cdot,\cdot)$ denote the Riemann curvature endomorphism of $\nabla$. Using (2.3) and the definition of $R$ we see that

$$\nabla_{s}\tau(u_{s}) = \nabla_{s}\nabla_{\alpha}\nabla_{\alpha}u_{s}$$

$$= \nabla_{\alpha}\nabla_{s}\nabla_{\alpha}u_{s} - R(\nabla_{\alpha}u_{s},\nabla_{s}u_{s})\nabla_{\alpha}u_{s}$$

$$= \nabla_{\alpha}\nabla_{\alpha}\nabla_{s}u_{s} - R(\nabla_{\alpha}u_{s},\nabla_{s}u_{s})\nabla_{\alpha}u_{s}.$$
Proposition 2.1. The Euler-Lagrange equation for $G$ acting on $H^{s+1}(\mathbb{R}^n, N)$, for $s \geq 3$ is

\begin{equation}
F(u) \equiv \nabla_\alpha \nabla_\beta \tau(u) - R(\nabla_\alpha u, \tau(u)) \nabla_\alpha u = 0.
\end{equation}

The parabolic regularization of (1.4) which we now proceed to study is

\begin{equation}
\left\{ \begin{array}{l}
\frac{\partial u}{\partial t} = -\varepsilon F(u) + J(u) \tau(u) + \beta \tau(u) \\
u(0) = u_0
\end{array} \right.
\end{equation}

2.3. The ambient flow equations. Rather than attempting to study the parabolic equations (2.6) directly we will focus on the induced “ambient flow equations” for $v = w \circ u$ where $w : (N, g) \to \mathbb{R}^p$ is a fixed isometric embedding. We fix a $\delta > 0$, chosen sufficiently small so that on the $\delta$-tubular neighborhood $w(N)_\delta \subset \mathbb{R}^p$, the nearest point projection map

$$\Pi : w(N)_\delta \to w(N)$$

is a smooth map (cf. [40] §2.12.3). For a point $Q \in w(N)_\delta$ set

$$\rho(Q) = Q - \Pi(Q) \in \mathbb{R}^p$$

so that $|\rho(Q)| = \text{dist}(Q, w(N))$, and viewing $\rho$ and $\Pi$ as maps from $w(N)_\delta$ into itself we have

\begin{equation}
\Pi + \rho = \text{Id}_{w(N)_\delta}.
\end{equation}

Note that then the differentials of the maps satisfy

\begin{equation}
d\Pi + d\rho = \text{Id}
\end{equation}
as a linear map from $\mathbb{R}^p$ to itself. For any map $v : \mathbb{R}^n \to w(N)_\delta$ we set

$$T(v) = \Delta v - \Pi_{ab}(v) v_a^a v_b^b$$

where $\Pi_{ab}(v)$, $1 \leq a, b \leq p$ are the components of the Hessian of $\Pi$ at $v(\cdot)$. At a point $y \in N$ the Hessian of $\Pi$ is minus the second fundamental form of $N$ at $y$. So if $v = w \circ u$, with $u : \mathbb{R} \to N$, then $T(v)$ is simply the tangential component of the Laplacian of $v$ which corresponds to the tension of the map $u$, i.e.

$$dw(\tau(u)) = (\Delta v)^T = d\Pi(\Delta v) = T(v).$$

Therefore, in direct analogy with the functional $G(\cdot)$, we now consider

$$G(v) = \frac{1}{2} \int_{\mathbb{R}^n} |T(v)|^2 dx$$

\begin{equation}
= \frac{1}{2} \int_{\mathbb{R}^n} |\Delta v - \Pi_{ab}(v) v_a^a v_b^b|^2 dx.
\end{equation}

Our point here (and hence the seemingly odd notation) is that we wish to consider $T(v)$ for arbitrary maps into $w(N)_\delta$ whose image does not necessarily lie on $N$.

Definition 2.2. For $v : \mathbb{R}^n \to w(N)_\delta$, let $F(v)$ denote the Euler-Lagrange operator of $G(v)$ with respect to unconstrained variations. A simple computation shows that its components are given by

$$(F(v))^c = (\Delta T(v))^c$$

\begin{equation}
- \sum_{a, \beta = 1}^n (T(v)^c \Pi_{abc}(v) v_a^a v_b^a - (T(v)^c \Pi_{abc}(v) v_a^a)_\beta - (T(v)^c \Pi_{abc}(v) v_b^b)_a)\big)
\end{equation}

\begin{equation}
= \Delta^2 v^c - (\tilde{\mathcal{F}}(v))^c,
\end{equation}
where

\[ (\tilde{F}(v))^c = \sum_{\alpha,\beta=1}^{n} \left( (\Delta (\Pi^c_{ab}(v)v^a_{\alpha}v^b_{\beta})) + T(v)^c\Pi^c_{abc}(v)v^a_{\alpha}v^b_{\beta} - (T(v)^c\Pi^c_{ac}(v)v^a_{\beta})_\beta \right) \]

denotes the lower order terms. Note that the subscripts here refer to coordinate differentiation in \( \mathbb{R}^n \) (Greek indices) or \( \mathbb{R}^p \) (Roman indices).

For \( v = w \circ u \), we wish to consider compactly supported tangential variations of \( G(v) \). Such variations correspond to (compactly supported) vector fields \( \phi \) on \( w(N)_\delta \) which satisfy \( d\rho(\phi) = 0 \).

**Proposition 2.3.** If \( u : \mathbb{R}^n \to N \) and \( v = w \circ u \) then for all \( \phi \in \Gamma(Tw(N)_\delta) \) with compact support such that \( d\rho(\phi) = 0 \) we have

\[ \frac{d}{ds}G(v + s\phi) \bigg|_{s=0} = \int_{\mathbb{R}^n} \langle F(v), \phi \rangle dx = \int_{\mathbb{R}^n} \langle d\Pi(F(v)), \phi \rangle dx. \]

Recall that \( d\Pi = \text{Id} - d\rho \).

**Definition 2.4.** If \( v = w \circ u \), then the ambient form of the Schrödinger vector field \( J(u) \tau(u) \), is given by the vector field \( f_v \) with

\[ f_v = d\rho_{|_{w^{-1}\Pi(v(x))}} [J(w^{-1}\Pi(v)(dv))^{-1}(d\Pi_{|_{w(x)}}(\Delta v))]. \]

Note that \( f_v \) is defined for maps \( v : \mathbb{R}^n \to w(N)_\delta \) whose image does not necessarily lie on \( N \).

Next we have the following Lemma.

**Lemma 2.5.** If \( u : \mathbb{R}^n \to N \) and \( v = w \circ u \) then we have

\[ d\rho(v)(\nabla F(v)) = \Delta(\Pi_{ab}(v)\nabla a v^a \nabla b v^b) + \text{div}(\Pi_{ab}(v)\Delta v^a \nabla b v^b) + \Pi_{ab}(v)\nabla a \Delta v^a \nabla b v^b \]

\[ -d\rho(v)(\Delta(\nabla F(v))) = :H(v). \]

**Proof.** This follows from the facts that

\[ d\rho(v)(\nabla F(v)) = d\rho(v)(\Delta^2 v) - d\rho(v)(\tilde{F}(v)), \]

\[ \Delta \text{div}(d\rho(v)(\nabla v)) = \Delta(d\rho(v)(\Delta v)) + (\rho_{ab}(v)\nabla a v^a \nabla b v^b) \]

\[ = \text{div}(d\rho(v)(\nabla \Delta v)) + \text{div}(\rho_{ab}(v)\Delta v^a \nabla b v^b) \]

\[ + \Delta(\rho_{ab}(v)\nabla a v^a \nabla b v^b) \]

\[ = d\rho(v)(\Delta^2 v) + \rho_{ab}(v)\nabla a \Delta v^a \nabla b v^b \]

\[ + \text{div}(\rho_{ab}(v)\Delta v^a \nabla b v^b) + \Delta(\rho_{ab}(v)\nabla a \nabla b v^b) \]

and

\[ d\rho(v)(\nabla v) = 0. \]

Finally we note that

\[ \rho_{ab}(v) = -\Pi_{ab}(v). \]
Remark 2.6. Note that \( \mathcal{H}(v) \) only contains derivatives of \( v \) up to third order. Moreover this term is well-defined for every \( v : \mathbb{R}^n \to w(N) \).

The regularized ambient equations are given by

\[
\begin{aligned}
\frac{\partial v}{\partial \rho} &= -\varepsilon (F(v) - \mathcal{H}(v)) + f_\varepsilon + \beta T \nu \\
v(0) &= v_0
\end{aligned}
\tag{2.10}
\]

The basic relationship between the regularized geometric flows (2.6) and the regularized ambient flows (2.10) is provided by the following Lemma (cf. §7 of [14]).

Lemma 2.7. Fix \( \varepsilon \in [0, 1] \). Given \( u_0 \in H^{s+1}(\mathbb{R}^n, N) \) with \( s \geq 3 \), \( w : N \to \mathbb{R}^p \) an isometric embedding, and \( T_\varepsilon > 0 \), a flow \( u : \mathbb{R}^n \times [0, T_\varepsilon] \to N \) satisfies (2.6) if and only if the flow \( v = w \circ u : \mathbb{R}^n \times [0, T_\varepsilon] \to \mathbb{R}^p \) satisfies (2.10) with \( v_0 = w \circ u_0 \).

Proof. First note that since \( w \) is an isometry we have

\[
|T(v)|^2 = |\tau(u)|^2
\]

and therefore \( \mathcal{G}(v) = G(u) \). Given \( \xi \in \Gamma(u^{-1}(TN)) \) a smooth compactly supported vector field set \( \phi = dw(\xi) \in \Gamma(u^{-1}(T\mathbb{R}^p)) \). As before we consider the variation of \( u \) given by \( u_s(x) = \exp_{u(x)} s\xi \). We then have

\[
w \circ u_s = v + s\phi + \mathcal{O}(s^2)
\]

so that

\[
G(u_s) = G(v + s\phi) + \mathcal{O}(s^2).
\]

Therefore

\[
\int_{\mathbb{R}^n} \langle F(u), \xi \rangle dx = \int_{\mathbb{R}^n} \langle F(v), \phi \rangle dx.
\]

Observe that

\[
\int_{\mathbb{R}^n} \left( \frac{\partial u}{\partial t}, \xi \right) dx = \int_{\mathbb{R}^n} \left( dw \left( \frac{\partial u}{\partial t} \right), dw(\xi) \right) dx = \int_{\mathbb{R}^n} \left( \partial_v, \phi \right) dx.
\]

Since \( d\rho(\phi) = 0 \) and \( \mathcal{H}(v) = d\rho(\mathcal{F}(v)) \) we also have

\[
-\varepsilon \int_{\mathbb{R}^n} \langle F(u), \xi \rangle dx = -\varepsilon \int_{\mathbb{R}^n} \langle F(v), \phi \rangle dx = -\varepsilon \int_{\mathbb{R}^n} \langle \mathcal{F}(v) - \mathcal{H}(v), \phi \rangle dx.
\]

Note that

\[
\int_{\mathbb{R}^n} \langle J(u)\tau(u), \xi \rangle dx = \int_{\mathbb{R}^n} \langle dw(\tau(u)), dw(\xi) \rangle dx
\]

\[
= \int_{\mathbb{R}^n} \langle dw[J(w^{-1}(\Pi(v)))(dw)^{-1}(T(v))], dw(\xi) \rangle dx
\]

\[
= \int_{\mathbb{R}^n} \langle f_v, \phi \rangle dx
\]

and

\[
\int_{\mathbb{R}^n} \langle \tau(u), \xi \rangle dx = \int_{\mathbb{R}^n} \langle dw(\tau(u)), dw(\xi) \rangle dx
\]

\[
= \int_{\mathbb{R}^n} \langle f_v, \phi \rangle dx.
\]

This together with (2.12) and (2.13) implies that the flows correspond as claimed. \( \square \)
We end this section by exhibiting in a more practical form the structure of the parabolic operator appearing in the regularized ambient flow equations (2.10).

**Definition 2.8.** For \( v : \mathbb{R}^n \to \mathbb{R}^p \), and \( j \in \mathbb{N} \) we let \( \partial^j v \) denote an arbitrary \( j \text{-th} \) order partial derivative of \( v \)

\[
\partial^j v = \frac{\partial^j v}{\partial x^{\alpha_1} \cdots \partial x^{\alpha_r}} \quad \text{with} \quad \alpha_1 + \cdots + \alpha_r = j
\]

and let

\[
\partial^{j_1} v \ast \cdots \ast \partial^{j_r} v
\]

denote terms which are a sum of products of terms of the form \( \partial^{j_k} v \), ..., \( \partial^{j_k} v \).

**Proposition 2.9.** Let \( v : \mathbb{R}^n \to w(N) \subset \mathbb{R}^p \), then

\[
-\varepsilon (F(v) - H(v)) + f_v + \beta T v
\]

\[
= -\varepsilon \Delta^2 v - \varepsilon \sum_{l=3}^4 \sum_{j_1 + \cdots + j_l = 4} A_{(j_1 \cdots j_l)}(v) \partial^{j_1} v \ast \cdots \ast \partial^{j_l} v + B_0(v) \partial v + B_1(v) \partial v \ast \partial v
\]

where each \( j_k \geq 1 \) and each of \( A_{(j_1 \cdots j_l)}(v) \), \( B_0(v) \) and \( B_1(v) \) are bounded smooth functions of \( v \).

**Proof.** This follows from the explicit expressions for \( F(v) \), \( H(v) \), \( f_v \) and \( T v \).

In the following Lemma (which is a suitable modification of Theorem 7C of [14]) we show that if \( v : \mathbb{R}^n \times [0, T] \to w(N) \) is a solution of (2.10) and if \( v_0 : \mathbb{R}^n \to w(N) \), then \( v : \mathbb{R}^n \times [0, T] \to w(N) \).

**Lemma 2.10.** Fix \( \varepsilon \geq 0 \) and \( \beta \geq 0 \). Let \( v : \mathbb{R}^n \times [t_0, t_1] \to w(N) \) be a solution of (2.10) with \( v(x, t_0) = v_0(x) \in w(N) \), where \( v_0 \in H^{s+4}(\mathbb{R}^n, w(N)) \) with \( s \geq \left[ \frac{n}{2} \right] + 4 \). Then \( v(x, t) \in w(N) \) for all \( x \in \mathbb{R}^n \) and all \( t \in [t_0, t_1] \).

Note that in this case by Lemma 2.7 \( u(x, t) = w^{-1} \circ v(x, t) \) solves

\[
\begin{cases}
\frac{\partial u}{\partial t} = -\varepsilon F(u) + J(u) + \beta u \quad \text{and} \\
u(x, t_0) = v_0(x) \in w(N).
\end{cases}
\]

**Proof.** We start by calculating

\[
\partial_t \rho(v) = d_a \rho(v) \partial_t v^a,
\]

\[
\Delta \rho(v) = d_a \rho(v) \Delta v^a - \Pi_{ab}(v) \nabla v^a \nabla v^b \quad \text{and}
\]

\[
\Delta^2 \rho(v) = \Delta \left( d_a \rho(v) \Delta v^a \right) - \Delta \left( \Pi_{ab}(v) \nabla v^a \nabla v^b \right)
\]

\[
= \text{div} \left( d_a \rho(v) \Delta v^a \right) - \text{div} \left( \Pi_{ab}(v) \Delta v^a \nabla v^b \right) - \Delta \left( \Pi_{ab}(v) \nabla v^a \nabla v^b \right)
\]

\[
= d_a \rho(v) \Delta^2 v^a - \Pi_{ab}(v) \nabla \Delta v^a \nabla v^b - \text{div} \left( \Pi_{ab}(v) \nabla v^a \nabla v^b \right)
\]

\[- \Delta \left( \Pi_{ab}(v) \nabla v^a \nabla v^b \right).
\]
Here we used again that $\Pi_{ab}(v) = -\rho_{ab}(v)$. Now if $v$ is a solution of (2.10) we get that
\[
\partial_t v = -\varepsilon \Delta^2 v + \varepsilon F(v) - \varepsilon d\rho(v) \mathcal{F}(v) + f_v + \beta \Delta v - \beta \Pi_{ab}(v) \nabla v^a \nabla v^b
+ \varepsilon \left( \Delta (\Pi_{ab}(v)) \nabla v^a \nabla v^b + \text{div} (\Pi_{ab}(v) \Delta v^a \nabla v^b) + \Pi_{ab}(v) \nabla \Delta v^a \nabla v^b \right)
= \beta \Delta v - \varepsilon \Delta^2 v + \varepsilon d\Pi(v) \mathcal{F}(v) + f_v - \beta \Pi_{ab}(v) \nabla v^a \nabla v^b
+ \varepsilon \left( \Delta (\Pi_{ab}(v)) \nabla v^a \nabla v^b + \text{div} (\Pi_{ab}(v) \Delta v^a \nabla v^b) + \Pi_{ab}(v) \nabla \Delta v^a \nabla v^b \right).
\]
Combining these two calculations yields
\[
(\partial_t - \beta \Delta + \varepsilon \Delta^2) \rho(v) = \varepsilon d\rho(v) (d\Pi(v) \mathcal{F}(v)) + d\rho(v) f_v - \beta d\rho(v) (\Pi_{ab}(v) \nabla v^a \nabla v^b)
+ \varepsilon d\rho(v) \left( \Delta (\Pi_{ab}(v)) \nabla v^a \nabla v^b + \text{div} (\Pi_{ab}(v) \Delta v^a \nabla v^b) + \Pi_{ab}(v) \nabla \Delta v^a \nabla v^b \right)
+ \beta \Pi_{ab}(v) \nabla v^a \nabla v^b - \varepsilon \left( \Delta (\Pi_{ab}(v)) \nabla v^a \nabla v^b + \text{div} (\Pi_{ab}(v) \Delta v^a \nabla v^b) + \Pi_{ab}(v) \nabla \Delta v^a \nabla v^b \right)
= \varepsilon d\rho(v) f_v + \beta d\Pi(v) (\Pi_{ab}(v) \nabla v^a \nabla v^b) - \varepsilon d\Pi(v) \left( \Delta (\Pi_{ab}(v)) \nabla v^a \nabla v^b + \Pi_{ab}(v) \nabla \Delta v^a \nabla v^b \right)
+ \text{div} (\Pi_{ab}(v) \Delta v^a \nabla v^b) + \Pi_{ab}(v) \nabla \Delta v^a \nabla v^b) + \varepsilon d\rho(v) (d\Pi(v) \mathcal{F}(v)).
\]
Multiplying this equation with $\rho(v)$ and using the facts that (note that $f_v \in T_{\Pi(v)} w(N)$)
\[
\rho(v) \cdot d\Pi(v)(\tilde{\phi}) = 0 \quad \forall \phi \in w(N)_\delta,
\]
\[
\rho(v) \cdot d\rho(v) f_v = \rho(v) \cdot (f_v - d\Pi(v) f_v) = 0,
\]
and
\[
\rho(v) \cdot d\rho(v) (d\Pi(v)(\phi)) = \rho(v) \cdot d\Pi(v)(d\rho(v)(\phi)) = 0 \quad \forall \phi \in w(N)_\delta,
\]
gives for all $t \in (t_0, t_1)$
\[
\frac{1}{2} \partial_t |\rho(v)|^2 = \langle \rho(v), \beta \Delta \rho(v) - \varepsilon \Delta^2 \rho(v) \rangle.
\]
Integrating this equation over $\mathbb{R}^n$ and using integration by parts, we have for all $t \in (t_0, t_1)$
\[
\partial_t \int_{\mathbb{R}^n} |\rho(v)|^2 = -2 \int_{\mathbb{R}^n} (\beta |\nabla \rho(v)|^2 + \varepsilon |\Delta \rho(v)|^2)
\leq 0.
\]
Since $\rho(v_0) = 0$ this implies that $\rho(v) = 0$ for all $t \in [t_0, t_1]$ and hence finishes the proof of the Lemma. \hfill \Box

3. The Duhamel solution to the ambient flow equations

In this section we introduce a fixed point method that solves the initial value problem (2.10) in the Sobolev space $H^{s+1}(\mathbb{R}^n, \mathbb{R}^p)$, for $s \geq \frac{n}{2} + 4$. To simplify the notation, using Proposition 2.9, we rewrite (2.10) as
\[
\begin{cases}
\frac{\partial v}{\partial t} = -\varepsilon \Delta^2 v + N(v) \\
v(x, 0) = v_0,
\end{cases}
\]
(3.1)
where
\[ N(v) = -\varepsilon \sum_{l=2}^{4} \sum_{j_1+\cdots+j_l=4} A_{j_1,\ldots,j_l}(v) \partial^{j_1} v \cdots \partial^{j_l} v \]
\[ + B_0(v) \partial^2 v + B_1(v) \partial v \ast \partial v. \]

We now state the well-posedness theorem for (3.1). For any fixed \( v_0 \), define the spaces
\[ L^2_\delta = \{ v : \mathbb{R}^n \to \mathbb{R}^p \mid \| v - v_0 \|_{L^2} < \delta \}. \]
and
\[ L^2_{2,\infty} = \{ v : \mathbb{R}^n \to \mathbb{R}^p \mid \| v - v_0 \|_{L^2}, \| v - v_0 \|_{L^\infty} < \delta \}. \]

We then have the following theorem:

**Theorem 3.1.** Assume \( \delta > 0, \varepsilon > 0, \) and \( \gamma \in \mathbb{R}^p \) are fixed. Then for any \( (v_0 - \gamma) \in H^{s+1}(\mathbb{R}^n, \mathbb{R}^p) \), \( s \geq \frac{n}{2} + 4 \) there exist \( T_\varepsilon = T(\varepsilon, \delta, \| \partial v_0 \|_{H^{\gamma}}, \| v_0 - \gamma \|_{L^2}) \) and a unique solution \( v = v_\varepsilon \) for (3.1) such that \( v \in C([0, T_\varepsilon], H^{s+1} \cap L^2_{2,\infty}) \).

To prove the theorem we rewrite (3.1) as an integral equation using the Duhamel principle:
\[ v(x, t) = S_\varepsilon(t)(v_0 - \gamma) + \int_0^t S_\varepsilon(t - t') N(v)(x, t') dt' + \gamma, \]
where for \( f \in H^{s+1}(\mathbb{R}^n, \mathbb{R}^p) \)
\[ S_\varepsilon(t)f(x) = \int_{\mathbb{R}^n} e^{i(x, \xi) - \varepsilon|\xi|t} \hat{f}(\xi) d\xi \]
is the solution of the linear and homogeneous initial value problem associated to (3.1). The main idea is to consider the operator
\[ L v(x, t) = S_\varepsilon(t)(v_0 - \gamma) + \int_0^t S_\varepsilon(t - t') N(v)(x, t') dt' + \gamma \]
and prove that for a certain \( T_\varepsilon \) the operator \( L \) is a contraction from a suitable ball in \( C([0, T_\varepsilon], H^s \cap L^2_{2,\infty}) \) into itself.

To estimate \( L \) we need to study the smoothing properties of the linear solution \( S_\varepsilon(t)v_0 \). Because the order of derivatives that appears in \( N(v) \) is 3, in order to be able to estimate the nonlinear part of \( L \) in \( H^{s+1} \), we should prove that the operator \( S_\varepsilon(t) \) provides a smoothing effect also of order 3. We have in fact the following lemma:

**Lemma 3.2.** Define the operator \( D^s \), \( s \in \mathbb{R} \) as the multiplier operator such that \( \hat{D^s f}(\xi) = |\xi|^s \hat{f} \). Then for any \( t > 0 \) and \( i = 1, 2, 3, \)
\[ \| S_\varepsilon(t)f \|_{L^2} \lesssim \| f \|_{L^2}, \]
\[ \| D^s S_\varepsilon(t)f \|_{L^2} \lesssim t^{-\frac{s}{2}} \varepsilon^{-\frac{s}{2}} \| D^{s-i} f \|_{L^2}. \]

**Proof.** The proof follows from Plancherel theorem and the two estimates
\[ \left| e^{-\varepsilon |\xi| t} \right| \lesssim 1 \]
\[ \left| |\xi|^s e^{-\varepsilon |\xi|^t} \right| \lesssim |\xi|^{s-i} t^{-\frac{i}{2}} \varepsilon^{-\frac{i}{2}}. \]
To state the next lemma, where we show how for small intervals of time the evolution \( S_\varepsilon(t)(v_0 - \gamma) \) stays close to \( v_0 - \gamma \), we need to introduce the space \( \dot{H}^s \). This space denotes the homogeneous Sobolev space defined as the set of all functions \( f \) such that \( D^s f \in L^2 \).

**Lemma 3.3.** Let \( \sigma \in (0, 1) \), \( s > \frac{n}{2} + 4\sigma \) and assume that \( f \in H^{4\sigma} \cap \dot{H}^s \). Then

\[
\| S_\varepsilon(t) f - f \|_{L^\infty} \leq e^{\sigma t^\sigma} \| f \|_{H^s} + \| f \|_{\dot{H}^{4\sigma}}, \quad \text{and} \quad \| S_\varepsilon(t) f - f \|_{L^2} \leq e^{\sigma t^\sigma} \| f \|_{\dot{H}^{4\sigma}}.
\]

**Proof.** By the mean value theorem

\[
\left| e^{-\varepsilon |\xi|^t} - 1 \right| \lesssim |\xi|^4 t \varepsilon,
\]

which combined with the trivial bound

\[
\left| e^{-\varepsilon |\xi|^t} - 1 \right| \leq 2
\]
gives, for any \( \sigma \in [0, 1] \)

\[
\left| e^{-\varepsilon |\xi|^t} - 1 \right| \lesssim (|\xi|^4 t \varepsilon)^\sigma.
\]

We now write

\[
\left| (S_\varepsilon(t) - 1)f(x) \right| = \left| \int_{\mathbb{R}^n} e^{i(x, \xi)} [e^{-\varepsilon |\xi|^t} - 1] \hat{f}(\xi) d\xi \right|
\]

\[
\lesssim (t \varepsilon)^\sigma \int_{\mathbb{R}^n} |\hat{f}(\xi)||\xi|^{4\sigma}
\]

\[
= (t \varepsilon)^\sigma \left[ \int_{|\xi| \leq 1} |\hat{f}(\xi)||\xi|^{4\sigma} + \int_{|\xi| \geq 1} |\hat{f}(\xi)||\xi|^{s} \frac{1}{|\xi|^{s-4\sigma}} \right],
\]

and this concludes the argument since \( s > \frac{n}{2} + 4\sigma \) guarantees the summability after the application of Cauchy-Schwarz. Note also that

\[
\| (S_\varepsilon(t) - 1)f \|_{L^2} \leq \| (e^{-\varepsilon |\xi|^t} - 1)\hat{f} \|_{L^2}
\]

\[
\lesssim (t \varepsilon)^\sigma \left( \int (|\xi|^{4\sigma})^2 |\hat{f}|^2 \right)^{\frac{1}{2}}
\]

\[
\lesssim (t \varepsilon)^\sigma \| f \|_{\dot{H}^{4\sigma}} \lesssim (t \varepsilon)^\sigma \| \partial f \|_{\dot{H}^{4\sigma-1}}.
\]

\[\blacktriangleleft\]

We are now ready to prove Theorem 3.1.

**Proof.** For \( T_\varepsilon, r > 0 \) and \( s \geq \frac{n}{2} + 4 \) consider the ball

\[
B_r = \{ \partial v \in H^s : \| \partial(v - v_0) \|_{L^\infty_{T_\varepsilon} H^s} \leq r \} \cap L^2_0.
\]

We want to prove that for the appropriate \( T_\varepsilon \) and \( r \), the operator \( L \) maps \( B_r \) to itself and is a contraction. We start with the estimate of the linear part of \( L \). By (3.6) we have

\[
\| \partial(S_\varepsilon(t)(v_0 - \gamma) - (v_0 - \gamma)) \|_{H^s} \lesssim \| (1 + D^s)S_\varepsilon(t)\partial v_0 \|_{L^2} + \| \partial v_0 \|_{H^s} \lesssim \| \partial v_0 \|_{H^s}.
\]

(3.12)
To estimate the nonlinear term we use (3.6) (3.7), and interpolation:

\begin{equation}
(3.13) \| \partial \left( \int_0^t S_t(t-t')N(v)(x,t')dt' \right) \|_{L^s} \\
= \left\| \int_0^t S_t(t-t') \partial N(v)(x,t')dt' \right\|_{L^2} + \left\| \int_0^t D_t S_t(t-t') \partial N(v)(x,t')dt' \right\|_{L^2} \\
\lesssim \int_0^t \| \partial N(v) \|_{L^2}(t') \ dt' + \int_0^t (t')^{-3/4} \varepsilon^{-3/4} \| D_t^{s-3} \partial N(v) \|_{L^2}(t') \ dt' \\
\lesssim \int_0^t (1 + (t')^{-3/4} \varepsilon^{-3/4}) \| \partial v \|_{H^s}(t') \ dt',
\end{equation}

where \( m \) is the order of the nonlinearity\(^1 \) \( N(v) \). Note that to control \( \partial N(v) \) and \( D_t^{s-3} \partial N(v) \) in the previous inequality we are never in the position of estimating \( v \) in \( L^2 \). By (3.5), (3.7), (3.12) and (3.13), we obtain the estimate

\begin{equation}
(3.14) \| \partial (Lv - v_0) \|_{H^s}(t) \leq C_0 \| \partial v_0 \|_{L^s} + C_1 \int_0^t (1 + (t')^{-3/4} \varepsilon^{-3/4}) \| \partial v \|_{H^s}(t') \ dt'.
\end{equation}

Thus

\begin{equation}
(3.15) \| \partial (Lv - v_0) \|_{L^\infty_t H^s_x} \leq C_0 \| \partial v_0 \|_{L^s} + C_1 \varepsilon^{-3/4} T^1 \| \partial v \|_{L^\infty_t H^s_x}.
\end{equation}

We still need to check that \( L \) is continuous in time and that \( Lv \in L^\infty_t \). The continuity follows directly from the continuity of the operator \( S_t(\cdot) \). To prove the \( L^\infty \) and \( L^2 \) estimates one uses (3.8) with \( \sigma = 1/4 \) applied to \( f = v_0 - \gamma \), the Sobolev inequality and estimates similar to the ones used to obtain (3.14). One gets

\begin{equation}
(3.16) \|Lv - v_0\|_{L^\infty_t H^s_x} + \|Lv - v_0\|_{L^\infty_t L^\infty_x} \leq C_1 \varepsilon^{1/4} T^1 \| \partial v_0 \|_{L^s} + C_1 \varepsilon^{-3/4} T^1 \| \partial v \|_{L^\infty_t H^s_x}.
\end{equation}

We now take \( r = 3C_0 \varepsilon \|v_0\|_{L^s} \) and

\begin{equation}
(3.17) T \leq \min(\delta^4 C_1^{-1} \varepsilon^{-3/4} 4m \varepsilon^{-4m} C_0^{-4m} \varepsilon^{-4m} + \delta^2 C_1^{-1} \varepsilon^{-1} \varepsilon^{-4m} \varepsilon^{-4m})
\end{equation}

so that (3.14) and (3.16) guarantees that \( L \) maps \( B_r \) into itself. Note that (3.13) yields for \( v, w \in B_r \)

\begin{equation}
(3.18) \left\| \int_0^t S_t(t-t') \partial[N(v) - N(w)](x,t') \ dt' \right\|_{H^s} \lesssim \varepsilon^{-3/4} T^1 \| \partial[N(v) - N(w)] \|_{L^\infty_t H^s_x}. \end{equation}

Therefore

\begin{equation}
(3.19) \| \partial(Lv - Lw) \|_{L^\infty_t H^s_x} \lesssim \varepsilon^{-3/4} T^1 \| \partial[N(v) - N(w)] \|_{L^\infty_t H^s_x} \lesssim \varepsilon^{-3/4} T^1 C(\delta) (\| \partial v \|_{L^\infty_t H^s_x} + \| \partial w \|_{L^\infty_t H^s_x}) \| \partial(v-w) \|_{L^\infty_t H^s_x} \end{equation}

Similarly one shows that

\begin{equation}
\|Lv - Lw\|_{L^\infty_t H^s_x} \lesssim \varepsilon^{-3/4} T^1 C(\delta) (\| \partial v_0 \|_{H^s_x}) \| \partial(v-w) \|_{L^\infty_t H^s_x}.
\end{equation}

\(^1\)In our case actually one can compute that \( m = 4 \).
By shrinking $T_\varepsilon$ further by an absolute constant if necessary, from (3.19) and (3.20) we obtain
\begin{equation}
\|Lv - Lw\|_{L^\infty_t H^{s+1}_x} \leq \frac{1}{2} \|v - w\|_{L^\infty_t H^{s+1}_x}.
\end{equation}

The contraction mapping theorem ensures that there exists a unique function $v = v_\varepsilon$ in $L^2_\delta \cap \{ \partial v \in H^s : \|\partial(v - v_0)\|_{L^\infty_t H^s} \leq r\}$ which solves the integral equation (3.3) in the time interval $[0, T_\varepsilon]$ defined in (3.17). Moreover $v \in B_r$ by our choice of $T_\varepsilon$. The uniqueness in the whole space $H^{s+1}_x \cap L^\infty_2$ follows by similar and by now classical arguments. 

4. Analytic preliminaries

In this section we state and present the detailed proof of an interpolation inequality for Sobolev sections on vector bundles which appears in [13] (see Theorem 2.1). This inequality was first proved for functions on $\mathbb{R}^n$ by Gagliardo and Nirenberg, and for functions on Riemannian manifolds by Aubin [1]. The justification for presenting a complete proof is that this estimate plays a crucial role in the energy estimates and therefore in the proof of the results this paper. The precise dependence of the constants involved in this inequality is vital to our argument and we feel compelled to emphasize it.

Let $\Pi : E \to \mathbb{R}^n$ be a Riemannian vector bundle over $\mathbb{R}^n$. We have the bundle $\Lambda^P T^* \mathbb{R}^n \otimes E \to \mathbb{R}^n$ which is a tensor product of the bundle $E$ and the induced $P$-form bundle over $\mathbb{R}^n$, with $P = 1, 2, \ldots, n$. We define $T(\Lambda^P T^* \mathbb{R}^n \otimes E)$ as the set of all smooth sections of $\Lambda^P T^* \mathbb{R}^n \otimes E \to \mathbb{R}^n$. There exists an induced metric on $\Lambda^P T^* \mathbb{R}^n \otimes E \to \mathbb{R}^n$ from the metric on $T^* \mathbb{R}^n$ and $E$ such that for any $s_1, s_2 \in \Gamma(\Lambda^P T^* \mathbb{R}^n \otimes E)$
\begin{equation}
\langle s_1, s_2 \rangle = \sum_{i_1 \leq \cdots \leq i_p} \langle s_1(e_{i_1}, \ldots, e_{i_p}), s_2(e_{i_1}, \ldots, e_{i_p}) \rangle
\end{equation}

where $\{e_i\}$ is an orthonormal local frame for $T\mathbb{R}^n$. We define the inner product on $\Gamma(\Lambda^P T^* \mathbb{R}^n \otimes E)$ as follows
\begin{equation}
(s_1, s_2) = \int_{\mathbb{R}^n} \langle s_1, s_2 \rangle (x) dx.
\end{equation}

The Sobolev space $L^2(\mathbb{R}^n, \Lambda^P T^* \mathbb{R}^n \otimes E)$ is the completion of $\Gamma(\Lambda^P T^* \mathbb{R}^n \otimes E)$ with respect to the above inner product. To define the bundle-valued Sobolev space $H^{k,r}(\mathbb{R}^n, \Lambda^P T^* \mathbb{R}^n \otimes E)$ consider $\nabla$ the covariant derivative induced by the metric on $E$, then take the completion of smooth sections of $E$ in the norm
\begin{equation}
\|s\|_{H^{k,r}} = \|s\|_{k,r} = \left( \sum_{i=0}^k \int_{\mathbb{R}^n} |\nabla^i s|^r dx \right)^{\frac{1}{r}}
\end{equation}

where
\begin{equation}
|\nabla^i s|^2 = (\underbrace{\nabla \cdots \nabla}_i s, \underbrace{\nabla \cdots \nabla}_i s).
\end{equation}

If $r = 2$, $H^{k,r} = H^k$. 


Proposition 4.1. Let $s \in C^\infty(E)$ where $E$ is a finite dimensional $C^\infty$ vector bundle over $\mathbb{R}^n$. Then given $q, r \in [1, \infty]$ and integers $0 \leq j \leq k$ we have that

\begin{equation}
\| \nabla^j s \|_{L^p} \leq C \| \nabla^k s \|_{L^q} \| s \|_{L^r}^{1-a} \tag{4.5}
\end{equation}

with $p \in [2, \infty)$, $a \in \left( \frac{j}{k}, 1 \right]$ and satisfying

\begin{equation}
\frac{1}{p} = \frac{j}{n} + \frac{1}{r} + a \left( \frac{1}{q} - \frac{1}{r} - \frac{k}{n} \right). \tag{4.6}
\end{equation}

If $r = n/k - 1 \neq 1$ then (4.5) does not hold for $a = 1$. The constant $C$ that appears in (4.5) only depends on $n, k, j, q, r$ and $a$.

Proof. If $f$ is a real valued smooth function with compact support on $E$ then Theorem 3.70 in [2] ensures that (4.5) holds.

Case 1: Let $j = 0$ and $k = 1$. Then for $f = |s|$ we have by (4.5) that

\begin{equation}
\| |s| \|_{L^p} \leq C \| |\nabla s| \|_{L^q} \| s \|_{L^r}^{1-a} \tag{4.7}
\end{equation}

Kato’s inequality ensures that $|\nabla s| \leq |\nabla |s||$ which using (4.7) yields

\begin{equation}
\| |s| \|_{L^p} \leq C \| |\nabla s| \|_{L^q} \| s \|_{L^r}^{1-a}, \tag{4.8}
\end{equation}

which proves (4.5) for $j = 0$ and $k = 1$. In general if $f = |\nabla^j s|$ Kato’s inequality ensures that $|\nabla |\nabla^j s|| \leq |\nabla^{j+1} s|$ which yields using (4.8)

\begin{equation}
\| \nabla^j s \|_{L^p} \leq C \| |\nabla s| \|_{L^q} \| \nabla^j s \|_{L^r}^{1-a} \tag{4.9}
\end{equation}

\begin{equation}
\leq C \| |\nabla^{j+1} s| \|_{L^q} \| \nabla^j s \|_{L^r}^{1-a}
\end{equation}

where $a \in (0, 1)$ and

\begin{equation}
\frac{1}{p} = \frac{1}{r} + a \left( \frac{1}{q} - \frac{1}{r} - \frac{1}{n} \right). \tag{4.10}
\end{equation}

Note that so far the condition $p \geq 2$ has not played a role.

Case 2: Let $j = 1, k = 2$ and $\frac{1}{2} \leq a \leq 1$. If $a = 1$ (4.9) yields

\begin{equation}
\| \nabla s \|_{L^p} \leq C \| \nabla^2 s \|_{L^q} \tag{4.11}
\end{equation}

with

\begin{equation}
\frac{1}{p} = \frac{1}{q} - \frac{1}{n}. \tag{4.12}
\end{equation}

If $a = \frac{1}{2}$, assume $p \geq 2$ then

\begin{equation}
\text{div} \langle |\nabla^2 s|^{p-2} \nabla s, s \rangle = |\nabla s|^p + |\nabla s|^{p-2} \langle \nabla s, \nabla \nabla s, s \rangle +
\end{equation}

\begin{equation}
+ (p-2)|\nabla s|^{p-4} \langle \nabla s, \nabla \nabla^2 s, \nabla \nabla s \rangle = 0
\end{equation}

Since

\begin{equation}
\int_{\mathbb{R}^n} \text{div} \langle |\nabla^2 s|^{p-2} \nabla s, s \rangle = 0
\end{equation}

then (4.13) gives

\begin{equation}
\int_{\mathbb{R}^n} |\nabla s|^p \leq (n + p - 2) \int_{\mathbb{R}^n} |\nabla s|^{p-2} |\nabla^2 s| |s|. \tag{4.15}
\end{equation}

Given our choice of $j = 1, k = 2$ and $a = \frac{1}{2}$ we have $\frac{1}{q} + \frac{1}{r} = \frac{2}{p}$, i.e. $\frac{1}{q} + \frac{1}{r} + \frac{p-2}{p} = 1$. Thus Hölder’s inequality yields

\begin{equation}
\| \nabla s \|_{L^p} \leq (n + p - 2) \| \nabla^2 s \|_{L^q} \| s \|_{L^r} \| \nabla s \|_{L^r}^{p-2}, \tag{4.16}
\end{equation}

thus

\[(4.17) \quad \|\nabla s\|_{L^p} \leq \sqrt{n + p - 2}\|\nabla^2 s\|_{L^2}^{\frac{1}{2}}\|s\|_{L^r}^{\frac{1}{2}}\]

with

\[(4.18) \quad \frac{1}{p} = \frac{1}{2} \left( \frac{1}{r} + \frac{1}{n} \right).\]

For \(a \in \left(\frac{1}{2}, 1\right)\) we consider two cases: \(q < n\), and \(q \geq n\). For \(q < n\) using the convexity of \(\log \|f\|_{L^p}^p\) as a function of \(p\) we have

\[(4.19) \quad \|\nabla s\|_{L^p} \leq \|\nabla^2 s\|_{L^t} \|\nabla s\|_{L^r}^{1-\alpha} \text{ with } \alpha = \frac{p^{-1} - \sigma^{-1}}{t^{-1} - \sigma^{-1}} \in (0, 1)\]

where \(t < p < \sigma\) are such that

\[(4.20) \quad \frac{2}{t} = \frac{1}{q} + \frac{1}{r} \text{ and } \frac{1}{\sigma} = \frac{1}{q} - \frac{1}{n}.\]

Using (4.11) and (4.17) we have that

\[(4.21) \quad \|\nabla s\|_{L^p} \leq C \|\nabla^2 s\|_{L^t} \|\nabla s\|_{L^r}^{\frac{1}{2}}\]

and

\[(4.22) \quad \|\nabla s\|_{L^t} \leq C \|\nabla^2 s\|_{L^q}^{\frac{1}{2}} \|s\|_{L^r}^{\frac{1}{2}}.\]

Combining (4.19), (4.21) and (4.22) we obtain

\[(4.23) \quad \|\nabla s\|_{L^p} \leq C \|\nabla^2 s\|_{L^q}^{\frac{1}{2}} \|s\|_{L^r}^{\frac{1}{2}}\]

where

\[(4.24) \quad \frac{1}{p} = \frac{1}{n} + \frac{1}{r} + \left(1 - \frac{\alpha}{2}\right) \left(\frac{1}{q} - \frac{1}{r} - \frac{2}{n}\right),\]

which proves the case \(a \in \left(\frac{1}{2}, 1\right)\) and \(q < n\).

For \(q \geq n\), \(t > 0\) and \(b \in (0, 1)\) such that

\[(4.25) \quad \frac{1}{p} = \frac{1}{t} + b \left(\frac{1}{q} - \frac{1}{t} - \frac{1}{n}\right)\]

we have by (4.9)

\[(4.26) \quad \|\nabla s\|_{L^p} \leq C \|\nabla^2 s\|_{L^q}^b \|s\|_{L^r}^{1-b}.\]

Choosing \(t > 0\) so that

\[(4.27) \quad \frac{2}{t} = \frac{1}{q} + \frac{1}{r}\]

we have by (4.17)

\[(4.28) \quad \|\nabla s\|_{L^t} \leq C \|\nabla^2 s\|_{L^q}^{\frac{1}{2}} \|s\|_{L^r}^{\frac{1}{2}}.\]

Combining (4.26) and (4.28) we obtain

\[(4.29) \quad \|\nabla s\|_{L^p} \leq C \|\nabla^2 s\|_{L^q}^{\frac{b+1}{2}} \|s\|_{L^r}^{\frac{1-b}{2}}\]

with

\[(4.30) \quad \frac{1}{p} = \frac{1}{n} + \frac{1}{r} + \left(\frac{b+1}{2}\right) \left(\frac{1}{q} - \frac{1}{r} - \frac{2}{n}\right)\]

by (4.25) and (4.27). This concludes the proof of Case 2.
**Case 3:** Let \( j = 0 \) and \( k = 2 \). From (4.8) we have

\[
\|s\|_{L^p} \leq C\|\nabla s\|_{{L^{q_1} L^r}_1} \|s\|^{1-a_1}_{L^r}
\]

with \( a_1 \in (0, 1) \) and

\[
\frac{1}{p} = \frac{1}{r} + a_1 \left( \frac{1}{q_1} - \frac{1}{r} - \frac{1}{n} \right).
\]

Choosing \( q_1 \) so that

\[
\frac{1}{q_1} = \frac{1}{r} + \frac{1}{n} + a_2 \left( \frac{1}{q} - \frac{1}{r} - \frac{2}{n} \right)
\]

then \( a_2 \in \left( \frac{1}{2}, 1 \right) \) and

\[
\|\nabla s\|_{L^{n_1}} \leq C\|\nabla^2 s\|_{{L^{q_2} L^r}_1} \|s\|^{1-a_2}_{L^r}.
\]

Combining (4.31) and (4.34) we have that

\[
\|s\|_{L^p} \leq C\|\nabla^2 s\|_{{L^{q_1} L^r}_1} \|s\|^{1-a_1}_{L^r}
\]

with

\[
\frac{1}{p} = \frac{1}{r} + a_1 a_2 \left( \frac{1}{q} - \frac{1}{r} - \frac{2}{n} \right)
\]

from (4.32) and (4.33).

**Case 4:** We now proceed by induction on \( k \). Assume that for \( k \geq 2 \) and \( j < k \) we have proved (4.5). Let \( j < k < k + 1 \). By (4.9) we have

\[
\|\nabla^k s\|_{L^{n_1}} \leq C\|\nabla^{k+1} s\|_{{L^{q_2} L^r}_{k+2}} \|\nabla^k s\|^{1-a_2}_{L^r}
\]

with

\[
\frac{1}{q_1} = \frac{1}{r_2} + a_2 \left( \frac{1}{q_2} - \frac{1}{r_2} - \frac{1}{n} \right).
\]

By the induction hypothesis, applied to \( \nabla^{k-1} s \), we also have

\[
\|\nabla^k s\|_{L^{r_2}} \leq C\|\nabla^{k+1} s\|_{{L^{q_3} L^r}_{k+3}} \|\nabla^{k-1} s\|^{1-a_3}_{L^r}
\]

with

\[
\frac{1}{r_2} = \frac{1}{r_3} + \frac{1}{n} + a_3 \left( \frac{1}{q_3} - \frac{1}{r_3} - \frac{2}{n} \right)
\]

and

\[
\|\nabla^{k-1} s\|_{L^{r_0}} \leq C\|\nabla^k s\|_{{L^{q_4} L^r}_{k+4}} \|s\|^{1-a_4}_{L^r}
\]

with

\[
\frac{1}{r_3} = \frac{1}{r_4} + \frac{k-1}{n} + a_4 \left( \frac{1}{q_4} - \frac{1}{r_4} - \frac{k}{n} \right).
\]

Letting \( q_4 = r_2, q_3 = q, r_4 = r, r_2 = p \) we obtain

\[
\|\nabla^k s\|_{L^p} \leq C\|\nabla^{k+1} s\|_{{L^{q_1} L^r}_1} \|s\|^{1-a}_L
\]

with \( a = \frac{a_3}{1 - a_4 + a_3 a_4} \in \left[ \frac{k}{k+1}, 1 \right] \)

and

\[
\frac{1}{p} = \frac{1}{r} + \frac{k}{n} + a \left( \frac{1}{q} - \frac{1}{r} + \frac{k+1}{n} \right).
\]
By hypothesis for \( j < k \) and using (4.43) we have

\[
\|\nabla^j s\|_{L^p} \leq C \|\nabla^k s\|_{L^q_1} \|s\|_{L^r_1}^{1-a_1} \\
\leq C \|\nabla^{k+1} s\|_{L^q_0} \|s\|_{L^r_1}^{1-a_0 a_1},
\]

with \( a_0 a_1 \in \left[ \frac{j}{k+1}, 1 \right] \) and

\[
\frac{1}{p} = \frac{1}{r} + \frac{j}{n} + a_1 a_0 \left( \frac{1}{q} - \frac{1}{r} - \frac{k+1}{n} \right)
\]

which finishes the proof of the proposition.

\[\square\]

**Corollary 4.2.** Let \( u \in C^\infty(\mathbb{R}^n, N) \) be constant outside a compact set. Then for \( k \geq 1, q, r \in [1, \infty) \) and \( 0 \leq j \leq k-1 \) we have

\[
\|\nabla^{j+1} u\|_{L^p} \leq C \|\nabla^k u\|_{L^q_1} \|\nabla u\|_{L^r_1}^{1-a}
\]

with

\[
\frac{1}{p} = \frac{j}{n} + \frac{1}{r} + a \left( \frac{1}{q} - \frac{1}{r} - \frac{k-1}{n} \right).
\]

If \( r = \frac{n}{k-1-j} \neq 1 \) then (4.47) does not hold for \( a = 1 \). The constant \( C \) that appears in (4.48) only depends on \( n, k, j, q, r \) and \( a \).

**Proof.** Apply (4.5) to \( s = \nabla u \) a section of the bundle \( u^*(TN) \otimes T^*\mathbb{R}^n \). Since \( \nabla u \) is not necessarily compactly supported a standard approximation argument might be needed to complete the proof.

\[\square\]

In the second part of this section we establish the equivalence of the Sobolev norms defined in either the intrinsic, geometric setting or in the ambient, Euclidean setting. These results hold when we are above the range in which these spaces have suitable multiplication properties. Since we are working with the gradients of the maps we must consider the \( H^s \) spaces with \( s > \frac{n}{2} + 1 \).

We begin by assuming that we have chosen coordinate systems on \((N, g)\) so that the eigenvalues of \( g \) are bounded above and below by a fixed constant \( C > 1 \), i.e. we assume that

\[
C^{-1} |\xi|^2 \leq g_{ij} \xi_i \xi_j \leq C |\xi|^2 \quad \text{for all} \quad \xi \in \mathbb{R}^k.
\]

We denote these coordinates by either \((y^1, \ldots, y^k)\) or \((u^1, \ldots, u^k)\). As before \((x^1, \ldots, x^n)\) denotes Euclidean coordinates on \( \mathbb{R}^n \).

For \( v : \mathbb{R}^n \to \mathbb{R}^p \) we let

\[
\partial_\alpha v = \frac{\partial v}{\partial x^\alpha} e_a
\]

where \( \{e_1, \ldots, e_p\} \) is an orthonormal basis for \( \mathbb{R}^p \). Recall that if \( X \in \Gamma(u^{-1}(TN)) \) then

\[
(\nabla_\alpha X)^j = \frac{\partial X^j}{\partial x^\alpha} + \Gamma^j_{ik} X^i \frac{\partial u^k}{\partial x^\alpha}
\]

and \( \nabla_\alpha u = \partial_\alpha u \in \Gamma(u^{-1}(TN)) \) denotes the vector field along \( u \) defined in (2.1). We use the following notation for higher order derivatives.
4.3. Let \( \alpha = (\alpha_1, \ldots, \alpha_{l+1}) \) denote a multi-index of length \( l+1 \) \(|\alpha| = l+1\) with each \( \alpha_s \in \{1, \ldots, n\} \). We let \( \nabla^{l+1} u \in \Gamma(u^{-1}(TN)) \) denote any covariant derivative of \( u \) of order \( l+1 \) e.g.

\[
\nabla^{l+1} u = \sum_{\alpha = (\alpha_1, \ldots, \alpha_{l+1})} \nabla_{\alpha_1} \cdots \nabla_{\alpha_{l+1}} u
\]

Similarly

\[
\partial^{l+1} v = \sum_{\alpha = (\alpha_1, \ldots, \alpha_{l+1})} \partial^{l+1} v^a \frac{\partial^{l+1} u^a}{\partial x^{\alpha_1} \cdots \partial x^{\alpha_{l+1}}} e_a
\]

and

\[
\partial^{l+1} u = \sum_{\alpha = (\alpha_1, \ldots, \alpha_{l+1})} \partial^{l+1} u^a \frac{\partial}{\partial x^{\alpha_1} \cdots \partial x^{\alpha_{l+1}}} \partial y^a.
\]

Remark 1. Note that our use of the multi-index notation differs from the usual one.

Recall that for

\[
v : \mathbb{R}^n \to \mathbb{R}^p
\]

\[
u \in \mathbb{N}
\]

the Sobolev norms of \( \partial v \) and \( \nabla u \) for \( k \in \mathbb{N} \) are defined by

\[
\|\partial v\|_{H^k} = \sum_{l=0}^k \|\partial^{l+1} v\|_{L^2(\mathbb{R}^n)}
\]

\[
\|\nabla u\|_{H^k} = \sum_{l=0}^k \|\nabla^{l+1} u\|_{L^2(\mathbb{R}^n)}
\]

\[
= \sum_{l=0}^k \left( \int_{\mathbb{R}^n} g_{ij} (\nabla^{l+1} u)^i (\nabla^{l+1} u)^j \right)^{\frac{1}{2}}
\]

where here

\[
\|\nabla^{l+1} u\|_{L^2(\mathbb{R}^n)} = \sum_{|\alpha| = l+1} \|\nabla_{\alpha_1} \cdots \nabla_{\alpha_{l+1}} u\|_{L^2(\mathbb{R}^n)}
\]

and the sum is taken over all distinct multi-indices of length \( l+1 \). The \( L^2 \) norm of each of these is computed with respect to the metric \( g \) as indicated. We use the obvious analogous definition for \( \|\partial^{l+1} v\|_{L^2(\mathbb{R}^n)} \).

Note that by definition \( u \in H^k(\mathbb{R}^n, N) \) if \( \exists y_u \in N \) such that for \( v = w \circ u \)

\[
\|v - w(y_u)\|_{L^2} + \|\partial v\|_{H^{k-1}} < \infty.
\]

Our immediate goal is to show that for \( k > \frac{n}{2} + 1 \) if \( v = w \circ u \) then

\[
\|\partial v\|_{H^k} < \infty \text{ if and only if } \|\nabla u\|_{H^k} < \infty.
\]
Lemma 4.4. For each \( k \geq 0 \) we have

\[
\nabla^{k+1} u = \partial^{k+1} u + \sum_{i=2}^{k+1} \sum_{j_1+\cdots+j_i = k+1} G_{(j_1, \ldots, j_i)}(u) \partial^{j_1} u \cdots \partial^{j_i} u \tag{4.49}
\]

\[
\nabla^{k+1} u = \nabla^{k+1} u + \sum_{i=2}^{k+1} \sum_{j_1+\cdots+j_i = k+1} E_{(j_1, \ldots, j_i)}(u) \nabla^{j_1} u \cdots \nabla^{j_i} u \tag{4.50}
\]

\[
\partial^{k+1} v = \frac{\partial u^a}{\partial y^j} \partial^{k+1} u^j e_a + \sum_{i=2}^{k+1} \sum_{j_1+\cdots+j_i = k+1} F_{(j_1, \ldots, j_i)}(u) \partial^{j_1} u \cdots \partial^{j_i} u \tag{4.51}
\]

where each subscript \( j_s \geq 1 \), and

\[
G_{(j_1, \ldots, j_i)}(u) = G_{(j_1, \ldots, j_i)}^j(u) \frac{\partial}{\partial y^j}
\]

\[
E_{(j_1, \ldots, j_i)}(u) = E_{(j_1, \ldots, j_i)}^j(u) \frac{\partial}{\partial y^j}
\]

\[
F_{(j_1, \ldots, j_i)}(u) = F_{(j_1, \ldots, j_i)}^a(u)e_a
\]

and each \( G, E \) and \( F \) are smooth, bounded functions of \( u \).

The notation \( a_{j_1} \ast \cdots \ast a_{j_i} \) corresponds to a product of the \( a_{j_k} \)'s.

Remark 2. Throughout this section whenever expressions similar to the right hand side of (4.49), (4.50) or (4.51) occur, a key point is to note that all the subscripts \( j_s \geq 1 \), for \( s \in \{1, \ldots, l\} \). This is always to be understood even if it is not explicitly stated.

Proof. We establish each of these by induction, beginning with (4.49). Note that for \( k = 0 \), \( \nabla u = \partial u \). For \( k = 1 \)

\[
\nabla_{\alpha_2} \nabla_{\alpha_1} u = \nabla_{\alpha_2} \left( \frac{\partial u^i}{\partial x^{\alpha_1}} \frac{\partial}{\partial y^j} \right) = \left( \frac{\partial^2 u^i}{\partial x^{\alpha_2} \partial x^{\alpha_1}} \frac{\partial}{\partial y^j} + \Gamma^j_{ik} \frac{\partial u^i}{\partial x^{\alpha_1}} \frac{\partial u^k}{\partial y^j} \right).\]
Then
\[ \nabla^{k+2} u = \nabla^{\alpha_k+2} \nabla^{k+1} u \]
\[ = \nabla^{\alpha_k+2} (\nabla^{\alpha_{k+1}} \cdots \nabla^{\alpha_1} u) \]
\[ = \nabla^{\alpha_k+2} \left( \frac{\partial^{k+1} u^j}{\partial x^{\alpha_{k+1}} \cdots \partial x^{\alpha_1}} \frac{\partial}{\partial y^j} \right) \]
\[ + \nabla^{\alpha_k+2} \left( \sum_{l=2}^{k+1} \sum_{j_1 + \cdots + j_l = k+1} \left( G_{j_1, \ldots, j_l}^j (u) \partial^{j_1} u^* \cdots \partial^{j_l} u^* \right) \right) \]
\[ = \partial^{k+2} u + \Gamma^{j}_{i l} \frac{\partial^{k+1} u^i}{\partial x^{\alpha_{k+1}} \cdots \partial x^{\alpha_1}} \frac{\partial u^l}{\partial y^j} \frac{\partial}{\partial y^j} \]
\[ + \sum_{l=2}^{k+1} \sum_{j_1 + \cdots + j_l = k+1} \left( G_{j_1, \ldots, j_l}^j (u) \partial^{j_1} u^* \cdots \partial^{j_l} u^* \right) \]
\[ + \sum_{l=2}^{k+1} \sum_{j_1 + \cdots + j_l = k+2} G_{j_1, \ldots, j_l}^i (u) \partial^{j_1} u^* \cdots \partial^{j_l} u^* \partial u^l \frac{\partial}{\partial x^{\alpha_1}} \]
\[ + \sum_{l=2}^{k+1} \sum_{j_1 + \cdots + j_l = k+2} G_{j_1, \ldots, j_l}^i (u) \partial^{j_1} u^* \cdots \partial^{j_l} u^* \partial u^l \frac{\partial}{\partial x^{\alpha_1}} \frac{\partial u^l}{\partial y^j} \frac{\partial}{\partial y^j} \]

Therefore
\[ \nabla^{k+2} u = \partial^{k+2} u + \sum_{l=2}^{k+2} \sum_{j_1 + \cdots + j_l = k+2} G_{j_1, \ldots, j_l}^i (u) \partial^{j_1} u^* \cdots \partial^{j_l} u^* \partial u^l \]

which completes the proof of (4.49). The proof of (4.50) proceeds in a similar fashion and is left to the reader.

To prove (4.51) we recall that \( v = w \circ u \) and thus

\[ \partial v^a = \partial w^a \frac{\partial}{\partial x^{\alpha_1}} \]

which is the case \( k = 0 \). When \( k = 1 \) we differentiate this to obtain

\[ \frac{\partial^2 v^a}{\partial x^{\alpha_2} \partial x^{\alpha_1}} = \frac{\partial w^a}{\partial y^j} \frac{\partial^2 w^i}{\partial y^j \partial x^{\alpha_1}} + \frac{\partial w^a}{\partial y^j} \frac{\partial u^j}{\partial x^{\alpha_1}} \frac{\partial w^i}{\partial x^{\alpha_1}} \]

Assume now that (4.51) holds for some \( k \geq 1 \). Then

\[ \partial^{k+2} v = \partial^{\alpha_{k+2}} (\partial^{k+1} v) \]
\[ = \partial w^a \frac{\partial^{k+2} w^i}{\partial y^j} + \partial^2 w^a \frac{\partial^{k+1} w^i}{\partial y^j \partial y^j} \frac{\partial u^i}{\partial x^{\alpha_{k+2}} e_a} \]
\[ + \sum_{l=2}^{k+2} \sum_{j_1 + \cdots + j_l = k+2} F_{j_1, \ldots, j_l} (u) \partial^{j_1} u^* \cdots \partial^{j_l} u^*. \]

This implies (4.51) and completes the proof of the Lemma. \(\square\)

Combining (4.50) and (4.51) in Lemma 4.4 we obtain the following.
THE CAUCHY PROBLEM FOR SCHRÖDINGER FLOWS INTO KÄHLER MANIFOLDS

Lemma 4.5. For $v = w \circ u$ and $k \geq 0$ we have

\[ \partial^{k+1} v^a = \frac{\partial w^a}{\partial y^j} (\nabla^{k+1} u)^j + \sum_{l=2}^{k+1} \sum_{j_l = k+1} H^a_{(j_1, \ldots, j_l)}(u) \nabla^{j_1} u \cdots \nabla^{j_l} u \]

where, as before, each subscript $j_s \geq 1$ and each $H^a$ is a smooth, bounded function of $u$.

We now proceed to bound the pointwise norms in terms of each other.

Lemma 4.6. For $v = w \circ u$ and $k \geq 0$ there is a constant $C > 1$ depending only on $n$ and $k$ such that

\[ |\partial^{k+1} v|^2 \leq C |\nabla^{k+1} u|^2 + C \sum_{l=2}^{k+1} \sum_{j_l = k+1} |\nabla^{j_1} u|^2 \cdots |\nabla^{j_l} u|^2 \]

and

\[ |\nabla^{k+1} u|^2 \leq C |\partial^{k+1} v|^2 + C \sum_{l=2}^{k+1} \sum_{j_l = k+1} |\partial^{j_1} v|^2 \cdots |\partial^{j_l} v|^2 \]

Proof. Using (4.53) we have

\[
\sum_{a=1}^p |\partial^{k+1} v^a|^2 = \sum_{a=1}^p \sum_{|\alpha| = k+1} |\partial_{\alpha+1} \cdots \partial_{\alpha_1} v^a|^2 \\
= \sum_{a=1}^p \frac{\partial w^a}{\partial y^j} (\nabla^{k+1} u)^j \frac{\partial w^a}{\partial y^i} (\nabla^{k+1} u)^i \\
+ \sum_{l=2}^{k+1} \sum_{j_l = k+1} H^a_{(j_1, \ldots, j_l)}(u) \nabla^{j_1} u \cdots \nabla^{j_l} u \sum_{l=2}^{k+1} \sum_{j_l = k+1} H^a_{(j_1, \ldots, j_l)}(u) \nabla^{j_1} u \cdots \nabla^{j_l} u \\
+ 2 \frac{\partial w^a}{\partial y^j} (\nabla^{k+1} u)^j \sum_{l=2}^{k+1} \sum_{j_l = k+1} H^a_{(j_1, \ldots, j_l)}(u) \nabla^{j_1} u \cdots \nabla^{j_l} u.
\]

Since $w : N \to \mathbb{R}^p$ is an isometric embedding we note that

\[ g_{ij} = \sum_{a=1}^p \frac{\partial w^a}{\partial y^i} \frac{\partial w^a}{\partial y^j}. \]

Therefore, using the fact that for any $l \geq 1$

\[ C^{-1} \sum_{i=1}^k |(\nabla^l u)^i|^2 \leq |\nabla^l u|^2 = g_{ij} (\nabla^l u)^i (\nabla^l u)^j \leq C \sum_{i=1}^k |(\nabla^l u)^i|^2 \]

we have

\[
\sum_{a=1}^p |\partial^{k+1} v^a|^2 \leq 2 |\nabla^{k+1} u|^2 + 2C \sum_{l=2}^{k+1} \sum_{j_l = k+1} |\nabla^{j_1} u|^2 \cdots |\nabla^{j_l} u|^2
\]

which establishes (4.54). To prove (4.55) we proceed by induction. For $k = 0$ we have

\[ \nabla_a u = \frac{\partial u^i}{\partial x^a} \frac{\partial}{\partial y^i}. \]
Using (4.52) and (4.56) this implies
\[ |\nabla_\alpha u|^2 = g_{ij} \frac{\partial u^i}{\partial x^\alpha} \frac{\partial u^j}{\partial x^\alpha} = \frac{\partial v^\alpha}{\partial x^\alpha} \frac{\partial v_{\alpha}}{\partial x^\alpha} \]
Therefore
\[ |\nabla u|^2 = |\partial v|^2. \] (4.57)
Note that for \( k = 1 \), by (4.53) we have
\[ \partial w^a_{\alpha} \partial y^j (\nabla^2 u) = \partial^2 w^a - H^a(u) \nabla u \ast \nabla u. \]
So that
\[ |\nabla^2 u|^2 \leq 2|\partial^2 v|^2 + C|\nabla u|^4 \]
or
\[ |\nabla^2 u|^2 \leq 2|\partial^2 v|^2 + C|\partial v|^4. \] (4.58)
Assume now that (4.55) holds for any \( k \geq 1 \). Again using (4.53) we then have
\[ |\nabla^{k+2} u|^2 \leq 2|\partial^{k+2} v|^2 + C \sum_{l=2}^{k+2} \sum_{j_1+\cdots+j_l = k+2} |\nabla^{j_1} u|^2 \cdots |\nabla^{j_l} u|^2 \]
which completes the proof of Lemma 4.6. \( \square \)

**Lemma 4.7.** Assume that \( k > \frac{n}{2} + 1 \). There exists a constant \( C = C(N,k,n) \) such that for \( u \in C^\infty(\mathbb{R}^n,N) \) constant outside a compact set of \( \mathbb{R}^n \) if \( v = w \circ u \) then
\[ \|\nabla^{k+1} u\|_{L^2} \leq C \sum_{l=1}^{k} \|\partial^l v\|_{H^k}. \] (4.59)
\[ \|\partial^{k+1} v\|_{L^2} \leq C \sum_{l=1}^{k} \|\nabla^l u\|_{H^k}. \] (4.60)

**Proof.** By (4.55) we have
\[ \|\nabla^{k+1} u\|_{L^2} \leq C \|\partial^{k+1} v\|_{L^2} + C \sum_{l=2}^{k+1} \sum_{j_1+\cdots+j_l = k+1} \left( \int_{\mathbb{R}^n} |\partial^{j_1} v|^2 \cdots |\partial^{j_l} v|^2 \right)^{\frac{1}{2}}. \]
Let \( 2 \leq p_i \leq \infty, i = 1, \ldots, l \) be such that
\[ \frac{1}{p_1} + \cdots + \frac{1}{p_l} = \frac{1}{2}. \] (4.62)
Then by Hölder’s inequality
\[ \|\partial^{j_1} v \cdots |\partial^{j_l} v\|_{L^2} \leq \|\partial^{j_1} v\|_{L^{p_1}} \cdots \|\partial^{j_l} v\|_{L^{p_l}}. \]
Since \( k \geq \frac{n}{2} + 1 \) then
\[ \frac{j_i - 1}{k} < a_i = \frac{j_i - 1}{k} + \frac{n}{2k^2} \left( k - j_i + \frac{1}{l} \right) < 1 \] (4.64)
and

\[ \frac{1}{2} \geq \frac{1}{p_i} = \frac{j_i - 1}{n} + \frac{1}{2} - \frac{k a_i}{n} > 0. \]

Note that to ensure that \( a_i < 1 \) in (4.64) we either need \( n \leq 3 \) or we must have \( \left( \frac{n}{2k} - 1 \right) \left( k - j_i + \frac{1}{2} \right) < 1 - \frac{1}{2} \). Since \( 2 \leq l \leq k + 1 \) and \( 1 \leq j_i \leq k \) the previous inequality holds provided \( \left( \frac{n}{2k} - 1 \right) \left( k - j_i + \frac{1}{2} \right) < \frac{1}{2} \). Thus to accommodate all values of \( n \) simultaneously, it is enough to choose \( k \geq \frac{n}{2} + 1 \) and \( k \in \mathbb{N} \).

Thus to accommodate all values of \( n \) simultaneously, it is enough to choose \( k \geq \frac{n}{2} + 1 \) and \( k \in \mathbb{N} \).

Thus (4.5) in Proposition 4.1 yields

\[ \| \partial^{j_i} v \|_{L^{p_i}} \leq C \| \partial^{k+1} v \|_{L^2}^{\frac{a_i}{n}} \| \partial v \|_{L^2}^{1 - a_i} \leq C \| \partial v \|_{H^k}. \]

Therefore combining (4.61), (4.63) and (4.66) we have

\[ \| \nabla^{k+1} u \|_{L^2} \leq C \sum_{l=1}^{k} \| \partial v \|_{H^k}^l. \]

A similar argument to the one above where Proposition 4.1 is now applied to \( \nabla u \) rather than \( \partial v \) yields (4.60).

**Lemma 4.8.** There exists a constant \( C = C(N, n) \) such that if \( u \in C^\infty(\mathbb{R}^n, N) \) is constant outside a compact set of \( \mathbb{R}^n \) and \( v = w \circ u \) then for \( 1 \leq k \leq \frac{n}{2} + 1 \)

\[ \| \nabla^{k+1} u \|_{L^2} \leq C \sum_{l=1}^{k} \| \partial v \|_{H^k}^l. \]

**Proof.** The proof is very similar to that of Lemma 4.7, where the \( a_i \)'s and \( p_i \)'s in the interpolation are taken as follows

\[ \frac{j_i - 1}{s_0} < a_i = \frac{j_i - 1}{s_0} + \frac{n}{2ks_0} (k - j_i + l^{-1}) < 1, \]

where \( s_0 = \left[ \frac{n}{2} \right] + 2 \), and

\[ \frac{1}{2} \geq \frac{1}{p_i} = \frac{j_i - 1}{n} + \frac{1}{n} - \frac{s_0}{n} a_i > 0. \]

**Remark 4.9.** Proposition 4.1 holds for \( s \in C^m_c(E) \) where \( E \) is a finite dimensional \( C^m \) vector bundle over \( \mathbb{R}^n \) provided \( k < m \). Similarly Lemma 4.7 holds for \( u \in C^m(\mathbb{R}^n, N) \) and \( u \) constant outside a compact set of \( \mathbb{R}^n \), provided once again that \( m > k \). A simple approximation theorem ensures that Lemma 4.7 holds for \( u \in C^m(\mathbb{R}^n, N) \cap H^k(\mathbb{R}^n, N) \) with \( m > k \).
Corollary 4.10. Assume that $k \geq \frac{n}{2} + 4$. There exists a constant $C = C(N, k, n)$ such that for $u \in C^{k+1}(\mathbb{R}^n, N) \cap H^k(\mathbb{R}^n, N)$

\begin{align}
\|\nabla u\|_{L^\infty} &\leq C \sum_{j=0}^{\lfloor \frac{n}{2} \rfloor + 2} \|\partial^{j+1} v\|_{L^2} \\
\|\nabla^2 u\|_{L^\infty} &\leq C \sum_{l=1}^{\lfloor \frac{n}{2} \rfloor + 3} \|\partial^{l} v\|_{L^2} \\
\|\nabla^3 u\|_{L^\infty} &\leq C \sum_{l=1}^{\lfloor \frac{n}{2} \rfloor + 4} \|\partial^{l+1} v\|_{L^2}.
\end{align}

Proof. Recall that $\|\nabla u\| = |\partial v|$ if $v = w \circ u$, and by Sobolev embedding theorem

\begin{align}
\|\partial v\|_{L^\infty} &\leq c\|\partial v\|_{H^\lfloor \frac{n}{2} \rfloor + 2} \\
\|\partial^2 v\|_{L^\infty} &\leq c\|\partial v\|_{H^\lfloor \frac{n}{2} \rfloor + 3} \\
\|\partial^3 v\|_{L^\infty} &\leq c\|\partial v\|_{H^\lfloor \frac{n}{2} \rfloor + 4}
\end{align}

Therefore combining (4.60), (4.69) and (4.75) we have

\begin{align}
\|\nabla u\|_{L^\infty} &\leq C \sum_{j=0}^{\lfloor \frac{n}{2} \rfloor + 2} \|\partial^{j+1} v\|_{L^2} \\
&\leq C \left( \|\nabla u\|_{L^2} + \sum_{j=1}^{\lfloor \frac{n}{2} \rfloor + 2} \|\nabla u\|_{H^\lfloor \frac{n}{2} \rfloor + 2} \right) \\
&\leq C \sum_{j=1}^{\lfloor \frac{n}{2} \rfloor + 2} \|\nabla u\|_{H^\lfloor \frac{n}{2} \rfloor + 2}.
\end{align}

Note that (4.55) ensures that

\begin{align}
|\nabla^2 u| &\leq C|\partial^2 v| + c|\partial v|^2.
\end{align}

Combining (4.75), (4.76), (4.60) and (4.69) we have

\begin{align}
\|\nabla^2 u\|_{L^\infty} &\leq C\|\partial^2 v\|_{L^\infty} + C\|\partial v\|_{L^\infty}^2 \\
&\leq C\|\partial v\|_{H^\lfloor \frac{n}{2} \rfloor + 3} + C\|\partial v\|_{H^\lfloor \frac{n}{2} \rfloor + 2} \\
&\leq C \sum_{j=0}^{\lfloor \frac{n}{2} \rfloor + 3} \|\partial^{j+1} v\|_{L^2} + C \sum_{j=0}^{\lfloor \frac{n}{2} \rfloor + 2} \|\partial^{j+1} v\|_{L^2} \\
&\leq C \sum_{l=1}^{\lfloor \frac{n}{2} \rfloor + 4} \|\nabla u\|_{H^\lfloor \frac{n}{2} \rfloor + 3}.
\end{align}
Note that (4.55) also ensures that

\[(4.81) \quad \|\nabla^3 u\|_{L^\infty} \leq C(\|\partial^3 v\| + \|\partial^2 v\| \|\partial v\| + \|\partial v\|^3).\]

Combining (4.75), (4.76), (4.77), (4.60) and (4.69) we have

\[(4.82) \quad \|\nabla^3 u\|_{L^\infty} \leq C \sum_{j=1}^{3(\lfloor \frac{s}{2}\rfloor+4)} \|\nabla u\|_{H^\lfloor \frac{s}{2}\rfloor+4}^j.\]

\[\square\]

5. \(\varepsilon\)-independent energy estimates

Theorem 3.1 ensures that the initial value problem

\[
\begin{align*}
\frac{\partial \varepsilon}{\partial t} &= -\varepsilon \Delta^2 v + N(v) \\
v(0) &= u_0,
\end{align*}
\]

has a unique solution \(v_\varepsilon \in C([0,T_\varepsilon],H^{s+1} \cap L^2_{\varepsilon})\) provided \(v_0 \in H^{s+1}(\mathbb{R}^n,\mathbb{R}^n)\) for \(s > \lfloor \frac{n}{2}\rfloor + 4\). To prove that (1.4) has a solution we need to show that (2.10) has a solution for \(\varepsilon = 0\). To do this we need to show that each \(v_\varepsilon\) extends to a solution in \(C([0,T],H^{s+1} \cap L^2_{s})\) where \(T > 0\) is independent of \(\varepsilon\). This is accomplished by proving \(\varepsilon\)-independent energy estimates for the function \(v_\varepsilon\). It turns out that thanks to the geometric nature of this flow, if one assumes enough regularity (i.e. \(s > \lfloor \frac{n}{2}\rfloor + 4\)), it is easier to prove \(\varepsilon\)-independent energy estimates for the corresponding \(u_\varepsilon\). Lemma 4.7 and Lemma 4.8 then allows us to translate these into estimates for \(v_\varepsilon\).

Let \(u_\varepsilon = u \in C([0,T_\varepsilon],H^{s+1}(\mathbb{R}^n,\mathbb{N}))\) with \(s\) large enough\(^2\) be a solution of

\[(5.1) \quad \begin{align*}
\frac{\partial \varepsilon}{\partial t} &= -\varepsilon \Delta \tau(u) + \varepsilon R(\nabla u, \tau(u))\nabla u + J(u)\tau(u) + \beta\tau(u) \\
\v(0) &= u_0,
\end{align*}\]

where \(\varepsilon \in (0,1], \beta \geq 0, \Delta = \sum_{\alpha=1}^{n} \nabla_\alpha \nabla_\alpha\). Our goal is to understand how \(\|\nabla u\|_{H^s}(t)\) varies with time.

Let \(l \in \mathbb{N}\). We denote by \(\alpha\) the multi-index of length \(l\), \(\alpha = (\alpha_1 \cdots \alpha_l)\), and \(\nabla_\alpha u = \nabla_{\alpha_1} \cdots \nabla_{\alpha_l} u\). The following lemma and corollaries establish some computational identities which are very useful.

**Lemma 5.1.** Let \(u \in C^1([0,T],H^s(\mathbb{R}^n,\mathbb{N}))\), \(s \in \mathbb{N}, s > \frac{n}{2} + 2\). Let \(X \in TN\) for \(1 \leq l \leq s\) and \(|\alpha| = l\). We have

\[(5.2) \quad \nabla_{\alpha_0} \nabla_\alpha u = \nabla_\alpha \nabla_{\alpha_0} u + \sum_{j=0}^{l-2} \nabla_{\alpha_1} \cdots \nabla_{\alpha_j} [R(\nabla_{\alpha_0} u, \nabla_{\alpha_{j+1}} u)\nabla_{\alpha_{j+2}} \cdots \nabla_{\alpha_l} u],\]

\[(5.3) \quad \nabla_t \nabla_\alpha u = \nabla_\alpha \nabla_t u + \sum_{j=0}^{l-2} \nabla_{\alpha_1} \cdots \nabla_{\alpha_j} [R(\nabla_t u, \nabla_{\alpha_{j+1}} u)\nabla_{\alpha_{j+2}} \cdots \nabla_{\alpha_l} u],\]

\[(5.4) \quad \nabla_{\alpha_0} \nabla_\alpha X = \nabla_\alpha \nabla_{\alpha_0} X + \sum_{j=0}^{l-1} \nabla_{\alpha_1} \cdots \nabla_{\alpha_j} [R(\nabla_{\alpha_0} u, \nabla_{\alpha_{j+1}} u)\nabla_{\alpha_{j+2}} \cdots \nabla_{\alpha_l} X].\]

\[\text{\textsuperscript{2}}\text{We will see later that } s > \lfloor \frac{n}{2}\rfloor + 4 \text{ will be enough. In this paper we do not attempt to obtain the lowest possible exponent } s.\]
Proof. The proof is done by induction on the length of the multi-index $\alpha$, i.e., on $l$. We prove (5.4) and leave (5.2) and (5.3) to the reader, as the proofs are very similar. If $l = 1$

\begin{equation}
\nabla_{\alpha_0} \nabla_{\alpha_1} X = \nabla_{\alpha_1} \nabla_{\alpha_0} X + R(\nabla_{\alpha_0} u, \nabla_{\alpha_1} u) X.
\end{equation}

Suppose (5.4) holds for $l \geq 1$ and consider

\begin{equation}
\nabla_{\alpha_0} \nabla_{\alpha_1} \cdots \nabla_{\alpha_{l+1}} X
\end{equation}

\begin{align*}
&= \nabla_{\alpha_1} [\nabla_{\alpha_0} \nabla_{\alpha_2} \cdots \nabla_{\alpha_{l+1}} X] + R(\nabla_{\alpha_0} u, \nabla_{\alpha_1} u) \nabla_{\alpha_2} \cdots \nabla_{\alpha_{l+1}} X \\
&= \nabla_{\alpha_1} \cdots \nabla_{\alpha_{l+1}} X + R(\nabla_{\alpha_0} u, \nabla_{\alpha_1} u) \nabla_{\alpha_2} \cdots \nabla_{\alpha_{l+1}} X \\
&\quad + \nabla_{\alpha_1} \sum_{j=1}^{l} \nabla_{\alpha_2} \cdots \nabla_{\alpha_j} [R(\nabla_{\alpha_0} u, \nabla_{\alpha_{j+1}} u) \nabla_{\alpha_{j+2}} \cdots \nabla_{\alpha_{l+1}} X] \\
&= \nabla_{\alpha_1} \cdots \nabla_{\alpha_{l+1}} \nabla_{\alpha_0} X \\
&\quad + \sum_{j=0}^{l} \nabla_{\alpha_1} \cdots \nabla_{\alpha_j} [R(\nabla_{\alpha_0} u, \nabla_{\alpha_{j+1}} u) \nabla_{\alpha_{j+2}} \cdots \nabla_{\alpha_{l+1}} X]
\end{align*}

\[\square\]

Corollary 5.2. Let $u \in C^1([0, T], H^s(\mathbb{R}^n, N))$ $s \in \mathbb{N}$, $s > \frac{n}{2} + 2$, then for $1 \leq l \leq s$, $|\alpha| = l$ we have

\begin{equation}
\Delta \nabla_\alpha u = \nabla_\alpha \tau(u) + \sum_{j=0}^{l-1} \nabla_{\alpha_1} \cdots \nabla_{\alpha_j} [R(\nabla_{\alpha_0} u, \nabla_{\alpha_{j+1}} u) \nabla_{\alpha_{j+2}} \cdots \nabla_{\alpha_l} \nabla_{\alpha_0} u] \\
&\quad + \sum_{j=1}^{l-2} \nabla_{\alpha_0} \nabla_{\alpha_1} \cdots \nabla_{\alpha_j} [R(\nabla_{\alpha_0} u, \nabla_{\alpha_{j+1}} u) \nabla_{\alpha_{j+2}} \cdots \nabla_{\alpha_l} \nabla_{\alpha_0} u]
\end{equation}

\begin{equation}
\nabla_t \nabla_\alpha \nabla_{\alpha_0} u = \nabla_\alpha \nabla_{\alpha_0} \nabla_t u \\
&\quad + \sum_{j=0}^{l-1} \nabla_{\alpha_1} \cdots \nabla_{\alpha_j} [R(\nabla_t u, \nabla_{\alpha_{j+1}} u) \nabla_{\alpha_{j+2}} \cdots \nabla_{\alpha_l} \nabla_{\alpha_0} u]
\end{equation}

\begin{equation}
\nabla_{\beta_0} \nabla_\alpha \nabla_{\alpha_0} u = \nabla_\alpha \nabla_{\alpha_0} \nabla_{\beta_0} u \\
&\quad + \sum_{j=0}^{l-1} \nabla_{\alpha_1} \cdots \nabla_{\alpha_j} [R(\nabla_{\beta_0} u, \nabla_{\alpha_{j+1}} u) \nabla_{\alpha_{j+2}} \cdots \nabla_{\alpha_l} \nabla_{\alpha_0} u]
\end{equation}

Proof. The proof of (5.7) is an application of (5.2) and (5.4). To prove (5.8) and (5.9) apply (5.4) to $\nabla_{\alpha_0} u = X$ and note that $\nabla_t$ and $\nabla_{\beta_0}$ behave the same way. Moreover recall that $\nabla_{\alpha_0} \nabla_t u = \nabla_t \nabla_{\alpha_0} u$. \[\square\]
Corollary 5.3. Let \( u \in C^1([0,T], H^s(\mathbb{R}^n, N)) \), \( s \in \mathbb{N} \ s > \frac{n}{2} + 2 \). Let \( X \in TN \) then for \( l \geq 1 \) and \( |\alpha| = l \) we have

\[
\Delta \nabla_\alpha X = \nabla_\alpha \Delta X \\
+ \sum_{j=0}^{l-1} \nabla_{\alpha_1} \cdots \nabla_{\alpha_j} [R(\nabla_{\alpha_0} u, \nabla_{\alpha_{j+1}} u) \nabla_{\alpha_{j+2}} \cdots \nabla_{\alpha_l} \nabla_{\alpha_0} X] \\
+ \sum_{j=0}^{l-1} \nabla_{\alpha_0} \nabla_{\alpha_1} \cdots \nabla_{\alpha_j} [R(\nabla_{\alpha_0} u, \nabla_{\alpha_{j+1}} u) \nabla_{\alpha_{j+2}} \cdots \nabla_{\alpha_l} X].
\]

Proof. To prove (5.10) we apply (5.4) twice, first to \( X \) then for \( \nabla_{\alpha_0} X \).

\[
\Delta \nabla_\alpha X = \nabla_{\alpha_0} \nabla_{\alpha_0} \nabla_\alpha X \\
= \nabla_{\alpha_0} [\nabla_\alpha \nabla_{\alpha_0} X + \nabla_{\alpha_0} \sum_{j=0}^{l-1} \nabla_{\alpha_1} \cdots \nabla_{\alpha_j} [R(\nabla_{\alpha_0} u, \nabla_{\alpha_{j+1}} u) \nabla_{\alpha_{j+2}} \cdots \nabla_{\alpha_l} X] \\
+ \sum_{j=0}^{l-1} \nabla_{\alpha_0} \nabla_{\alpha_1} \cdots \nabla_{\alpha_j} [R(\nabla_{\alpha_0} u, \nabla_{\alpha_{j+1}} u) \nabla_{\alpha_{j+2}} \cdots \nabla_{\alpha_l} X].
\]

Remark 5.4. Note that in particular (5.10) applied to \( X = \tau(u) \) yields

\[
\Delta \nabla_\alpha \tau(u) = \nabla_\alpha \Delta \tau(u) \\
+ \sum_{j=0}^{l-1} \nabla_{\alpha_1} \cdots \nabla_{\alpha_j} [R(\nabla_{\alpha_0} u, \nabla_{\alpha_{j+1}} u) \nabla_{\alpha_{j+2}} \cdots \nabla_{\alpha_l} \nabla_{\alpha_0} \tau(u)] \\
+ \sum_{j=0}^{l-1} \nabla_{\alpha_0} \nabla_{\alpha_1} \cdots \nabla_{\alpha_j} [R(\nabla_{\alpha_0} u, \nabla_{\alpha_{j+1}} u) \nabla_{\alpha_{j+2}} \cdots \nabla_{\alpha_l} \tau(u)].
\]

Lemma 5.5. Let \( u \in C^1([0,T], H^s(\mathbb{R}^n, N)) \) with \( s \in \mathbb{N} \) and \( s \geq \left\lceil \frac{n}{2} \right\rceil + 4 \) be a solution of (5.1). Then for \( \left\lceil \frac{n}{2} \right\rceil + 4 \leq l \leq s \) and \( l \in \mathbb{N} \) we have

\[
\frac{d}{dt} \| \nabla^l u \|^2_{L^2} \leq C \| \nabla u \|^2_{H^{l-1}} (1 + \| \nabla u \|^3_{H^{l+1}}^2).
\]

For \( l = \left\lceil \frac{n}{2} \right\rceil + 2 \) and \( l = \left\lceil \frac{n}{2} \right\rceil + 3 \) we have

\[
\frac{d}{dt} \| \nabla^l u \|^2_{L^2} \leq C \left( 1 + \| \nabla u \|^3_{H_{\left\lceil \frac{n}{2} \right\rceil + 4}}^2 \right) \| \nabla u \|^2_{H^{l-1}} (1 + \| \nabla u \|^2_{H^{l+1}}^2).
\]
Proof. We first compute the evolution

\[
\frac{1}{2} \frac{d}{dt} \int_{\mathbb{R}^n} |\nabla u|^2 \, dx = \sum_{\alpha_0=1}^{n} \int \langle \nabla_t \nabla_{\alpha_0} u, \nabla_{\alpha_0} u \rangle \\
= \int \nabla_{\alpha_0} \langle \nabla_t u, \nabla_{\alpha_0} u \rangle - \int \langle \nabla_t u, \tau(u) \rangle \\
= \varepsilon \int \langle \Delta \tau(u), \tau(u) \rangle - \varepsilon \int \langle \nabla \nabla_t u, \nabla, \tau(u) \rangle - \int \langle J(u) \tau(u), \tau(u) \rangle - \beta \int |\tau(u)|^2 \\
= -\varepsilon \int |\nabla \tau(u)|^2 - \beta \int |\tau(u)|^2 \\
- \varepsilon \int \langle R(\nabla u, \tau(u)) \nabla u, \tau(u) \rangle,
\]

where we have used the fact that for \( f \in L^1(\mathbb{R}^n, \mathbb{R}^n) \int_{\mathbb{R}^n} \text{div} f = 0 \) as well as integration by parts. Note that using integration by parts and Cauchy-Schwarz we have

\[
\left| \int \langle R(\nabla u, \tau(u)) \nabla u, \tau(u) \rangle \right| \leq C \|\nabla u\|_{L^\infty}^2 \int |\tau(u)|^2 \\
\leq C \|\nabla u\|_{L^\infty}^2 \|\nabla u\|_{L^2} \|\nabla \tau(u)\|_{L^2} \\
\leq \frac{1}{2} \|\nabla \tau(u)\|_{L^2}^2 + C \|\nabla u\|_{L^\infty}^4 \|\nabla u\|_{L^2}^2.
\]

Combining (5.15) and (5.16) we have

\[
\frac{1}{2} \frac{d}{dt} \|\nabla u\|_{L^2}^2 \leq C \|\nabla u\|_{L^\infty}^4 \|\nabla u\|_{L^2}^2.
\]

For \( 1 \leq l \leq s \) applying (5.3) we have

\[
\frac{1}{2} \frac{d}{dt} \|\nabla^l u\|_{L^2}^2 = \sum_{|\alpha|=l} \int \langle \nabla_t \nabla_{\alpha} u, \nabla_{\alpha} u \rangle \\
= \sum_{|\alpha|=l} \int \langle \nabla_{\alpha} \nabla_t u, \nabla_{\alpha} u \rangle \\
+ \sum_{|\alpha|=l} \sum_{j=0}^{l-2} \int \langle \nabla_{\alpha_1} \cdots \nabla_{\alpha_j} [R(\nabla_t u, \nabla_{\alpha_{j+1}} u) \nabla_{\alpha_{j+2}} \cdots \nabla_{\alpha_l} u], \nabla_{\alpha} u \rangle.
\]

Consider each term separately

\[
\int \langle \nabla_{\alpha} \nabla_t u, \nabla_{\alpha} u \rangle = -\varepsilon \int \langle \nabla_{\alpha} \Delta \tau(u), \nabla_{\alpha} u \rangle \\
+ \varepsilon \int \langle \nabla_{\alpha} (R(\nabla u, \tau(u)) \nabla u, \nabla_{\alpha} u \rangle \\
+ \int \langle \nabla_{\alpha} J(u) \tau(u), \nabla_{\alpha} u \rangle + \beta \int \langle \nabla_{\alpha} \tau(u), \nabla_{\alpha} u \rangle.
\]
Using (5.12) and (5.7) and integrating by parts we have that

\begin{equation}
\int \langle \nabla_{\alpha} \Delta \tau(u), \nabla_{\alpha} u \rangle = \int \langle \nabla_{\alpha} \tau(u), \Delta \nabla_{\alpha} u \rangle
\end{equation}

\begin{align*}
&- \sum_{j=0}^{l-1} \int \langle \nabla_{\alpha_1} \cdots \nabla_{\alpha_j} [R(\nabla_{\alpha_0} u, \nabla_{\alpha_{j+1}} u) \nabla_{\alpha_{j+2}} \cdots \nabla_{\alpha_l} \nabla_{\alpha_0} \tau(u)], \nabla_{\alpha} u \rangle \\
&- \sum_{j=0}^{l-1} \int \langle \nabla_{\alpha_0} \nabla_{\alpha_1} \cdots \nabla_{\alpha_j} [R(\nabla_{\alpha_0} u, \nabla_{\alpha_{j+1}} u) \nabla_{\alpha_{j+2}} \cdots \nabla_{\alpha_l} \tau(u)], \nabla_{\alpha} u \rangle \\
&= \int |\nabla_{\alpha} \tau(u)|^2 \\
&+ \sum_{j=0}^{l-1} \int \langle \nabla_{\alpha_1} \cdots \nabla_{\alpha_j} [R(\nabla_{\alpha_0} u, \nabla_{\alpha_{j+1}} u) \nabla_{\alpha_{j+2}} \cdots \nabla_{\alpha_l} \tau(u)], \nabla_{\alpha} u \rangle \\
&- \sum_{j=0}^{l-1} \int \langle \nabla_{\alpha_0} \nabla_{\alpha_1} \cdots \nabla_{\alpha_j} [R(\nabla_{\alpha_0} u, \nabla_{\alpha_{j+1}} u) \nabla_{\alpha_{j+2}} \cdots \nabla_{\alpha_l} \tau(u)], \nabla_{\alpha} u \rangle \\
&- \sum_{j=0}^{l-2} \int \langle \nabla_{\alpha_0} \nabla_{\alpha_1} \cdots \nabla_{\alpha_j} [R(\nabla_{\alpha_0} u, \nabla_{\alpha_{j+1}} u) \nabla_{\alpha_{j+2}} \cdots \nabla_{\alpha_l} \tau(u)], \nabla_{\alpha} u \rangle
\end{align*}

(5.20) yields

\begin{equation}
- \varepsilon \sum_{|\alpha|=l} \int \langle \nabla_{\alpha} \Delta \tau(u), \nabla_{\alpha} u \rangle \leq - \varepsilon \int |\nabla^l \tau(u)|^2 \\
+ C \varepsilon \sum_{m=3}^{l+2} \sum_{j_1 + \cdots + j_m = l+2} \int |\nabla^j \tau(u)| \nabla^{j_1} u \cdots \nabla^{j_m} u \\
+ C \varepsilon \sum_{m=3}^{l+2} \sum_{j_1 + \cdots + j_m = l+2} \int |\nabla^j \tau(u)| \nabla^{j_1} u \cdots \nabla^{j_m} u \nabla^l u.
\end{equation}

Similarly

\begin{equation}
\sum_{|\alpha|=l} \int \langle \nabla_{\alpha} [R(\nabla u, \tau(u)) \nabla u], \nabla_{\alpha} u \rangle \leq \\
\leq C \sum_{m=3}^{l+2} \sum_{j_1 + \cdots + j_m = l+2} \int |\nabla^j u| |\nabla^{j_1} \tau(u)| \nabla^{j_2} u \cdots \nabla^{j_m} u.
\end{equation}
We now look at the third term in (5.19) and recall that $\nabla J = 0$ and $\langle JX, X \rangle = 0$ for $X \in TN$. Integrating by parts and applying (5.7) we obtain for $\gamma = (\alpha_2 \cdots \alpha_l)$

\begin{equation}
\int \langle \nabla_\alpha J(u) \tau(u), \nabla_\alpha u \rangle \tag{5.23}
\end{equation}

\begin{align*}
&= - \int \langle \nabla_\gamma J(u) \tau(u), \nabla_{\alpha_1} \nabla_\alpha u \rangle \\
&= - \int \langle \nabla_\gamma J(u) \tau(u), \Delta \nabla_\gamma u \rangle \\
&= - \int \langle J(u) \nabla_\gamma \tau(u); \nabla_\gamma \tau(u) \rangle \\
&\quad - \sum_{j=1}^{l-1} \int \langle J(u) \nabla_\gamma \tau(u), \nabla_{\alpha_2} \cdots \nabla_{\alpha_j} [R(\nabla_{\alpha_1} u, \nabla_{\alpha_{j+1}} u, \nabla_{\alpha_{j+2}} \cdots \nabla_{\alpha_l} \nabla_{\alpha_1} u)] \rangle \\
&\quad - \sum_{j=2}^{l-2} \int \langle J(u) \nabla_\gamma \tau(u), \nabla_{\alpha_2} \nabla_{\alpha_3} \cdots \nabla_{\alpha_j} [R(\nabla_{\alpha_1} u, \nabla_{\alpha_{j+1}} u, \nabla_{\alpha_{j+2}} \cdots \nabla_{\alpha_l} \nabla_{\alpha_1} u)] \rangle \\
&\quad \cdots \nabla_{\alpha_j} [R(\nabla_{\alpha_1} u, \nabla_{\alpha_{j+1}} u, \nabla_{\alpha_{j+2}} \cdots \nabla_{\alpha_l} u)].
\end{align*}

Thus (5.23) yields

\begin{equation}
\sum_{|\alpha|=l} \int \langle \nabla_\alpha J(u) \tau(u), \nabla_\alpha u \rangle \tag{5.24}
\end{equation}

\begin{align*}
&\leq C \sum_{m=3}^{l+2} \sum_{\substack{j_1 + \cdots + j_m = l+2 \atop j_s \geq 1}} \int |\nabla^{l-2} \tau(u)| |\nabla^{j_1} u| \cdots |\nabla^{j_m} u|. 
\end{align*}

A very similar computation yields

\begin{equation}
\int \langle \nabla_\alpha \tau(u), \nabla_\alpha u \rangle \tag{5.25}
\end{equation}

\begin{align*}
&\leq - \int |\nabla_\gamma \tau(u)|^2 + C \sum_{m=3}^{l+2} \sum_{\substack{j_1 + \cdots + j_m = l+2 \atop j_s \geq 1}} \int |\nabla^{l-2} \tau(u)| |\nabla^{j_1} u| \cdots |\nabla^{j_m} u|. 
\end{align*}

Combining (5.19), (5.21), (5.22), (5.24) and (5.25) we obtain
We now look at the second term in (5.18). Using equation (5.1) we obtain

\[
\sum_{|\alpha| = l} \int \langle \nabla_\alpha \nabla_t u, \nabla_\alpha u \rangle \\
\leq -\varepsilon \int |\nabla^l \tau (u)|^2 + C \varepsilon \sum_{m=3}^{l+2} \sum_{j_1 + \cdots + j_m = l+2} \int |\nabla^j \tau (u)||\nabla^{j_1} u||\nabla^{j_2} u| \cdots |\nabla^{j_m} u|
\]

\[
+ C \varepsilon \sum_{m=3}^{l+2} \sum_{j_1 + \cdots + j_m = l+2} \int |\nabla^{j_1} \tau (u)||\nabla^{j_2} u||\nabla^{j_3} u| \cdots |\nabla^{j_m} u|
\]

\[
+ C \varepsilon \sum_{m=3}^{l+2} \sum_{j_1 + \cdots + j_m = l+2} \int |\nabla^l u||\nabla^{j_1} \tau (u)||\nabla^{j_2} u||\nabla^{j_3} u| \cdots |\nabla^{j_m} u|
\]

\[
- \beta \int |\nabla^{l-1} \tau (u)|^2 + C \sum_{m=3}^{l+2} \sum_{j_1 + \cdots + j_m = l+2} \int |\nabla^{l-2} \tau (u)||\nabla^{j_1} u||\nabla^{j_2} u| \cdots |\nabla^{j_m} u|.
\]

Combining (5.18), (5.26) and (5.27) we obtain
\begin{align}
(5.28) \quad & \quad \frac{1}{2} \frac{d}{dt} \| \nabla^l u \|^2_{L^2} \\
\leq & \quad - \varepsilon \int |\nabla^l \tau(u)|^2 \\
& + C \varepsilon \int |\nabla^l \tau(u)||\nabla^l u||\nabla u|^2 \\
& + C \varepsilon \int |\nabla^{l-1} \tau(u)||\nabla^l u| (|\nabla u|^3 + |\nabla u| |\nabla^2 u|) \\
& + C \varepsilon \sum_{m=3}^{l+2} \sum_{j_1 + \cdots + j_m = l+2 \atop l \leq j_s \leq l-1} \int |\nabla^l \tau(u)||\nabla^{j_1} u| \cdots |\nabla^{j_m} u| \\
& + C \varepsilon \sum_{m=3}^{l+2} \sum_{j_1 + \cdots + j_m = l+2 \atop j_s \geq 1} \int |\nabla^l u| |\nabla^{j_1} \tau(u)| \cdots |\nabla^{j_m} u| \\
& + C \varepsilon \sum_{m=3}^{l+3} \sum_{j_1 + \cdots + j_m = l+4 \atop j_s \geq 1} \int |\nabla^l u| |\nabla^{j_1} u| \cdots |\nabla^{j_m} u| \\
& + C \sum_{m=3}^{l+2} \sum_{j_1 + \cdots + j_m = l+2 \atop l \leq j_s \leq l-1} \int |\nabla^l \tau(u)||\nabla^{j_1} u| \cdots |\nabla^{j_m} u| - \beta \int |\nabla^{l-1} \tau(u)|^2 \\
\leq & \quad - \varepsilon \int |\nabla^l \tau(u)|^2 + C \varepsilon \int |\nabla^l \tau(u)||\nabla^l u||\nabla u|^2 \\
& + C \varepsilon \int |\nabla^{l-1} \tau(u)||\nabla^l u| (|\nabla u|^3 + |\nabla^2 u| |\nabla u|) \\
& + C \varepsilon \int |\nabla^l u| |\tau(u)||\nabla^{l+1} u| |\nabla u| \\
& + C \varepsilon \int |\nabla^l u|^2 (|\tau(u)||\nabla u|^2 + |\tau(u)||\nabla^2 u|) \\
& + C \varepsilon \int |\nabla^l u|^2 (|\nabla u|^4 + |\nabla \tau(u)||\nabla u|) \\
& + C \varepsilon \sum_{m=3}^{l+2} \sum_{j_1 + \cdots + j_m = l+2 \atop l \leq j_s \leq l-1} \int |\nabla^l \tau(u)||\nabla^{j_1} u| \cdots |\nabla^{j_m} u| \\
& + C \varepsilon \sum_{m=5}^{l+3} \sum_{j_1 + \cdots + j_m = l+4 \atop l \leq j_s \leq l-1} \int |\nabla^l u| |\nabla^{j_1} u| \cdots |\nabla^{j_m} u| \\
& + C \sum_{m=3}^{l+2} \sum_{j_1 + \cdots + j_m = l+2 \atop l \leq j_s \leq l-1} \sum_{j_1 \leq j_s \leq l-2} \int |\nabla^l u| |\nabla^{j_1} \tau(u)| \cdots |\nabla^{j_m} u|.
\end{align}
We now look at each term of (5.28) separately. Apply Cauchy-Schwarz we have

\begin{equation}
C\varepsilon \int |\nabla^l \tau(u) ||\nabla^l u| |\nabla u|^2 \leq C\varepsilon \|\nabla u\|_{L^\infty}^2 \left( \int |\nabla^l \tau(u)|^2 \right)^{\frac{1}{2}} \left( \int |\nabla^l u|^2 \right)^{\frac{1}{2}} \\
\leq \frac{\varepsilon}{64} \int |\nabla^l \tau(u)|^2 + C\|\nabla u\|_{L^\infty}^6 \int |\nabla^l u|^2.
\end{equation}

Using Cauchy-Schwarz and integration by parts we have

\begin{equation}
C\varepsilon \int |\nabla^{l-1} \tau(u) ||\nabla^l u| |\nabla u| \\
\leq C\varepsilon \|\nabla u\|_{L^\infty} |\nabla u| \left( \int |\nabla^{l-1} \tau(u)|^2 \right)^{\frac{1}{2}} \left( \int |\nabla^l u|^2 \right)^{\frac{1}{2}} \\
\leq \frac{\varepsilon}{64} \int |\nabla^l \tau(u)|^2 + C\|\nabla u\|_{L^\infty}^6 \|\nabla^2 u\|_{L^\infty} \int |\nabla^l u|^2.
\end{equation}

Using Cauchy-Schwarz, integration by parts and (5.17) we have

\begin{equation}
C\varepsilon \int |\nabla^l u| |\tau(u) | |\nabla^{l+1} u| |\nabla u| \\
\leq C\varepsilon \|\tau(u)\|_{L^\infty} \|\nabla u\|_{L^\infty} \left( \int |\nabla^{l+1} \tau(u)|^2 \right)^{\frac{1}{2}} \left( \int |\nabla^l u|^2 \right)^{\frac{1}{2}} \\
\leq \frac{\varepsilon}{64} \int |\nabla^{l+1} u|^2 + C\|\tau(u)\|_{L^\infty}^2 \|\nabla u\|_{L^\infty}^2 \int |\nabla^l u|^2 \\
\leq \frac{\varepsilon}{64} \int |\nabla^l \tau(u)| |\nabla^{l+1} u| + C\|\tau(u)\|_{L^\infty}^2 \|\nabla u\|_{L^\infty}^2 \int |\nabla^l u|^2 \\
+ C\varepsilon \sum_{m=3}^{l+2} \sum_{j_1+\cdots+j_m=l+2} \|\nabla^{j_1+m} u\| |\nabla^l u| \\
\leq \frac{\varepsilon}{64} \int |\nabla^l \tau(u)|^2 + C\|\tau(u)\|_{L^\infty}^2 \|\nabla u\|_{L^\infty}^2 + 1 \int |\nabla^l u|^2 \\
+ C\varepsilon \sum_{m=3}^{l+2} \sum_{j_1+\cdots+j_m=l+2} \int |\nabla^{j_1+m} u| |\nabla^l u|.
Combining (5.28), (5.29), (5.30), (5.31) and (5.32) and using the fact that 
\[ ab \leq \frac{a^p}{p} + \frac{b^q}{q} \text{ if } \frac{1}{p} + \frac{1}{q} = 1 \] we have

\[
\frac{1}{2} \int \|
abla^l u\|_{L^2}^2 \leq -\frac{3\varepsilon}{4} \int |\nabla^l \tau (u)|^2 + C(1 + \|\nabla u\|_{L^6}^6 + \|\nabla^2 u\|_{L^6}^2 + \|\nabla u\|_{L^\infty} \|\nabla^3 u\|_{L^\infty}) \int |\nabla^l u|^2
\]

\[ + C\varepsilon \sum_{m=3, j_1+\cdots+j_m=1+2}^{l+2} \sum_{1 \leq j_s \leq l-1} \int |\nabla^l \tau (u)| \|\nabla j_1 u\| \cdots |\nabla j_m u| \]

\[ + C\varepsilon \sum_{m=5, j_1+\cdots+j_m=1+4}^{l+1} \sum_{1 \leq j_s \leq l-1} \int |\nabla^l u| |\nabla j_1 u| \cdots |\nabla j_m u| \]

\[ + C\varepsilon \sum_{m=3, j_1+\cdots+j_m=1+2}^{l+2} \sum_{1 \leq j_s \leq l-1} \int |\nabla^l \tau (u)| |\nabla j_1 u| \cdots |\nabla j_m u| \]

\[ + C \sum_{m=3, j_1+\cdots+j_m=1+2}^{l+2} \sum_{1 \leq j_s \leq l-1} \int |\nabla^l u| |\nabla j_1 u| \cdots |\nabla j_m u|. \]

To finish the estimate we need to use the interpolation result that appears in Proposition 4.1. Consider 
\[ 3 \leq m \leq l+2, 1 \leq j_s \leq l-1 \text{ and } j_1 + \cdots + j_m = l+2 \] then by Cauchy-Schwarz we have

\[
\int |\nabla^l \tau (u)| |\nabla j_1 u| \cdots |\nabla j_m u| \leq \left( \int |\nabla^l \tau (u)|^2 \right)^{\frac{1}{2}} \left( \int |\nabla j_1 u|^2 \cdots |\nabla j_m u|^2 \right)^{\frac{1}{2}}.
\]

Let \( p_i \in [2, \infty) \) for \( i = 1, \ldots, m \) be such that

\[
\frac{1}{p_1} + \cdots + \frac{1}{p_m} = \frac{1}{2},
\]

by Hölder’s inequality

\[
\left( \int |\nabla j_1 u|^2 \cdots |\nabla j_m u|^2 \right)^{\frac{1}{2}} \leq \|\nabla j_1 u\|_{L^{p_1}} \cdots \|\nabla j_m u\|_{L^{p_m}}.
\]

Since \( l > \left[ \frac{n}{2} \right] + 1 \) for

\[
\frac{j_i - 1}{l - 1} < a_i = \frac{j_i - 1}{l - 1} + \frac{n}{2(l - 1)^2} \left( l - 1 - j_i + \frac{3}{m} \right) < 1
\]

and when \( m > 3 \) or \( m = 3 \) and \( j_1 \geq 2 \)

\[
\frac{1}{2} = \frac{1}{p_i} = \frac{j_i - 1}{n} + \frac{1}{2} - \frac{l - 1}{n} a_i > 0.
\]

Thus (4.5) yields

\[
\|\nabla j_1 u\|_{L^{p_1}} \leq C \|\nabla^l u\|_{L^2}^{\alpha_1} \|\nabla u\|_{L^2}^{1 - \alpha_1} \leq C \|\nabla u\|_{H^{l-1}}.
\]
Combining (5.34), (5.36) and (5.39) we have in the case $m > 3$ that
\begin{equation}
\int |\nabla^l \tau(u)| |\nabla^{j_1} u| \cdot \cdots |\nabla^{j_m} u| \leq c \left( \int |\nabla^l \tau(u)|^2 \right)^{\frac{1}{2}} \|\nabla u\|_{H^{l-1}}^m.
\end{equation}
In the case when $m = 3$, $j_1 \geq j_2 \geq j_3$, and $j_3 = 1$ we have $j_1 + j_2 = l + 1$ and
\begin{equation}
\left( \int |\nabla^{j_1} u|^2 |\nabla^{j_2} u|^2 |\nabla u|^2 \right)^{\frac{1}{2}} \leq \|\nabla u\|_{L^\infty} \left( \int |\nabla^{j_1} u|^2 |\nabla^{j_2} u|^2 \right)^{\frac{1}{2}}.
\end{equation}
If $j_2 = 1$ then (5.34) becomes
\begin{equation}
\int |\nabla^l \tau(u)| |\nabla^l u| |\nabla u|^2 \leq c \|\nabla u\|_{L^\infty}^2 \left( \int |\nabla^l \tau(u)|^2 \right)^{\frac{1}{2}} \left( \int |\nabla^l u|^2 \right)^{\frac{1}{2}}.
\end{equation}
If $j_2 > 1$ then for $i = 1, 2$ let $l_0 = \max \{ \left\lfloor \frac{j_i}{2} \right\rfloor + 4, l \}$. If
\begin{equation}
\frac{j_i - 1}{l_0 - 1} \leq \frac{1}{n} \sum_{a_i = 1}^{\left\lfloor \frac{j_i}{2} \right\rfloor + 4} \left( \frac{j_i - 1}{(l_0 - 1)(l - j_i)} \right) < 1
\end{equation}
and
\begin{equation}
\frac{1}{2} \geq \frac{1}{p_i} = \frac{j_i - 1}{n} + \frac{l_0 - 1}{n} - a_i > 0.
\end{equation}
Hölder's inequality and Proposition 4.1 yield
\begin{equation}
\left( \int |\nabla^{j_1} u|^2 |\nabla^{j_2} u|^2 \right)^{\frac{1}{2}} \leq \|\nabla^{j_1} u\|_{L^{p_1}} \|\nabla^{j_2} u\|_{L^{p_2}}
\leq C \|\nabla^0 u\|^\frac{a_1}{2} \|\nabla u\|^{1-a_1}_{L^2} \|\nabla^0 u\|^\frac{a_2}{2} \|\nabla u\|^{1-a_2}_{L^2}
\leq C \|\nabla u\|_{H^{l_0-1}}^2.
\end{equation}
Thus in this case (5.34) becomes combining (5.41) and (5.45)
\begin{equation}
\int |\nabla^l \tau(u)| |\nabla^{j_1} u| \cdots |\nabla u| \leq c \|\nabla u\|_{L^\infty}^2 \|\nabla u\|_{H^{l_0-1}}^2 \left( \int |\nabla^l \tau(u)|^2 \right)^{\frac{1}{2}}.
\end{equation}
Combining (5.40), (5.42) and (5.46) we can estimate the third term on the right hand side of (5.33)
\begin{equation}
\sum_{m=3}^{l+2} \sum_{1 \leq j_1 \leq \cdots \leq j_m \leq l+2} \int |\nabla^l \tau(u)| |\nabla^{j_1} u| \cdots |\nabla^{j_m} u| \leq C \left( \int |\nabla^l \tau(u)|^2 \right)^{\frac{1}{2}} \left( \sum_{m=1}^{l+2} \|\nabla u\|_{H^{l_1-1}}^m + \|\nabla u\|_{H^{l_0-1}}^2 \right).
\end{equation}
To estimate the fourth term in (5.33) consider $5 \leq m \leq l + 3$, $1 \leq j_s \leq l - 1$ and $j_1 + \cdots + j_m = l + 4$ then by Cauchy-Schwarz we have
\begin{equation}
\int |\nabla^{j_1} u| |\nabla^{j_2} u| \cdots |\nabla^{j_m} u| \leq \left( \int |\nabla^{j_1} u|^2 \right)^{\frac{1}{2}} \left( \int |\nabla^{j_2} u|^2 \cdots |\nabla^{j_m} u|^2 \right)^{\frac{1}{2}}.
\end{equation}
Let $2 \leq p_i \leq \infty$ for $i = 1, \ldots, m$ be such that
\begin{equation}
\frac{1}{p_1} + \cdots + \frac{1}{p_m} = \frac{1}{2}
\end{equation}
by Hölder’s inequality (5.48) becomes

\[
\int |\nabla^l u| |\nabla^{j_1} u| \cdots |\nabla^{j_m} u| \leq \left( \int |\nabla^l u|^2 \right)^{\frac{1}{2}} \|\nabla^{j_1} u\|_{L^{p_1}} \cdots \|\nabla^{j_m} u\|_{L^{p_m}}
\]

since \( l > \left[ \frac{n}{2} \right] + 1 \) for

\[
\frac{j_i - 1}{l - 1} \leq a_i = \frac{j_i - 1}{l - 1} + \frac{n}{2(l - 1)^2} \left( l - 1 - j_i + \frac{5}{m} \right) < 1
\]

and when \( m > 5 \) or \( m = 5 \) and \( j_i \geq 2 \)

\[
\frac{1}{2} \geq \frac{1}{p_i} = \frac{j_i - 1}{n} + \frac{1}{2} - \frac{l - 1}{n} a_i > 0.
\]

Thus (4.5) yields

\[
\int |\nabla^l u|^2 |\nabla^{j_1} u| \cdots |\nabla^{j_m} u| \leq C \left( \int |\nabla^l u|^2 \right)^{\frac{1}{2}} \|\nabla u\|_{H^{j_i - 1}}^{m-1}.
\]

If \( m = 5 \), \( j_1 \geq j_2 \geq \cdots \geq j_5 \geq 1 \), and \( j_5 = 1 \) then \( j_1 + j_2 + j_3 + j_4 = l + 3 \), by Cauchy-Schwarz and Hölder’s inequality

\[
\int |\nabla^l u| |\nabla^{j_1} u| \cdots |\nabla^{j_m} u| |\nabla u|
\]

\[
\leq \|\nabla u\|_{L^\infty} \left( \int |\nabla^l u|^2 \right)^{\frac{1}{2}} \left( \int |\nabla^{j_1} u|^2 \cdots |\nabla^{j_m} u|^2 \right)^{\frac{1}{2}}
\]

\[
\leq \|\nabla u\|_{L^\infty} \left( \int |\nabla^l u|^2 \right)^{\frac{1}{2}} \|\nabla^{j_1} u\|_{L^{p_1}} \cdots \|\nabla^{j_4} u\|_{L^{p_4}}
\]

with \( \frac{1}{p_1} + \frac{1}{p_2} + \frac{1}{p_3} + \frac{1}{p_4} = \frac{1}{2} \). For

\[
\frac{j_i - 1}{l - 1} < a_i = \frac{j_i - 1}{l - 1} + \frac{n}{2(l - 1)^2} (l - j_i) < 1
\]

if \( j_4 > 1 \) we have

\[
\frac{1}{2} \geq \frac{1}{p_i} = \frac{j_i - 1}{n} + \frac{1}{2} - \frac{l - 1}{n} a_i > 0
\]

and (5.4) becomes by Proposition 4.1

\[
\int |\nabla^l u| |\nabla^{j_1} u| \cdots |\nabla^{j_4} u| |\nabla u| \leq C \|\nabla u\|_{L^\infty} \left( \int |\nabla^l u|^2 \right)^{\frac{1}{2}} \|\nabla u\|_{H^{j_i - 1}}^{m-1}
\]

If \( j_4 = 1 \) and \( j_3 > 1 \) a similar argument yields

\[
\int |\nabla^l u| |\nabla^{j_1} u| |\nabla^{j_3} u| |\nabla u|^2 \leq C \|\nabla u\|_{L^\infty}^2 \left( \int |\nabla^l u|^2 \right)^{\frac{1}{2}} \|\nabla u\|_{H^{j_i - 1}}^{3}.
\]

If \( j_3 = 1 \) then \( j_1 + j_2 = l + 1 \) since \( j_1 \leq l - 1 \) then \( j_2 > 1 \) and we have

\[
\int |\nabla^l u| |\nabla^{j_1} u| |\nabla^{j_2} u| |\nabla u|^3 \leq C \|\nabla u\|_{L^\infty}^3 \left( \int |\nabla^l u|^2 \right)^{\frac{1}{2}} \|\nabla u\|_{H^{j_i - 1}}^{2}.
\]
Combining (5.53), (5.57), (5.58) and (5.59) we can estimate the fourth term on the right hand side of (5.33) as follows

\[
\sum_{m=3}^{l+3} \sum_{j_1+\ldots+j_m=l+4} \int |\nabla^l u| |\nabla^{j_1} u| \cdots |\nabla^{j_m} u| \\
\leq C \left( \int |\nabla^l u|^2 \right)^{\frac{1}{2}} (1 + \|\nabla u\|_{L^\infty}^2) \sum_{m=2}^{l+3} \|\nabla u\|_{H^{l+1-m}}^m \\
\leq C (1 + \|\nabla u\|_{L^\infty}^3) \sum_{m=3}^{l+4} \|\nabla u\|_{H^{l-m}}^m.
\]

To estimate the fifth term in (5.33) consider \(3 \leq m \leq l+2, j_1 + \ldots + j_m = l+2, j_1 \leq l-2, 1 \leq j_s \leq l-1\) if \(s \geq 2\). Cauchy-Schwarz and Hölder’s inequality ensure that for \(\frac{1}{p_1} + \ldots + \frac{1}{p_m} = \frac{1}{2}\)

\[
\int |\nabla^l u| |\nabla^{j_1} \tau(u)| |\nabla^{j_2} u| \cdots |\nabla^{j_m} u| \\
\leq \left( \int |\nabla^l u|^2 \right)^{\frac{1}{2}} \|\nabla^{j_1} \tau(u)\|_{L^{p_1}} \cdots \|\nabla^{j_m} u\|_{L^{p_m}}.
\]

For \(l_0 = \max \{ \left\lfloor \frac{n}{2} \right\rfloor + 4, \frac{l_0}{3} \} > 1\) for \(i \geq 2\)

\[
\frac{j_i - 1}{l_0 - 1} < a_i = \frac{j_i - 1}{l_0 - 1} + \frac{n}{2(l_0 - 1)(l_0 - 1)} \left( l - 1 - j_i + \frac{3}{m} \right) < 1
\]

and

\[
\frac{j_1}{l_0 - 1} < a_1 = \frac{j_1}{l_0 - 1} + \frac{n}{2(l_0 - 1)(l_0 - 1)} \left( l - 1 - j_1 + \frac{3}{m} \right) < 1
\]

when \(m > 3\) or \(m = 3\) and \(j_i \geq 2\) for \(i \geq 2\)

\[
\frac{1}{2} \geq \frac{1}{p_i} = \frac{j_i - 1}{n} + \frac{l_0 - 1}{n} a_i > 0
\]

and \(m > 3\) or \(m = 3\) and \(j_1 \geq 2\)

\[
\frac{1}{2} \geq \frac{1}{p_1} = \frac{j_1}{n} + \frac{l_0 - 1}{n} a_1 > 0.
\]

In these cases (5.61) can be estimated by (4.5) as follows

\[
\int |\nabla^l u| |\nabla^{j_1} \tau(u)| |\nabla^{j_2} u| \cdots |\nabla^{j_m} u| \\
\leq \left( \int |\nabla^l u|^2 \right)^{\frac{1}{2}} \|\nabla^{l-1} \tau(u)\|_{L^{p_1}}^{a_1} \|\tau(u)\|_{L^2}^{1-a_1} \|\nabla u\|_{H^{l-1-m}}^{m-1}.
\]

If \(m = 3\) and \(j_1 \leq 1\) then \(j_2 \geq 2\) and \(j_3 \geq 2\). Cauchy-Schwarz and Hölder’s inequality yield for \(\frac{1}{p_2} + \frac{1}{p_3} = \frac{1}{2}\)

\[
\int |\nabla^l u| |\tau(u)| |\nabla^{j_2} u| |\nabla^{j_3} u| \\
\leq \|\tau(u)\|_{L^{\infty}} \left( \int |\nabla^l u|^2 \right)^{\frac{1}{2}} \|\nabla^{j_2} u\|_{L^{p_2}} \|\nabla^{j_3} u\|_{L^{p_3}}.
\]
and

\begin{equation}
1/2 \geq \frac{1}{p_i} = \frac{j_i - 1}{n} + \frac{1}{2} - \frac{l - 1}{n} a_i > 0,
\end{equation}

Proposition 4.1 ensures that

\begin{equation}
\int |\nabla^j u| |\tau(u)| |\nabla^{j_2} u| |\nabla^{j_3} u| \leq C \|\tau(u)\|_{L^\infty} \left( \int |\nabla^l u|^2 \right)^{1/2} \|\nabla u\|_{H^{l-1}}^2.
\end{equation}

Similarly

\begin{equation}
\int |\nabla^j u| |\nabla^{j_2} u| |\nabla^{j_3} u| \leq C \|
abla \tau(u)\|_{L^\infty} \left( \int |\nabla^l u|^2 \right)^{1/2} \|\nabla u\|_{H^{l-1}}^2.
\end{equation}

If \( m = 3, j_1 \geq 2 \) and \( j_2 = 1, j_3 > 1 \) we have by Cauchy-Schwarz and Hölder’s inequality for \( \frac{1}{p_1} + \frac{1}{p_2} = \frac{3}{2} \)

\begin{equation}
\int |\nabla^l u| |\nabla^{j_1} \tau(u)| |\nabla u| |\nabla^{j_3} u|
\leq C \|\nabla u\|_{L^\infty} \left( \int |\nabla^l u|^2 \right)^{1/2} \|
abla^{j_1} \tau(u)\|_{L^{p_1}} \|
abla^{j_3} u\|_{L^{p_2}}.
\end{equation}

For

\begin{equation}
a_1 = \frac{j_1}{l - 1} + \frac{n}{2(l - 1)^2} (l - j_1) < 1 \text{ and } \frac{1}{2} \geq \frac{1}{p_1} = \frac{j_1}{n} + \frac{1}{2} - \frac{l - 1}{n} a_1 > 0
\end{equation}

and

\begin{equation}
a_3 = \frac{j_3 - 1}{l - 1} + \frac{n}{2(l - 1)^2} (l - j_3) < 1 \text{ and } \frac{1}{2} \geq \frac{1}{p_3} = \frac{j_3 - 1}{n} + \frac{1}{2} - \frac{l - 1}{n} a_3 > 0.
\end{equation}

Proposition 4.1 ensures

\begin{equation}
\int |\nabla^l u| |\nabla^{j_1} \tau(u)| |\nabla u| |\nabla^{j_3} u|
\leq C \|\nabla u\|_{L^\infty} \left( \int |\nabla^l u|^2 \right)^{1/2} \|
abla^{l-1} \tau(u)\|_{L^2}^{a_1} \|
abla \tau(u)\|_{L^2}^{1-a_1} \|\nabla u\|_{H^{l-1}}.
\end{equation}

In the case \( j_1 = l, j_2 = j_3 = 1 \) see (5.29).

Combining (5.66), (5.69), (5.70) and (5.74) we estimate the \( 5^{th} \) term of (5.33) as follows

\begin{equation}
\sum_{m=3}^{l+2} \sum_{ \begin{aligned} j_1 + \cdots + j_m = l+2 \\ 1 \leq j_1, \ldots, j_m \leq l \end{aligned} } \int |\nabla^l u| |\nabla^{j_1} \tau(u)| \cdots |\nabla^{j_m} u|
\leq C \left( \int |\nabla^l u|^2 \right)^{1/2} \left( 1 + \|\nabla u\|_{L^\infty} \right) \sum_{m=1}^{l+1} \|\tau(u)\|_{L^2} \|\nabla u\|_{H^{l-1}} \|\nabla^{l-1} \tau(u)\|_{L^2}
\end{equation}

\begin{equation}
+ C \left( \int |\nabla^l u|^2 \right)^{1/2} \left( 1 + \|\nabla u\|_{L^\infty} \right) \sum_{m=1}^{l+1} \|\tau(u)\|_{L^2} \|\nabla u\|_{H^{l_0-1}} \|\nabla^{l_0-1} \tau(u)\|_{L^2}
\end{equation}

\begin{equation}
+ C(\|\tau(u)\|_{L^\infty} + \|\nabla \tau(u)\|_{L^\infty}) \left( \int |\nabla^l u|^2 \right)^{1/2} \|\nabla u\|_{H^{l-1}}^2.
\end{equation}

Here we have used the fact that for \( a \in (0, 1) \leq r^a s^{1-a} \leq ar + (1 - a)s.\)
Finally we look at the last term of (5.33). Let $3 \leq m \leq l+2$, $j_1 + \cdots + j_m = l+2$. Applying the same argument as the one used to obtain (5.47) we conclude that

$$\sum_{m=3}^{l+2} \sum_{j_1 + \cdots + j_l = l+2} \int |\nabla^l u| |\nabla^{j_1} u| \cdots |\nabla^{j_m} u|$$

$$\leq C \left(1 + \|\nabla u\|_{L^\infty}^2 \right) \left(\int |\nabla^l u|^2 \right)^\frac{1}{2} \left(\sum_{m=1}^{l+2} \|\nabla u\|_{H^{m-1}}^m + \|\nabla u\|_{H^{l_0-1}}^2 \right).$$

Combining (5.33), (5.47), (5.60), (5.75) and (5.76), using (4.78), (4.80), (4.82) and the fact that $l > \left[\frac{n}{2}\right] + 1$ as well as $\varepsilon \in (0,1)$ and the fact that for $a \in (0,1) \leq r^{a}s^{1-a} \leq ar + (1-a)s$ we obtain for $l_0 = l \geq \left[\frac{n}{2}\right] + 4$

$$\frac{1}{2} \frac{d}{dt} \|\nabla^l u\|_{L^2}^2 \leq \frac{-3\varepsilon}{4} \int |\nabla^l \tau(u)|^2 + C \left(1 + \|\nabla u\|_{L^\infty}^6 + \|\nabla^2 u\|_{L^\infty}^3 \right) |\nabla^l u|^2_{L^2}$$

$$+ C\varepsilon \left(\int |\nabla^l \tau(u)|^2 \right)^\frac{1}{2} \left(1 + \|\nabla u\|_{L^\infty}^2 \right) \sum_{m=1}^{l+2} \|\nabla u\|_{H^{m-1}}^m$$

$$+ C\varepsilon \left(\int |\nabla^l u|^2 \right)^\frac{1}{2} \left(1 + \|\nabla u\|_{L^\infty} \right) \left(\|\nabla^{l-1} \tau(u)\|_{L^2} + \|\tau(u)\|_{L^2} \right) \sum_{m=1}^{l+1} \|\nabla u\|_{H^{m-1}}^m$$

$$+ C(\|\tau(u)\|_{L^\infty} + \|\nabla \tau(u)\|_{L^\infty}) \left(\int |\nabla^l u|^2 \right)^\frac{1}{2} \|\nabla u\|_{H^{m-1}}^m$$

$$+ C(1 + \|\nabla u\|_{L^\infty}^2) \left(\int |\nabla^l u|^2 \right)^\frac{1}{2} \sum_{m=1}^{l+2} \|\nabla u\|_{H^{m-1}}^m$$

$$\leq \frac{-3\varepsilon}{4} \int |\nabla^l \tau(u)|^2 + C \left(\|\nabla u\|_{L^\infty}^6 + 12 \right) \sum_{m=2}^{l+2} \|\nabla u\|_{H^{m-1}}^m$$

$$+ C\varepsilon \|\nabla^l u\|_{L^2} \left(1 + \|\nabla u\|_{L^\infty}^2 \right) \sum_{m=1}^{l+2} \|\nabla u\|_{H^{m-1}}^m \|\nabla^{l-1} \tau(u)\|_{L^2}$$

$$\leq \frac{-3\varepsilon}{4} \int |\nabla^l \tau(u)|^2 + \frac{\varepsilon}{64} \|\nabla^{l-1} \tau(u)\|_{L^2}^2$$

$$+ C \left(1 + \|\nabla u\|_{L^\infty}^{3n+12} \right) \sum_{m=2}^{2l+4} \|\nabla u\|_{H^{m-1}}^m.$$

Using the same trick as in (5.30) we obtain from (5.77) for $l \geq \left[\frac{n}{2}\right] + 4$

$$\frac{d}{dt} \|\nabla^l u\|_{L^2}^2 \leq -\frac{\varepsilon}{2} \int |\nabla^l \tau(u)|^2 + C \left(1 + \|\nabla u\|_{L^\infty}^{3n+12} \right) \sum_{m=2}^{2l+4} \|\nabla u\|_{H^{m-1}}^m \leq C \left(1 + \|\nabla u\|_{L^\infty}^{3n+12} \right) \|\nabla u\|_{H^{m-1}}^2 \left(1 + \|\nabla u\|_{H^{m-1}}^{2l+2} \right)$
Thus (5.78) and (5.79) conclude the proof of Lemma 5.5.

(5.79) \[ \frac{1}{2} \frac{d}{dt} \| \nabla^l u \|^2_{L^2} \]
\[ \leq -\frac{3\varepsilon}{4} \int |\nabla^l \tau(u)|^2 + \frac{\varepsilon}{64} \| \nabla^{l-1} \tau(u) \|^2_{L^2} + C \left( 1 + \| \nabla u \|^3_{H^{\frac{3}{2}} + 4} \right) \sum_{m=2}^{2l+4} \| \nabla u \|^m_{H^{l-1}} \]
\[ + C \varepsilon \| \nabla^l u \|_{L^2} \left( 1 + \| \nabla u \|^2_{H^{\frac{3}{2}} + 4} \right) \sum_{m=1}^{l+2} \| \nabla u \|^m_{H^{l-1}} \| \nabla^{3} \tau(u) \|_{L^2} \]
\[ \leq C \left( 1 + \| \nabla u \|^3_{H^{\frac{3}{2}} + 4} \right) \| \nabla u \|^2_{H^{l-1}} (1 + \| \nabla u \|_{H^{l-1}}^{2l+2}) \]

Thus (5.78) and (5.79) conclude the proof of Lemma 5.5. \( \square \)

Since our ultimate goal is to estimate \( \frac{d}{dt} \| \nabla u \|^2_{H^{l-1}} \) for \( l \geq 1 \), we still need to analyze \( \frac{d}{dt} \| \nabla^l u \|^2_{L^2} \) for \( 1 \leq l \leq \left\lfloor \frac{n}{2} \right\rfloor + 1 \).

**Lemma 5.6.** Let \( u \in C([0, T], H^{\left\lfloor \frac{3n}{2} \right\rfloor + 4}(\mathbb{R}^n, N)) \) be a solution of (5.2). Let \( 1 \leq l \leq \left\lfloor \frac{n}{2} \right\rfloor + 1 \) then if \( s_0 = \left\lfloor \frac{n}{2} \right\rfloor + 2 \) we have

\[ \frac{d}{dt} \| \nabla^l u \|^2_{L^2} \leq c \| \nabla u \|^3_{H^{\tau_0}} \left( 1 + \| \nabla u \|^2_{H^{\tau_0}} \right) \]

where \( M_l = 3n + 2l + 12 \).

**Proof.** Note that (5.17) and the Sobolev embedding theorem yields

\[ \frac{d}{dt} \| \nabla u \|^2_{L^2} \leq C \| \nabla u \|^4_{H^{\left\lfloor \frac{n}{2} \right\rfloor + 1}} \left( 1 + \| \nabla u \|^2_{H^{\left\lfloor \frac{n}{2} \right\rfloor + 2}} \right) \]

Note that for \( l \geq 2 \) computation (5.33) remains valid. In fact we only used \( l > \left\lfloor \frac{n}{2} \right\rfloor + 1 \) when we started to interpolate as in Proposition 4.1. Let \( s_0 = \left\lfloor \frac{n}{2} \right\rfloor + 2 \). Consider \( 3 \leq m \leq l + 2 \) \( 1 \leq j_s \leq l - 1 \) and \( j_1 + \cdots + j_m = l + 2 \) then by Cauchy-Schwarz, Hölder’s inequality applied with \( \frac{1}{p_1} + \cdots + \frac{1}{p_m} = \frac{1}{2} \) where

\[ \frac{1}{p_i} = \frac{j_i - 1}{n} + \frac{1}{2} - \frac{s_0}{n} a_i \]

and

\[ \frac{j_i - 1}{s_0} \leq a_i = \frac{j_i - 1}{s_0} + \frac{n}{2(l-1)s_0} \left( l - 1 - j_i + \frac{3}{m} \right) < 1 \]

and (4.5) in the case \( m > 3 \) or \( m = 3 \) and \( j_i \geq 2 \) we obtain as in (5.40)

\[ \int |\nabla^l \tau(u)||\nabla^{j_1} u| \cdots |\nabla^{j_m} u| \leq C \left( \int |\nabla^l \tau(u)|^2 \right)^{\frac{1}{2}} \| \nabla u \|^m_{H^{\tau_0}}. \]

In the case \( m = 3 \) we proceed as in the proof of (5.46) (where \( s_0 \) now plays the role of \( l_0 \)) and obtain

\[ \int |\nabla^l \tau(u)|^2 |\nabla^{j_1} u| \cdots |\nabla^{j_m} u| \leq C \| \nabla u \|_{L^\infty} \left( \int |\nabla^l \tau(u)|^2 \right)^{\frac{1}{2}} \| \nabla u \|^2_{H^{\tau_0}}. \]
Thus for $2 \leq l \leq \left[ \frac{n}{2} \right] + 1$ (5.47) becomes

\begin{equation}
(5.86) \sum_{m=3}^{l+2} \sum_{\substack{j_1+\ldots+j_m=l+2 \leq 1 \leq j_1 \leq l-1}} \int |\nabla^{j_1} \tau(u)| |\nabla^{j_1} u| \ldots |\nabla^{j_m} u| \leq C \left( \int |\nabla^l \tau(u)|^2 \right)^{\frac{1}{2}} (1 + \|u\|^{3}_{L^{\infty}}) \sum_{m=1}^{l+2} \|u\|_{H^{s_0}}^m.
\end{equation}

The same type of argument as the one used to prove (5.60), (5.75) and (5.76) yields

\begin{equation}
(5.87) \sum_{m=3}^{l+3} \sum_{\substack{j_1+\ldots+j_m=l+4 \leq 1 \leq j_1 \leq l-1 \leq 1 \leq j_2 \leq l-2 \leq \ldots \leq j_m \leq l}} \int |\nabla^{j_1} u| |\nabla^{j_1} \tau(u)| \ldots |\nabla^{j_m} u| \leq C \left( \int |\nabla^l u|^2 \right)^{\frac{1}{2}} (1 + \|u\|_{L^{\infty}}^{3}) \sum_{m=1}^{l+1} \|u\|_{H^{s_0}}^m \|\nabla^m \tau(u)\|_{L^2} \|\tau(u)\|_{L^{1-a_1}}^{1-a_1} + C(\|u\|_{L^{\infty}}^{3} + \|\nabla \tau(u)\|_{L^{\infty}}) \left( \int |\nabla^l u|^2 \right)^{\frac{1}{2}} \|u\|_{H^{s_0}}^2.
\end{equation}

\begin{equation}
(5.88) \sum_{m=4}^{l+2} \sum_{\substack{j_1+\ldots+j_m=l+2 \leq 1 \leq j_1 \leq l-1 \leq j_2 \leq l-2 \leq \ldots \leq j_m \leq l}} \int |\nabla^{j_1} u| |\nabla^{j_1} \tau(u)| \ldots |\nabla^{j_m} u| \leq C \left( \int |\nabla^l u|^2 \right)^{\frac{1}{2}} (1 + \|u\|_{L^{\infty}}^{3}) \sum_{m=2}^{l+2} \|u\|_{H^{s_0+1}}^m \|\nabla^m \tau(u)\|_{L^2} + C(\|u\|_{L^{\infty}} + \|\nabla \tau(u)\|_{L^{\infty}}) \left( \int |\nabla^l u|^2 \right)^{\frac{1}{2}} \|u\|_{H^{s_0}}.
\end{equation}

\begin{equation}
(5.89) \sum_{m=4}^{l+2} \sum_{\substack{j_1+\ldots+j_m=l+2 \leq 1 \leq j_1 \leq l-1 \leq j_2 \leq l-2 \leq \ldots \leq j_m \leq l}} \int |\nabla^{j_1} u|^2 |\nabla^{j_1} u| \ldots |\nabla^{j_m} u| \leq C(1 + \|u\|_{L^{\infty}}^{3}) \left( \int |\nabla^l u|^2 \right)^{\frac{1}{2}} \sum_{m=1}^{l+2} \|u\|_{H^{s_0}}^m.
\end{equation}
\( \frac{1}{2} \frac{d}{dt} \| \nabla' u(t) \|^2_{L^2} \leq -\frac{\varepsilon}{2} \int |\nabla' \tau(u(t))|^2 + C (1 + \| \nabla u(t) \|^6_{L^\infty} + \| \tau(u(t)) \|^3_{L^\infty}) \int |\nabla' u(t)|^2 \leq \frac{C}{2} (1 + \| \nabla u(t) \|^2_{L^\infty}) \sum_{m=2}^{2^l+4} \| \nabla u(t) \|^m_{H^{s_0}} + C (1 + \| \nabla u(t) \|^2_{L^\infty} +\| \tau(u(t)) \|^2_{L^\infty} + \| \nabla \tau(u(t)) \|^2_{L^\infty}) \sum_{m=2}^{t+3} \| \nabla u(t) \|^m_{H^{s_0+1}} \leq C \| \nabla u(t) \|^2_{H^{s_0}} (1 + \| \nabla u(t) \|^3_{H^{s_0+2}}) \)

\[ (5.90) \]

**Corollary 5.7** (Uniform energy estimate). Let \( u_c(t) \in \mathbb{H}^{s+1}(\mathbb{R}^n, N) \) with \( s \in \mathbb{N} \) and \( s \geq \left[ \frac{n}{2} \right] + 4 \) be a solution of (5.2). There exists \( T_0 = T_0(\| \nabla u_0 \|_{\mathcal{H}^s}) \) such that for \( 0 \leq t \leq T_0 \)

\[ \| \nabla u_c(t) \|_{\mathcal{H}^s} \leq 3 \| \nabla u_0 \|_{\mathcal{H}^s}. \]

**Proof.** Let \( E(t) = \| \nabla u(t) \|^2_{H^s} \). Then (5.13), (5.14) and (5.80) imply for \( \left[ \frac{n}{2} \right] + 4 \leq s \)

\[ \frac{d}{dt} E \leq C_0 E(1 + E^{2n+s+8}), \]

which leads, after integrating from 0 to \( t \), to

\[ \ln \frac{E(t)}{E(0)} - \frac{1}{2n+s+8} \ln \frac{E(t)^{2n+s+8}+1}{E(0)^{2n+s+8}+1} \leq C_0 t \]

which implies

\[ \frac{E(t)^{2n+s+8}}{1 + E(t)^{2n+s+8}} \leq e^{C_0 t(2n+s+8)} \frac{E(0)^{2n+s+8}}{1 + E(0)^{2n+s+8}} \leq (1 + 4C_0 t(2n+s+8)) \frac{E(0)^{2n+s+8}}{1 + E(0)^{2n+s+8}}, \]

for \( t \) such that \( C_0 t(2n+s+8) < \frac{1}{8} \) for example. A simple computation yields

\[ E(t)^{2n+s+8} \leq (1 + 4C_0 t(2n+s+8))E(0)^{2n+s+8} + 4C_0 t(2n+s+8)E(0)^{2n+s+8} E(t)^{2n+s+8}. \]

For \( t \) such that \( 4C_0 t(2n+s+8)E(0)^{2n+s+8} < \frac{1}{2} \) we have

\[ E(t)^{2n+s+8} \leq 2(1 + 4C_0 t(2n+s+8))E(0)^{2n+s+8}. \]

Thus for \( s \geq \left[ \frac{n}{2} \right] + 4 \), (5.96) shows that if

\[ 0 < t \leq T_0 = \min\left\{ \frac{1}{8SC_0(2n+s+8)}, \frac{1}{8SC_0(2n+s+8)} \right\} \]

then

\[ \| \nabla u_c(t) \|_{\mathcal{H}^s} \leq 3 \| \nabla u_0 \|_{\mathcal{H}^s}. \]
Lemma 5.8. Let \( u_c(t) \in H^{s+1}(\mathbb{R}^n, N) \) with \( s \in \mathbb{N} \) and \( s \geq \left[ \frac{n}{2} \right] + 4 \) be a solution of (5.1). Let \( v = v_c = u \circ u_c \). For \( T_0 = T_0(\| \nabla u_0 \|_{L^s}) \) as in (5.97) we have

\[
\sup_{0 < t \leq T_0} \| v(t) - v_0 \|_{L^2} \leq C \| \nabla u_0 \|_{H^s} \left( 1 + \| \nabla u_0 \|_{H^s}^{\frac{3}{2} + 6} \right) T_0.
\]

Proof. Our goal is to study how \( \| v(t) - v_0 \|_{L^2} \) evolves. Using (3.1) and (3.2) we have

\[
\frac{1}{2} \frac{d}{dt} \int | v - v_0 |^2 = \int \langle \partial_t v, v - v_0 \rangle \leq \| v - v_0 \|_{L^2} \left( \int (\partial_t v)^2 \right)^{\frac{1}{2}} \leq C \left( \| \Delta^2 v \|_{L^2} + \| \partial^2 v \|_{L^2} + \| \partial \|_{L^2} \| \partial v \|_{L^\infty} \right.
\]

\[
+ \| \partial^2 v \|_{L^2} \| \partial^2 v \|_{L^\infty} + \| \partial v \|_{L^2} \| \partial v \|_{L^\infty} \| v - v_0 \|_{L^2}.
\]

Recall that

\[
| \partial^2 v | \leq | \nabla^2 u | + C | \nabla u |^2 \quad \text{and} \quad | \partial v | = | \nabla u |.
\]

Moreover by (4.54) we have

\[
| \partial^4 v | \leq C | \nabla^4 u | + C \sum_{l=2}^4 \sum_{j_1 + \cdots + j_l = 4} | \nabla^{j_1} u | \cdots | \nabla^{j_l} u | \leq C | \nabla^4 u | + C | \nabla^2 u |^2 + C | \nabla^3 u |^2 + C | \nabla^3 u | | \nabla u |.
\]

Using (4.72), (4.73) and (5.102), (5.100) yields

\[
\frac{d}{dt} \int | v - v_0 |^2 \leq C \left\{ \| \nabla^4 u \|_{L^2} + \| \nabla^2 u \|_{L^\infty} \| \nabla^2 u \|_{L^2} \right.
\]

\[
+ \| \nabla u \|_{L^\infty} \| \nabla u \|_{L^2} + \| \nabla u \|_{L^\infty} \| \nabla^3 u \|_{L^2} + \| \nabla^3 u \|_{L^2}
\]

\[
+ \| \nabla u \|_{L^2} \| \nabla u \|_{L^\infty} \| \nabla^2 u \|_{L^2} \| \nabla u \|_{L^2} \} \| v - v_0 \|_{L^2} \leq C \| \nabla u \|_{H^s} \left( 1 + \| \nabla u_0 \|_{H^s}^{\frac{3}{2} + 6} \right) \| v - v_0 \|_{L^2}.
\]

For \( t \in [0, T_0] \) as in (5.97), (5.103) combined with (5.91) yields

\[
\frac{d}{dt} \| v - v_0 \|_{L^2} \leq C \| \nabla u_0 \|_{H^s} \left( 1 + \| \nabla u_0 \|_{H^s}^{\frac{3}{2} + 6} \right) \| v - v_0 \|_{L^2}.
\]

Integrating from 0 to \( T_0 \) (as defined in (5.97)) we deduce from (5.104) that

\[
\| v(t) - v_0 \|_{L^2} \leq C T_0 \| \nabla u_0 \|_{H^s} \left( 1 + \| \nabla u_0 \|_{H^s}^{\frac{3}{2} + 6} \right).
\]

\[
\square
\]
Theorem 5.9. Let \( s \geq \left[ \frac{3}{2} \right] + 4 \). Given \( u_0 \in H^{s+1}(\mathbb{R}^n, N) \) there exists \( T_0 = T_0(\|\nabla u_0\|_{H^s}, N) > 0 \) and a solution \( u_\varepsilon \in C([0, T_0], H^{s+1}(\mathbb{R}^n, N)) \) of (5.2). Furthermore

\[
\sup_{0 \leq t \leq T_0} \|\nabla u_\varepsilon(t)\|_{H^s} \leq 3\|\nabla u_0\|_{H^s}.
\]

Proof. Lemma 2.7, Lemma 4.7, Theorem 3.1 and Lemma 4.8 imply that there exist \( T_\varepsilon = T(\varepsilon, \|\nabla u_0\|_{H^s}, \|u_0 - \gamma\|_{L^2}, N) \) for some \( \gamma \in \mathbb{R}^p \), and a solution of (5.2) given by \( u_\varepsilon \in C([0, T_\varepsilon], H^{s+1}(\mathbb{R}^n, N)) \). Either \( T_\varepsilon \geq T_0 \) as defined in (5.97) and we are done or \( T_\varepsilon < T_0 \). Using the fact that

\[
\|v(T_\varepsilon) - v_0\|_{L^2} \leq C T_0 \|\nabla u_0\|_{H^{\left[\frac{3}{2}\right]}+4} \left(1 + \|\nabla u_0\|_{H^{\left[\frac{3}{2}\right]}+4}\right)
\]

the same argument as above ensures that there exists \( T'_\varepsilon = T(\varepsilon, \|\nabla u_0\|_{H^s}) \) and \( u_\varepsilon \in C([T_\varepsilon, T_\varepsilon + T'_\varepsilon], H^s(\mathbb{R}^n, N)) \) a solution of (5.2). The uniqueness statement in Theorem 3.1 ensures that we can extend \( u_\varepsilon \in C([0, T_\varepsilon + T'_\varepsilon], H^s(\mathbb{R}^n, N)) \) to be a solution of (5.2).

After a finite number of steps (namely \( l \) where \( T_\varepsilon + l T'_\varepsilon \leq T_0 < T_\varepsilon + (l+1) T'_\varepsilon \)) we manage to extend \( \forall \varepsilon \in (0, 1) \), \( u_\varepsilon \) to be a solution of (5.2) in \( C([0, T_0], H^s(\mathbb{R}^n, N)) \). Note that (5.106) is simply a restatement of (5.98). □

Proof of Theorem 1.2. For \( s \geq \left[ \frac{3}{2} \right] + 4 \), let \( u_\varepsilon \in C([0, T_0], H^{s+1}(\mathbb{R}^n, N)) \) be a solution of (5.1). Choosing a sequence \( \varepsilon_i \to 0 \) we conclude, by means of Theorem 5.9 and Lemma 4.8, 2.7 that there exist functions \( u \in C([0, T_0], H^{s+1}(\mathbb{R}^n, N)) \) and \( v \in C([0, T_0], H^{s+1}(\mathbb{R}^n, \mathbb{R}^m)) \) with \( v = \omega \circ u \) satisfying the initial value problems (3.1) and (2.10) with \( \varepsilon = 0 \) and \( v_0 = \omega \circ u_0 \).

To prove the well-posedness of the Schrödinger flow (i.e. when \( \beta = 0 \) in (1.4)) we refer to work of Ding and Wang [12] and McGahagan [32]. By adapting the argument of Ding and Wang [12] one can show that if a solution, \( u \in C([0, T_0], H^{s+1}(\mathbb{R}^n, N)) \) with \( s \geq \left[ \frac{3}{2} \right] + 4 \), to the initial value problem (1.4) (with \( \beta = 0 \)) exists then it is unique. This argument makes explicit use of the fact that the target is compact and isometrically embedded into some Euclidean space. We present and extend here part of an argument that appears in the proof of Theorem 4.1 in [32]. These inequalities yield uniqueness and continuous dependence on the initial data for general \( \beta \geq 0 \). Let \( u_1, u_2 \in C([0, T_0], H^{s+1}(\mathbb{R}^n, N)) \) be solutions of (1.4) with initial data \( u_0^1, u_0^2 \in H^{s+1}(\mathbb{R}^n, N) \) with \( s \geq \left[ \frac{3}{2} \right] + 4 \). Following the notation in [32] let \( V = \nabla u_1 \) and \( W = \nabla u_2 \). Let \( \widetilde{V}(x) \) represent the parallel transport of \( V \) to the point \( u_2(x) \) along the unique geodesic joining the points. McGahagan proves (see end of the proof of Theorem 4.1 in [32]) that whenever \( \|u_1^0 - u_2^0\|_{H^{\left[\frac{3}{2}\right]}+4} \) is small enough (depending only on the geometry of \( N \)) and \( \beta = 0 \), then

\[
(5.107) \quad \frac{d}{dt} \left( \|W - \widetilde{V}\|^2_{L^2} + \|u_1 - u_2\|^2_{L^2} \right) \leq C \left( \|W - \widetilde{V}\|^2_{L^2} + \|u_1 - u_2\|^2_{L^2} \right),
\]

where \( C \) depends on the \( H^{\left[\frac{3}{2}\right]}+4 \) norms of \( u_1 \) and \( u_2 \). In the case that \( u_1^0 = u_2^0 \) McGahagan concludes (using Gronwall’s) that \( \|W - \widetilde{V}\|^2_{L^2} = \|u_1 - u_2\|^2_{L^2} = 0 \), and that therefore \( u_1 = u_2 \) a.e.. In appendix A we show that the inequality (5.107) (and therefore also the uniqueness result) remains true for all \( \beta \geq 0 \).
Since the unique solution is constructed as a limit of solutions of equation (5.2) letting $\varepsilon \to 0$, the estimate in Theorem 5.9 yields that
\begin{equation}
\sup_{0 \leq t \leq T_0} \| \nabla u(t) \|_{H^s} \leq 3 \| \nabla u_0 \|_{H^s}.
\end{equation}

To prove the continuous dependence on the initial data note that, in general, (5.107) yields
\begin{equation}
\| W - \bar{V} \|_{L^2}^2(t) + \| u_1 - u_2 \|_{L^2}^2(t) \leq e^{Ct} \left( \| W^0 - \bar{V}^0 \|_{L^2}^2 + \| u_1^0 - u_2^0 \|_{L^2}^2 \right),
\end{equation}
where $W^0 = \nabla u_0^0$ and $\bar{V}^0(x)$ is the parallel transport of $V^0 = \nabla u_1^0$ to $u_0^0(x)$. Since
\begin{equation}
\| W - \bar{V} \|_{L^2}^2(t) \lesssim \| \partial u_1 - \partial u_2 \|_{L^2}^2(t) + \| u_1 - u_2 \|_{L^2}^2(t),
\end{equation}
and
\begin{equation}
\| \partial u_1 - \partial u_2 \|_{L^2}^2(t) \lesssim \| W - \bar{V} \|_{L^2}^2(t) + \| u_1 - u_2 \|_{L^2}^2(t),
\end{equation}
(5.109) yields
\begin{equation}
\| \partial u_1 - \partial u_2 \|_{L^2}^2(t) + \| u_1 - u_2 \|_{L^2}^2(t) \lesssim e^{Ct} \left( \| \partial u_1^0 - \partial u_2^0 \|_{L^2}^2 + \| u_1^0 - u_2^0 \|_{L^2}^2 \right).
\end{equation}

Note that (5.112) ensures that $C([0, T_0], H^{s+1}(\mathbb{R}^n, N))$ solutions to (1.4) with $s \geq \left[ \frac{n}{2} \right] + 4$ depend continuously in $H^1$ on the initial data. To show continuous dependence in $H^{s'}$ for $s' < s$ we need to use a classic interpolation inequality in $\mathbb{R}^n$. If $v_i = \omega \circ u_i$ for $i = 1, 2$, where $\omega$ denotes the embedding of $N$ into $\mathbb{R}^p$ then combining (4.52) and (5.112) we have
\begin{equation}
\| \partial v_1 - \partial v_2 \|_{L^2}^2(t) + \| v_1 - v_2 \|_{L^2}^2(t) \lesssim e^{Ct} \left( \| \partial v_1^0 - \partial v_2^0 \|_{L^2}^2 + \| v_1^0 - v_2^0 \|_{L^2}^2 \right).
\end{equation}

Interpolation, Lemma 4.7, Lemma 4.8, (5.108) and (5.113) yield for $s' < s$
\begin{equation}
\| \partial v_1 - \partial v_2 \|_{H^{s'}(t)} \lesssim \| \partial v_1 - \partial v_2 \|_{H^s(t)} \| v_1 - v_2 \|_{L^2}^{1-s'}(t)
\lesssim \left( \| \partial v_1 \|_{H^s(t)}^2 + \| \partial v_2 \|_{H^s(t)}^2 \right)^{1-\frac{s'}{2}} \| v_1 - v_2 \|_{L^2}^{1-\frac{s'}{2}}(t)
\lesssim \left( \| u_1^0 \|_{H^s}^2 + \| u_2^0 \|_{H^s}^2 \right)^{1-\frac{s'}{2}} \| v_1 - v_2 \|_{L^2}^{1-\frac{s'}{2}}(t)
\lesssim \left( \| u_1^0 \|_{H^s}^2 + \| u_2^0 \|_{H^s}^2 \right) e^{Ct} \left( \| \partial v_1^0 - \partial v_2^0 \|_{L^2} + \| v_1^0 - v_2^0 \|_{L^2} \right)^{1-\frac{s'}{2}}.
\end{equation}

Inequalities (5.113) and (5.114) prove that if $u_1, u_2 \in C([0, T_0], H^{s+1}(\mathbb{R}^n, N))$ are solutions to (1.4) and $\| u_1^0 - u_2^0 \|_{H^{s+1}}$ is small enough then the functions $v_1 = \omega \circ u_1$ and $v_2 = \omega \circ u_2$, which are solutions to the ambient equation, depend continuously in the $H^{s'+1}(\mathbb{R}^n, \mathbb{R}^p)$-norm on the initial data for $s' < s$. As mentioned in the introduction by means of the standard Bona-Smith regularization procedure ([8, 19, 22]) one can prove that the dependence on the initial data is continuous in $H^{s+1}(\mathbb{R}^n, \mathbb{R}^p)$. It is in this sense that we express the well-posedness of (1.4). This concludes the proof Theorem 1.2.
Appendix A. Proof of (5.107) for $\beta \geq 0$

Since the proof follows closely the one of Theorem 4.1 in [32] we only sketch the main ideas here.

We let $u_1, u_2 \in C([0, T_0], H^{s+1}(\mathbb{R}^n, N))$ be two solutions of (1.4) with initial data $u_1^0$ respectively $u_2^0$ and we assume that $|u_1^0 - u_2^0|_{H^{s+1}([0, T_0])}$ is small. As in [32] we let $\gamma(x; x, t)$ be the unique length minimizing geodesic (parametrized by arclength $s \in [0, l(x, t)]$) between $u_1(x, t)$ and $u_2(x, t)$, where $\gamma(0; x, t) = u_1(x, t)$ and $\gamma(l(x, t); x, t) = u_2(x, t)$ (the existence of the geodesic follows from the argument on page 392 in [32]; note that this argument is also applicable if $u_1^0$ and $u_2^0$ are only close to each other in $L^n$). Moreover we define $V_k = \partial_k u_1$, $W_k = \partial_k u_2$ and $V_k = X(l, 0) V_k$ as the parallel transport of $V_k$ to the point $u_2$. In the following we let $X(l, 0) =: X$.

In [32], page 391, the following commutator formulas are derived: \( \forall F \in T_{u_1, N} \) we have
\[
XJ(u_1)F = J(u_2)XF,
\]
(A.1) \[ [D_k, X]F = \int_0^t X(\tau) R(\partial_k \gamma, \partial_s \gamma) X(\tau, 0) F d\tau. \]

Additionally the estimates
\[
||[D_t, X]V||_{L^2} + ||[D, X] \partial_t u_1||_{L^2} + ||D[D_k, X]V_k||_{L^2} \leq c(||W - \bar{V}||_{L^2} + ||u_1 - u_2||_{L^2})
\]
(A.2) have been derived in [32] (see estimates (42), (43) and page 395). In the following we also need the fact that
\[
||[D_k, X]V_k||_{L^2} \leq c(||W - \bar{V}||_{L^2} + ||u_1 - u_2||_{L^2}).
\]
(A.3) In order to see this we note that
\[
||[D_k, X]V_k||_{L^2} \leq c||\nabla \gamma V_k||_{L^2}.
\]

For $n \geq 3$ we can use the Sobolev embedding theorem and Hölder’s inequality to get (note that $||\nabla \gamma|| \leq c(||V|| + ||W||)$)
\[
||[D_k, X]V_k||_{L^2} \leq c||\nabla l||_{L^2} ||V||(||V|| + ||W||)||_{L^n} \leq c||W - \bar{V}||_{L^2}^2
\]
In the case $n = 2$ one argues with the help of the Brezis-Wainger theorem as in [32], page 395.

Now we are finally able to prove (5.107). Since $u_1$ and $u_2$ are both solutions of (1.4) we get
\[
\partial_t u_2 - (J(u_2) + \beta)\tau(u_2) - X \left( \partial_t u_1 - (J(u_1) + \beta)\tau(u_1) \right) = 0.
\]
Using the previous definitions and the commutator formula (A.1) we can rewrite this equation as follows
\[
\partial_t u_2 - XD\partial_t u_1 - J(u_2)(D_k W_k - XD_k V_k) = \beta(D_k W_k - XD_k V_k).
\]
Multiplying this equation with $D_k W_k - XD_k V_k \in T_{u_2, N}$ and integrating we get
\[
\int_{\mathbb{R}^n} \langle \partial_t u_2 - XD\partial_t u_1, D_k W_k - XD_k V_k \rangle = \beta \int_{\mathbb{R}^n} |D_k W_k - XD_k V_k|^2.
\]
Next we calculate
\[ \int_{\mathbb{R}^n} \langle \partial_t u_2 - X \partial_t u_1, D_k W_k - X D_k V_k \rangle \]
\[ = - \int_{\mathbb{R}^n} \langle D_k (\partial_t u_2 - X \partial_t u_1), W_k - X V_k \rangle - \int_{\mathbb{R}^n} \langle \partial_t u_2 - X \partial_t u_1, [X, D_k] V_k \rangle \]
\[ = - \int_{\mathbb{R}^n} \langle \partial_t W_k - X \partial_t V_k, W_k - X V_k \rangle - \int_{\mathbb{R}^n} \langle [D_k, X] \partial_t u_1, W_k - X V_k \rangle - I \]
\[ = - \frac{1}{2} \int_{\mathbb{R}^n} |W_k - X V_k|^2 + \int_{\mathbb{R}^n} \langle [X, \partial_t] V_k, W_k - X V_k \rangle - I - II \]
\[ = - \frac{1}{2} \int_{\mathbb{R}^n} |W_k - X V_k|^2 - I - II + III. \]

Combining this with the above equality we conclude
\[ \frac{1}{2} \partial_t \int_{\mathbb{R}^n} |W_k - X V_k|^2 + \beta \int_{\mathbb{R}^n} |D_k W_k - X D_k V_k|^2 = -I - II + III. \]

Next we estimate the three terms on the right hand side. We start with
\[ |II| \leq c ||W_k - X V_k||_{L^2}||[D_k, X] \partial_t u_1||_{L^2} \]
\[ \leq c (||W - \bar{V}||^2_{L^2} + ||u_1 - u_2||^2_{L^2}), \]
where we used (A.2) in the last line. Using the same arguments we also get
\[ |III| \leq c ||W_k - X V_k||_{L^2}||[X, \partial_t] V_k||_{L^2} \]
\[ \leq c (||W - \bar{V}||^2_{L^2} + ||u_1 - u_2||^2_{L^2}). \]

In order to estimate I we use equation (1.4), the fact that \( \nabla J = 0 \) and (A.1) to rewrite
\[ -I = - \int_{\mathbb{R}^n} \langle \partial_t u_2 - X \partial_t u_1, [X, D_k] V_k \rangle \]
\[ = - \int_{\mathbb{R}^n} \langle (J(u_2) + \beta_x(u_2) - X(J(u_1) + \beta \tau(u_1)), [X, D_k] V_k \rangle \]
\[ = - \int_{\mathbb{R}^n} \langle (J(u_2) + \beta)(D_k W_k - D_k(XV_k) - [X, D_k] V_k), [X, D_k] V_k \rangle \]
\[ = \int_{\mathbb{R}^n} \langle (J(u_2) + \beta)(W_k - X V_k), D_k([X, D_k] V_k) \rangle + \beta \int_{\mathbb{R}^n} ||[X, D_k] V_k||^2. \]

Using Hölder’s inequality, (A.2) and (A.3) we get
\[ |I| \leq c (||W - \bar{V}||^2_{L^2} + ||u_1 - u_2||^2_{L^2}). \]

Altogether this implies
(A.4)
\[ \frac{1}{2} \partial_t \int_{\mathbb{R}^n} |W - \bar{V}|^2 + \beta \int_{\mathbb{R}^n} |D_k W_k - X D_k V_k|^2 \leq c (||W - \bar{V}||^2_{L^2} + ||u_1 - u_2||^2_{L^2}). \]

Next we need to estimate \( \frac{1}{2} \partial_t \int_{\mathbb{R}^n} |u_1 - u_2|^2. \) In order to do this we argue as in [32] and we consider \( N \) to be isometrically embedded into \( \mathbb{R}^p \) and we extend \( J \) as a continuous linear operator on \( \mathbb{R}^p. \) In the following we denote the second fundamental form of the embedding \( N \hookrightarrow \mathbb{R}^p \) by \( A. \) With the help of these conventions.
we calculate
\[
\frac{1}{2} \partial_t \int_{\mathbb{R}^n} |u_1 - u_2|^2 = \int_{\mathbb{R}^n} \langle \partial_t (u_1 - u_2), u_1 - u_2 \rangle
\]
\[
= \int_{\mathbb{R}^n} \langle J(u_1) \Delta u_1 - J(u_2) \Delta u_2, u_1 - u_2 \rangle + \beta \int_{\mathbb{R}^n} \langle \Delta u_1 - \Delta u_2, u_1 - u_2 \rangle
\]
\[
+ \int_{\mathbb{R}^n} \langle (J(u_1) + \beta) A(u_1)(\nabla u_1, \nabla u_1) - (J(u_2) + \beta) A(u_2)(\nabla u_2, \nabla u_2), u_1 - u_2 \rangle.
\]
Arguing as in [32], page 296, we get the estimate
\[
\int_{\mathbb{R}^n} \langle (J(u_1) + \beta) A(u_1)(\nabla u_1, \nabla u_1) - (J(u_2) + \beta) A(u_2)(\nabla u_2, \nabla u_2), u_1 - u_2 \rangle
\]
\[
+ \int_{\mathbb{R}^n} \langle (J(u_1) \Delta u_1 - J(u_2) \Delta u_2, u_1 - u_2 \rangle
\]
\[
\leq c(||W - \bar{V}||^2_{L^2} + ||u_1 - u_2||^2_{L^2}).
\]
Moreover we note that
\[
\beta \int_{\mathbb{R}^n} \langle \Delta u_1 - \Delta u_2, u_1 - u_2 \rangle = -\beta ||\nabla u_1 - \nabla u_2||^2_{L^2}
\]
and hence we conclude
\[
(A.5) \quad \frac{1}{2} \partial_t \int_{\mathbb{R}^n} |u_1 - u_2|^2 + \beta ||\nabla u_1 - \nabla u_2||^2_{L^2} \leq c(||W - \bar{V}||^2_{L^2} + ||u_1 - u_2||^2_{L^2}).
\]
Combining (A.4) and (A.5) finishes the proof of of (5.107) for general \( \beta \geq 0. \)

References


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