

①

Homework 7

3.4.1
$$\begin{aligned} h_1 &= a_{11} x_1 + a_{12} x_2 + a_{13} x_3 + b_1 \\ h_2 &= a_{21} x_1 + a_{22} x_2 + a_{23} x_3 + b_2 \end{aligned} \quad A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \text{ invertible}$$

a)
$$\nabla h_1(x^*) = \begin{pmatrix} a_{11} \\ a_{12} \\ a_{13} \end{pmatrix} \quad \nabla h_2(x^*) = \begin{pmatrix} a_{21} \\ a_{22} \\ a_{23} \end{pmatrix}$$

Suppose $\nabla h_1(x^*) \cdot \nabla h_2(x^*)$ are dependent. Then $\exists \lambda, \mu \neq 0$
s.t.
$$\lambda \begin{pmatrix} a_{11} \\ a_{12} \\ a_{13} \end{pmatrix} + \mu \begin{pmatrix} a_{21} \\ a_{22} \\ a_{23} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

In particular
$$\lambda \begin{pmatrix} a_{11} \\ a_{12} \end{pmatrix} + \mu \begin{pmatrix} a_{21} \\ a_{22} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \text{rk} \begin{bmatrix} a_{11} & a_{21} \\ a_{12} & a_{22} \end{bmatrix} < 2$$

$$\Rightarrow \text{rk} \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} = \text{rk} \begin{bmatrix} a_{11} & a_{21} \\ a_{12} & a_{22} \end{bmatrix} < 2 \text{ which contradicts that}$$

$$\begin{bmatrix} a_{12} & a_{13} \\ a_{22} & a_{23} \end{bmatrix} \text{ is invertible.}$$

$\therefore$ By Lemma 3.4.1 for any $w \in \mathbb{R}^3$ satisfying
 $\nabla h_1(x^*)^T w = 0, \nabla h_2(x^*)^T w = 0 \exists T \in (0, 1]$
and differentiable functions $x(t) = (x_1(t), x_2(t), x_3(t))$
 $t \in [0, T]$ s.t. $x(0) = x^*, x'(0) = w$ & $x(t)$ feasible
 $\forall t \in [0, T]$.

b)
$$\begin{aligned} h_1(x(t)) &= 0 \Rightarrow a_{11} x_1(t) + a_{12} x_2(t) + a_{13} x_3(t) + b_1 = 0 \\ h_2(x(t)) &= 0 \Rightarrow a_{21} x_1(t) + a_{22} x_2(t) + a_{23} x_3(t) + b_2 = 0 \end{aligned}$$

$$\Rightarrow \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \end{bmatrix} \begin{pmatrix} x_1(t) \\ x_2(t) \\ x_3(t) \end{pmatrix} = \begin{pmatrix} -b_1 \\ -b_2 \end{pmatrix} \Rightarrow \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}^{-1} \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \end{bmatrix} \begin{pmatrix} x_1(t) \\ x_2(t) \\ x_3(t) \end{pmatrix} = \begin{pmatrix} -b_1 \\ -b_2 \end{pmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{pmatrix} x_1(t) \\ x_2(t) \end{pmatrix} + A^{-1} \begin{pmatrix} a_{13} \\ a_{23} \end{pmatrix} x_3(t) = A^{-1} \begin{pmatrix} b_1 \\ b_2 \end{pmatrix}$$

$$\begin{pmatrix} x_1(t) \\ x_2(t) \end{pmatrix} = A^{-1} b - A^{-1} \begin{pmatrix} a_{13} \\ a_{23} \end{pmatrix} x_3(t) //$$

(2)

c) More generally if $\exists$ m equations $h_i = \sum_{j=1}^n a_{ij} x_j + b_i \quad i=1, \dots, m$
 and $A = \begin{bmatrix} a_{11} & \dots & a_{1m} \\ \vdots & & \vdots \\ a_{m1} & \dots & a_{mm} \end{bmatrix}$ is invertible

then $\nabla h_i(x^*) = \begin{pmatrix} a_{i1} \\ a_{i2} \\ \vdots \\ a_{im} \end{pmatrix}$. They are LI since the top $m \times m$ minor of the matrix $(\nabla h_1(x^*), \dots, \nabla h_m(x^*))$ is invertible

and

$$\begin{pmatrix} x_1(t) \\ \vdots \\ x_m(t) \end{pmatrix} + A^{-1} \begin{bmatrix} a_{1m+1} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{mm+1} & \dots & a_{mn} \end{bmatrix} \begin{pmatrix} x_{m+1}(t) \\ \vdots \\ x_n(t) \end{pmatrix} = A^{-1} b$$

$$\therefore \begin{pmatrix} x_1(t) \\ \vdots \\ x_m(t) \end{pmatrix} = A^{-1} b - A^{-1} \begin{bmatrix} a_{1m+1} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{mm+1} & \dots & a_{mn} \end{bmatrix} \begin{pmatrix} x_{m+1}(t) \\ \vdots \\ x_n(t) \end{pmatrix}$$

Also know $x'(0) = w$ and $x(0) = x^*$.

3.4.2: NLP $\min f(x)$

s.t. $g_1(x) \leq 0, \dots, g_l(x) \leq 0$

1st partials of f, g_i 's are continuous on $\mathbb{R}^n$

x^* local opt of NLP. $I(x^*) = \{i \in \{1, \dots, l\} : g_i(x^*) = 0\}$

Consider the inequality system:

$$(+) \quad \begin{aligned} \nabla f(x^*)^T w &< 0 \\ \nabla g_i(x^*)^T w &< 0 \quad \forall i \in I(x^*) \end{aligned}$$

Show this system has no solⁿ $\bar{w}$.

Suppose $\exists w$ satisfying (+). We will contradict that x^* is a local min.

Let $\phi(t) = f(x^* + tw)$. Then $\phi'(t) = \nabla f(x^* + tw)^T w \quad \forall t \in \mathbb{R}$
 by Lemma 3.1.1.

$\Rightarrow \phi'(0) = \nabla f(x^*)^T w < 0$ by assumption.

(3)

Since the 1st partial of f is const on $\mathbb{R}^n$, $\exists \bar{\epsilon}$ s.t. $\forall$
 $0 < t \leq \bar{\epsilon}$ $\frac{\phi(t) - \phi(0)}{t} < 0 \Rightarrow \phi(t) < \phi(0)$

$$\Rightarrow f(x^* + tw) < f(x^*).$$

This will contradict that x^* is a local min if we can further show that $g_i(x^* + tw) \leq 0 \quad \forall t \in (0, \bar{\epsilon}]$

If $i \notin I(x^*)$ then $g_i(x^*) < 0 \therefore$ for small t
 $g_i(x^* + tw) \leq 0$. So we need only worry about
 $i \in I(x^*)$

If $i \in I(x^*)$, we are given $\nabla g_i(x^*)^T w < 0$

$$g_i(x^* + tw) = g_i(x^*) + \nabla g_i(x^*)^T tw + \frac{1}{2}(tw)^T H g_i(z)(tw)$$

for some $z \in [x^*, x^* + tw]$ by Taylor

Now $g_i(x^*) = 0$ since $i \in I(x^*)$

$$\nabla g_i(x^*)^T tw < 0 \quad \text{since } t > 0 \text{ and } \nabla g_i(x^*)^T w < 0$$

and the second order term is small for t small. by assumption

$\therefore g_i(x^* + tw) \leq 0$ for t small.

Choosing $\bar{\epsilon}$ to be small enough to make all our "t small" statements true

we get that $f(x^* + tw) < f(x^*) \quad \forall 0 < t \leq \bar{\epsilon}$
 But since this segment $[x^*, x^* + tw]$ does not intersect
 any ball with center x^* , we get that
 x^* is not a local opt. Contradiction!

⑥ To do this part you need a version of duality that deals with strict inequalities

Claim: Either $Ax < b$ has no solⁿ or $y=0$ is not the only solⁿ of the system $y \geq 0, yA=0, yb \leq 0$.

Apply this to your system from ② let $p = |I(x^*)|$
 $\nabla f(x^*)^T w < 0$ $\nabla g_i(x^*)^T w < 0 \quad i \in I(x^*)$ has no solⁿ ($\Rightarrow$)
 $u = (u_0, u_1, \dots, u_p)$ is not the only solⁿ to
 $u \geq 0, \quad (u_0, u_1, \dots, u_p) \begin{bmatrix} \nabla f(x^*) \\ \nabla g_i(x^*) \end{bmatrix}_{i \in I(x^*)} = 0 \quad u \cdot 0 \leq 0$

Extend to $u_0, u_1, \dots, u_\ell$ by setting $u_i = 0$ if $i \notin I(x^*)$

$\therefore \exists$ a nonzero solⁿ $(u_0, u_1, \dots, u_\ell)$ to the system

$$u_0 \geq 0 \quad u_1, \dots, u_\ell \geq 0$$

$$u_0 \nabla f(x^*) + \sum_{i=1}^{\ell} u_i \nabla g_i(x^*) = 0$$

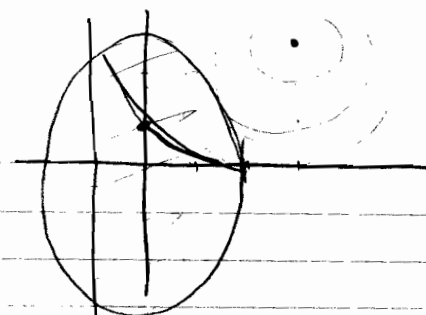
Check that $u_i g_i(x^*) = 0 \quad \forall i = 1, \dots, \ell$ since

if $g_i(x^*) \neq 0$ then $i \notin I(x^*) \Rightarrow u_i = 0$ by the way we set it.

④

3.4.3 $\min (x_1 - 3)^2 + (x_2 - 3)^2$
 s.t $4x_1^2 + 9x_2^2 - 36 \leq 0$
 $-x_1 - 1 \leq 0$
 $x_1^2 + 3x_2 - 3 = 0$

f
 g_1
 g_2
 h_1



$$\nabla f = \begin{pmatrix} 2(x_1 - 3) \\ 2(x_2 - 3) \end{pmatrix} \quad \nabla g_1 = \begin{pmatrix} 8x_1 \\ 18x_2 \end{pmatrix} \quad \nabla g_2 = \begin{pmatrix} -1 \\ 0 \end{pmatrix} \quad \nabla h_1 = \begin{pmatrix} 2x_1 \\ 3 \end{pmatrix}$$

(KKT) $\begin{cases} 2x_1 - 6 + \lambda_1 8x_1 - \lambda_2 + 2\mu_1 x_1 = 0 \\ 2x_2 - 6 + 18\lambda_1 x_2 + 3\mu_1 = 0 \end{cases} \begin{cases} \lambda_1 \geq 0 & \lambda_2 \geq 0 \\ \lambda_1 g_1 = 0 & \lambda_2 g_2 = 0 \end{cases}$

Case 1: $\lambda_1 = \lambda_2 = 0$

(KKT) $\Rightarrow 2x_1 - 6 + 2\mu_1 x_1 = 0 \Rightarrow 2x_1(\mu_1 + 1) = 6$

$\Rightarrow x_1 = \frac{3}{1 + \mu_1}$
 $2x_2 - 6 + 3\mu_1 = 0 \Rightarrow x_2 = \frac{6 - 3\mu_1}{2}$

$h_1 = 0 \Rightarrow \left(\frac{3}{1 + \mu_1}\right)^2 + 3\left(\frac{6 - 3\mu_1}{2}\right) = 3$

$\Rightarrow \frac{9}{(1 + \mu_1)^2} = 3\left(\frac{2 - 6 + 3\mu_1}{2}\right) = \frac{3}{2}(3\mu_1 - 4)$

$\Rightarrow 6 = (3\mu_1 - 4)(1 + \mu_1)^2 = (3\mu_1 - 4)(1 + \mu_1^2 + 2\mu_1)$
 $= 3\mu_1 + 3\mu_1^3 + 6\mu_1^2 - 4 - 4\mu_1^2 - 8\mu_1$
 $6 = 3\mu_1^3 + 2\mu_1^2 - 5\mu_1 - 4$

$\Rightarrow 3\mu_1^3 + 2\mu_1^2 - 5\mu_1 - 10 = 0$ has only one real root $\mu_1 = 1.6238$

$\therefore x_1 = \frac{3}{2.6238} = 1.1433 \quad x_2 = 0.5642$ Satisfies $g_1 \leq 0 \quad g_2 \leq 0$

Case 2: $\lambda_1 = 0, g_2 = 0$

$g_2 = 0 \Rightarrow -x_1 - 1 = 0 \Rightarrow x_1 = -1$

KKT $\Rightarrow 2x_1 - 6 - \lambda_2 + 2\mu_1 x_1 = 0 \Rightarrow -2 - 6 - \lambda_2 - 2\mu_1 = 0$

$\Rightarrow -8 - \lambda_2 - 2\mu_1 = 0 \Rightarrow \lambda_2 = -8 - 2\mu_1$

$h_1 = 0 \Rightarrow 3x_2 = 3 - x_1^2 = 3 - 1 = 2 \quad x_2 = 2/3$

KKT $\Rightarrow 2\left(\frac{2}{3}\right) - 6 + 3\mu_1 = 0 \Rightarrow 3\mu_1 = 6 - \frac{4}{3} = \frac{14}{3} \therefore \mu_1 = \frac{14}{9}$

not ok
 so
 discard

$\lambda_2 = -8 - 2\left(\frac{14}{9}\right) = -8 - \frac{28}{9} = -\frac{100}{9}$
 $\uparrow \neq -100$

(5)

Case 3 $\lambda_2 = 0$ $g_1 = 0$

$g_1 = 0 \Rightarrow$

$4x_1^2 + 9x_2^2 = 36$

(i)

$h_1 = 0 \Rightarrow$

$x_1^2 + 3x_2 - 3 = 0$

(ii)

(KKT) $\Rightarrow$

$2x_1 - 6 + 8\lambda_1 x_1 + 2\mu_1 x_1 = 0$

$2x_2 - 6 + 18\lambda_1 x_2 + 3\mu_1 = 0$

(ii) $\Rightarrow x_1^2 = 3 - 3x_2$ substituting in (i) we get

$4(3 - 3x_2) + 9x_2^2 = 36 \Rightarrow 12 - 12x_2 + 9x_2^2 - 36 = 0$

$\Rightarrow 9x_2^2 - 12x_2 - 24 = 0 \Rightarrow 3x_2^2 - 4x_2 - 8 = 0$

$x_2 = \frac{4 \pm \sqrt{16 + 96}}{6} = \frac{4 \pm \sqrt{112}}{6} = 2.4305 \text{ or } -1.0971$

$x_1^2 = 3 - 3(2.4305) = -4.2915 \text{ (not possible)}$

$x_1^2 = 3 - 3(-1.0971) \Rightarrow x_1 = 2.50824$

 $\therefore$ One possibility is $x_1 = 2.50824$ $x_2 = -1.0971$

Now substituting this into KKT gives

$\lambda_1 = -0.2395$

$\mu_1 = 1.15436$

(discard since $\lambda_1 < 0$)Case 4 $g_1 = 0$ $g_2 = 0$

$g_2 = 0 \Rightarrow x_1 = -1$

$g_1 = 0 \Rightarrow$

$4x_1^2 + 9x_2^2 - 36 = 0$

$\Rightarrow$

$4 + 9x_2^2 - 36 = 0 \Rightarrow 9x_2^2 = 32$

$x_2^2 = \frac{32}{9}$

$x_2 = \pm 1.885618$

Check if $h_1 = 0$

$1 + 3(1.885618) - 3 = -2 + 3(1.885618) \neq 0$

 $\therefore$ This soln is not feasible

$1 + 3(-1.885618) - 3 \neq 0 \therefore$ both solns not feasible.

 $\therefore$ Only $x_1 = 1.1433$ $x_2 = 0.5642$ $\mu_1 = 1.6238$ $\lambda_1 = \lambda_2 = 0$ is a possible local opt.

⑥

$$H_f = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$$

$$H_{g_1} = \begin{bmatrix} 8 & 0 \\ 0 & 18 \end{bmatrix}$$

$$H_{g_2} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$H_h = \begin{bmatrix} 2 & 0 \\ 0 & 0 \end{bmatrix}$$

$$\therefore H_f + \lambda_1 H_{g_1} + \lambda_2 H_{g_2} + \mu_1 H_h = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} + 1.6238 \begin{bmatrix} 2 & 0 \\ 0 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 5.2476 & 0 \\ 0 & 2 \end{bmatrix} > 0 \text{ since diagonal entries are positive.}$$

So this solⁿ is a local opt.