# The Discrete Transport Equation 

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#### Abstract

For background I first describe the continuous transport equation and the forward and inverse problems associated with it (as posed in [1]). I then formulate discrete analogs of these problems.


## 1 The Continuous Problem

Let $X \subset \mathbf{R}^{n}$ be an open convex set with piecewise smooth boundary $\partial X$, and let $v \in \mathbf{S}^{n-1}$ be any direction and $x \in X$. The Transport Equation, also known as the Linearized Boltzmann Equation, is

$$
\begin{equation*}
-v \cdot \nabla \phi(x, v)-\sigma(x, v) \phi(x, v)+\int_{\mathbf{S}^{n-1}} \kappa(x, v, w) \phi(x, w) d w=0 \tag{1}
\end{equation*}
$$

This equation describes the flow of a stream of particles as they move through a medium and are absorbed and scattered. The interpretation of the symbols in this equation is as follows.

- The Flux $\phi$ is defined on $X \times \mathbf{S}^{n-1}$, where $\phi(x, v)$ is the flux of particles through the point $x$ and in the direction $v$. Note that in general $\phi(x, v) \neq \phi(x,-v)$-imagine two beams of photons moving past each other in opposite directions. One does however usually require that $\phi \geq 0$.
- The Absorption Coefficient $\sigma$ is defined on $X \times \mathbf{S}^{n-1}$ and must be nonnegative, and represents the rate at which particles are absorbed as they move through the point $x$ in the direction $v$. In many situations one takes $\sigma$ to be independent of direction and depend only on location.
- The Collision Kernel $\kappa$ is defined on $X \times \mathbf{S}^{n-1} \times \mathbf{S}^{n-1}$ and takes on nonnegative values. $\kappa(x, v, w)$ gives the rate at which particles moving in the $w$ direction at the point $x$ are deflected into the $v$ direction.

In posing the forward and inverse problem in this setting, we will need the following notation. For $x \in \partial X$, let $n(x)$ be the unit outward pointing normal. Define $\Gamma_{+}$and $\Gamma_{-}$by $\Gamma_{ \pm}=\left\{(x, v) \in \partial X \times \mathbf{S}^{n-1} \mid \pm n \cdot v>0\right\}$.

Given a nonnegative function $\phi_{-}$on $\Gamma_{-}$as boundary data, the forward problem is to find a function $\phi$ on $X \times \mathbf{S}^{n-1}$ which satisfies the transport equation and has $\left.\phi\right|_{\Gamma_{-}}=\phi_{-}$.

Let $\phi_{+}=\left.\phi\right|_{\Gamma_{+}}$. The map $\mathcal{A}: \phi_{-} \longmapsto \phi_{+}$is called the Albedo operator. The inverse problem is to calculate $\sigma$ and $\kappa$ from $\mathcal{A}$.

## 2 Now we do it Discretely!

Definition 2.1 Let $G=\left(V, V_{B}, E\right)$ be a finite directed graph with boundary, and with the following additional conditions.

1. Each boundary node $p \in V_{B}$ has degree one.
2. At each interior node $p$ there is a bijection $\operatorname{in}(p) \longleftrightarrow$ out $(p)$. The image of an incoming edge $e$ is denoted $e^{+}$and the image of an outgoing edge $f$ is denoted $f^{-}$. Note that this implies that each interior node has even degree.

## Then $G$ is said to be a Transport Graph.

Let $\operatorname{in}(p)$ denote the set of edges incoming at the node $p$ and let out $(p)$ denote the set of edges outgoing at node $p$. If $P$ is a set of nodes in $G$, then $\operatorname{in}(P)=\bigcup_{p \in P} i n(p)$ and similarly for $\operatorname{out}(P)$. Thus $i n\left(V_{B}\right)$ is the set of all edges which have no successor, and $\operatorname{out}\left(V_{B}\right)$ is the set of all edges which have no predecessor. The sets out $\left(V_{B}\right.$ and $\operatorname{in}\left(V_{B}\right)$ take the place of $\Gamma_{-}$and $\Gamma_{+}$ respectively.

The relevant functions for the discrete transport equation are represented on the graph as follows:

- The flux $\phi: E \rightarrow \mathbf{R}^{+}$is an edge function. $\phi(e)$ is interpreted as giving the flux along the edge $e$ in the direction that $e$ points.
- The absorption coefficient is a function $\sigma: V \rightarrow(0,1)$, where $\sigma(p)$ is now interpreted as the probability that a particle coming into an interior node $p$ along any edge will be absorbed before it leaves. We will need $\sigma$ to be nonzero in order to prove the uniqueness of the solution to the forward problem.
- The collision kernel is a set of functions $\left\{\kappa_{p}: \operatorname{out}(p) \times \operatorname{in}(p) \rightarrow[0, \delta) \mid \forall p \in V\right\}$, (for $\delta$ sufficiently small as will be described shortly) defined at each interior node $p \in V$, and satisfying the condition that $\kappa_{p}\left(e^{+}, e\right)=0, \forall p \in V$, $\forall e \in \operatorname{in}(p)$ since direct transmission is mediated by absorption rather than collision. We have the interpretation that $\kappa_{p}(e, f)$ is the probability that a particle entering node $p$ along edge $f$ will leave along the edge $e$.

Replacing each term in the continuous equation with its discrete analog, one obtains

$$
-\left[\phi\left(e^{+}\right)-\phi(e)\right]-\sigma(p) \phi(e)+\sum_{g \in \operatorname{in}(p)} \kappa_{p}\left(e^{+}, g\right) \phi(g)=0
$$

However, this equation does not correctly conform to the probabilistic interpretation of $\sigma$, so we modify it by replacing $\sigma(p)$ with: (absorption probability) + (total collision probability for particle incoming along edge $e$ ). Therefore, the correct equation is

$$
-\left[\phi\left(e^{+}\right)-\phi(e)\right]-\left[\sigma(p)+\sum_{f \in \operatorname{out}(p)} \kappa_{p}(f, e)\right] \phi(e)+\sum_{g \in \operatorname{in}(p)} \kappa_{p}\left(e^{+}, g\right) \phi(g)=0
$$

which may be written in a more compact form as,

$$
\begin{equation*}
\phi\left(e^{+}\right)=\sum_{f \in \operatorname{in}(p)} \tau_{p}\left(e^{+}, f\right) \phi(f) \tag{2}
\end{equation*}
$$

Here $\tau_{p}$ is the transport function at node $p$. Its values are given by

$$
\tau_{p}\left(e^{+}, f\right)= \begin{cases}1-\sigma(p)-\sum_{g \in o u t(p)} \kappa_{p}(g, f) & f=e  \tag{3}\\ \kappa\left(e^{+}, f\right) & f \neq e\end{cases}
$$

The value of $\tau_{p}\left(e^{+}, f\right)$ can be interpreted as the probability that a particle entering node $p$ along the edge $f$ will leave $p$ along the edge $e^{+}$. For eq. 3 to make sense under this interpretation, it is apparent that the entries in the collision kernel must be sufficiently small. This consideration places an upper bound on $\delta$. We will thus assume that $\delta$ is small enough so that the values of $\tau_{p}$ are all in the range $[0,1)$. In the continuous setting there is a similar constraint on $\kappa$ for there to be a well posed forward problem.

Definition 2.2 A transport network $\Gamma$ is pair $(G, \tau)$, where $G$ is a transport network, and $\tau$ is a transport function (which can be decomposed into an absorption coefficient $\sigma: V \rightarrow[0,1]$ and a collision kernel $\kappa$ (with $\delta$ sufficiently small).

Number the elements of $\operatorname{in}(p)$ as $e_{1}, e_{2}, \ldots, e_{n}$. We form a matrix $T_{p}$, called the transport matrix at node $p$, with entries $\left[T_{p}\right]_{i j}=\tau_{p}\left(e_{i}^{+}, e_{j}\right)$. Let $\phi$ be a nonnegative function on the edges of $\Gamma$ and let $\Phi_{p}^{i n}$ denote the column vector $\left[\phi\left(e_{1}\right), \phi\left(e_{2}\right), \ldots, \phi\left(e_{n}\right)\right]^{T}$; define $\Phi_{p}^{\text {out }}$ similarly. To say that $\phi$ satisfies the transport equation is to say that $\forall p \in V$,

$$
\begin{equation*}
\Phi_{p}^{\text {out }}=T_{p} \Phi_{p}^{\text {in }} . \tag{4}
\end{equation*}
$$

In this case we say that $\phi$ is a $\tau$-flow.

### 2.1 The Discrete Forward Problem

Given transport network $\Gamma$ and a nonnegative function $\psi_{-}$defined on $\operatorname{out}\left(V_{B}\right)$, the forward problem is to find a $\tau$-flow $\phi$ such that $\left.\phi\right|_{\text {out }\left(V_{B}\right)}=\psi_{-}$. Equation 2 gives exactly one linear equation for each edge with an unknown flux. Putting these together results in a system of $n$ equations with $n$ unknowns, where $n$ is the number of edges with un-imposed fluxes. This system is of the form $Q x=b$.

Lemma 2.1 The matrix $Q$ has the following properties:

1. Each diagonal entry $q_{i i}$ of $Q$ is 1 .
2. The non-diagonal entries $q_{i j}$ of $Q$ all satisfy $-1<q_{i j} \leq 0$.
3. In each row or column there is at most a single non-diagonal entry that is larger than $\delta$ in magnitude.

Proof: Property (1) follows directly from the form of eq. 2. Property (2) also follows directly from eq. 2 combined with the fact that the values of the transport function are always in the range $[0,1$ ). To prove property (3), first note that $\tau_{p}(e, f)<\delta$ if $f$ is not the successor of $e$. From eq. 2, in each row of $Q$ there is at most a single non-diagonal entry that is greater than $\delta$ because each edge has only a single predecessor and only the successor-predecessor term can be greater than $\delta$. Similarly, each edge has at most one successor, so by the same reasoning in each column of $Q$ there is at most a single non-diagonal entry that is greater than $\delta$.

Theorem 2.1 Let $\sigma_{0}$ be the minimum value of $\sigma$. If $\delta<\sigma_{0} /(n-2)$ then $Q$ is diagonally dominant and hence nonsingular.

Proof: Computing a row sum of $Q$ in the $i$ th row,

$$
\sum_{j=1}^{n} q_{i j}=q_{i i}+\sum_{j=1, j \neq i}^{n} q_{i j}>1-(n-2) \delta-\left(1-\sigma_{0}\right)=\sigma_{0}-(n-2) \delta
$$

And clearly if $\delta<\sigma /(n-2)$ then this quantity is positive. A nearly identical argument shows that the column sums are all positive.

Corollary 2.1 Given a transport network $\Gamma, \exists \delta$ such that if $\forall p \in V,\left\|\kappa_{p}\right\|<\delta$ then there is a solution to the forward problem, and this solution is unique.

### 2.2 The Discrete Inverse Problem

Given $\psi_{-}$and assuming that the forward problem has a unique solution, we define $\psi_{+}=\left.\phi\right|_{\text {in }\left(V_{B}\right)}$. The Albedo operator is then the linear map

$$
\mathcal{A}: \psi_{-} \longmapsto \psi_{+}
$$

The inverse problem is to recover information about $\sigma$ and $\kappa$ from $\mathcal{A}$.

## References

[1] Plemen Stefanov, Gunther Uhlmann, "Optical Tomography in two dimensions", 2002. Preprint available at www.math.purdue.edu/~ stefanov

