# The Discrete Transport Equation

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#### Abstract

For background I first describe the continuous transport equation and the forward and inverse problems associated with it (as posed in [1]). I then formulate discrete analogs of these problems.

## 1 The Continuous Problem

Let  $X \subset \mathbf{R}^n$  be an open convex set with piecewise smooth boundary  $\partial X$ , and let  $v \in \mathbf{S}^{n-1}$  be any direction and  $x \in X$ . The *Transport Equation*, also known as the *Linearized Boltzmann Equation*, is

$$-v \cdot \nabla \phi(x,v) - \sigma(x,v)\phi(x,v) + \int_{\mathbf{S}^{n-1}} \kappa(x,v,w)\phi(x,w)dw = 0.$$
(1)

This equation describes the flow of a stream of particles as they move through a medium and are absorbed and scattered. The interpretation of the symbols in this equation is as follows.

- The Flux  $\phi$  is defined on  $X \times \mathbf{S}^{n-1}$ , where  $\phi(x, v)$  is the flux of particles through the point x and in the direction v. Note that in general  $\phi(x, v) \neq \phi(x, -v)$ —imagine two beams of photons moving past each other in opposite directions. One does however usually require that  $\phi \geq 0$ .
- The Absorption Coefficient  $\sigma$  is defined on  $X \times \mathbf{S}^{n-1}$  and must be nonnegative, and represents the rate at which particles are absorbed as they move through the point x in the direction v. In many situations one takes  $\sigma$  to be independent of direction and depend only on location.
- The Collision Kernel  $\kappa$  is defined on  $X \times \mathbf{S}^{n-1} \times \mathbf{S}^{n-1}$  and takes on nonnegative values.  $\kappa(x, v, w)$  gives the rate at which particles moving in the w direction at the point x are deflected into the v direction.

In posing the forward and inverse problem in this setting, we will need the following notation. For  $x \in \partial X$ , let n(x) be the unit outward pointing normal. Define  $\Gamma_+$  and  $\Gamma_-$  by  $\Gamma_{\pm} = \{(x, v) \in \partial X \times \mathbf{S}^{n-1} | \pm n \cdot v > 0\}.$  Given a nonnegative function  $\phi_{-}$  on  $\Gamma_{-}$  as boundary data, the forward problem is to find a function  $\phi$  on  $X \times \mathbf{S}^{n-1}$  which satisfies the transport equation and has  $\phi|_{\Gamma_{-}} = \phi_{-}$ .

Let  $\phi_+ = \phi|_{\Gamma_+}$ . The map  $\mathcal{A} : \phi_- \longmapsto \phi_+$  is called the *Albedo operator*. The inverse problem is to calculate  $\sigma$  and  $\kappa$  from  $\mathcal{A}$ .

# 2 Now we do it Discretely!

**Definition 2.1** Let  $G = (V, V_B, E)$  be a finite directed graph with boundary, and with the following additional conditions.

- 1. Each boundary node  $p \in V_B$  has degree one.
- At each interior node p there is a bijection in(p) → out(p). The image of an incoming edge e is denoted e<sup>+</sup> and the image of an outgoing edge f is denoted f<sup>-</sup>. Note that this implies that each interior node has even degree.

#### Then G is said to be a **Transport Graph**.

Let in(p) denote the set of edges incoming at the node p and let out(p) denote the set of edges outgoing at node p. If P is a set of nodes in G, then  $in(P) = \bigcup_{p \in P} in(p)$  and similarly for out(P). Thus  $in(V_B)$  is the set of all edges which have no successor, and  $out(V_B)$  is the set of all edges which have no predecessor. The sets  $out(V_B \text{ and } in(V_B)$  take the place of  $\Gamma_-$  and  $\Gamma_+$  respectively.

The relevant functions for the discrete transport equation are represented on the graph as follows:

- The flux  $\phi: E \to \mathbf{R}^+$  is an *edge* function.  $\phi(e)$  is interpreted as giving the flux along the edge e in the direction that e points.
- The absorption coefficient is a function  $\sigma : V \to (0, 1)$ , where  $\sigma(p)$  is now interpreted as the probability that a particle coming into an interior node p along any edge will be absorbed before it leaves. We will need  $\sigma$  to be nonzero in order to prove the uniqueness of the solution to the forward problem.
- The collision kernel is a set of functions  $\{\kappa_p : out(p) \times in(p) \to [0, \delta) | \forall p \in V\}$ , (for  $\delta$  sufficiently small as will be described shortly) defined at each interior node  $p \in V$ , and satisfying the condition that  $\kappa_p(e^+, e) = 0, \forall p \in V$ ,  $\forall e \in in(p)$  since direct transmission is mediated by absorption rather than collision. We have the interpretation that  $\kappa_p(e, f)$  is the probability that a particle entering node p along edge f will leave along the edge e.

Replacing each term in the continuous equation with its discrete analog, one obtains

$$-\left[\phi(e^+) - \phi(e)\right] - \sigma(p)\phi(e) + \sum_{g \in in(p)} \kappa_p(e^+, g)\phi(g) = 0.$$

However, this equation does not correctly conform to the probabilistic interpretation of  $\sigma$ , so we modify it by replacing  $\sigma(p)$  with: (absorption probability) + (total collision probability for particle incoming along edge e). Therefore, the correct equation is

$$-\left[\phi(e^+) - \phi(e)\right] - \left[\sigma(p) + \sum_{f \in out(p)} \kappa_p(f, e)\right] \phi(e) + \sum_{g \in in(p)} \kappa_p(e^+, g)\phi(g) = 0,$$

which may be written in a more compact form as,

$$\phi(e^{+}) = \sum_{f \in in(p)} \tau_p(e^{+}, f) \phi(f).$$
(2)

Here  $\tau_p$  is the transport function at node p. Its values are given by

$$\tau_p(e^+, f) = \begin{cases} 1 - \sigma(p) - \sum_{g \in out(p)} \kappa_p(g, f) & f = e \\ \kappa(e^+, f) & f \neq e \end{cases}$$
(3)

The value of  $\tau_p(e^+, f)$  can be interpreted as the probability that a particle entering node p along the edge f will leave p along the edge  $e^+$ . For eq. 3 to make sense under this interpretation, it is apparent that the entries in the collision kernel must be sufficiently small. This consideration places an upper bound on  $\delta$ . We will thus assume that  $\delta$  is small enough so that the values of  $\tau_p$ are all in the range [0, 1). In the continuous setting there is a similar constraint on  $\kappa$  for there to be a well posed forward problem.

**Definition 2.2** A transport network  $\Gamma$  is pair  $(G, \tau)$ , where G is a transport network, and  $\tau$  is a transport function (which can be decomposed into an absorption coefficient  $\sigma : V \to [0,1]$  and a collision kernel  $\kappa$  (with  $\delta$  sufficiently small).

Number the elements of in(p) as  $e_1, e_2, \ldots, e_n$ . We form a matrix  $T_p$ , called the *transport matrix at node* p, with entries  $[T_p]_{ij} = \tau_p(e_i^+, e_j)$ . Let  $\phi$  be a nonnegative function on the edges of  $\Gamma$  and let  $\Phi_p^{in}$  denote the column vector  $[\phi(e_1), \phi(e_2), \ldots, \phi(e_n)]^T$ ; define  $\Phi_p^{out}$  similarly. To say that  $\phi$  satisfies the transport equation is to say that  $\forall p \in V$ ,

$$\Phi_p^{out} = T_p \Phi_p^{in}.\tag{4}$$

In this case we say that  $\phi$  is a  $\tau$ -flow.

### 2.1 The Discrete Forward Problem

Given transport network  $\Gamma$  and a nonnegative function  $\psi_{-}$  defined on  $out(V_B)$ , the forward problem is to find a  $\tau$ -flow  $\phi$  such that  $\phi|_{out(V_B)} = \psi_{-}$ . Equation 2 gives exactly one linear equation for each edge with an unknown flux. Putting these together results in a system of n equations with n unknowns, where n is the number of edges with un-imposed fluxes. This system is of the form Qx = b. **Lemma 2.1** The matrix Q has the following properties:

- 1. Each diagonal entry  $q_{ii}$  of Q is 1.
- 2. The non-diagonal entries  $q_{ij}$  of Q all satisfy  $-1 < q_{ij} \leq 0$ .
- 3. In each row or column there is at most a single non-diagonal entry that is larger than  $\delta$  in magnitude.

**Proof:** Property (1) follows directly from the form of eq. 2. Property (2) also follows directly from eq. 2 combined with the fact that the values of the transport function are always in the range [0, 1). To prove property (3), first note that  $\tau_p(e, f) < \delta$  if f is not the successor of e. From eq. 2, in each row of Q there is at most a single non-diagonal entry that is greater than  $\delta$  because each edge has only a single predecessor and only the successor-predecessor term can be greater than  $\delta$ . Similarly, each edge has at most one successor, so by the same reasoning in each column of Q there is at most a single non-diagonal entry that is greater than  $\delta$ .  $\Box$ 

**Theorem 2.1** Let  $\sigma_0$  be the minimum value of  $\sigma$ . If  $\delta < \sigma_0/(n-2)$  then Q is diagonally dominant and hence nonsingular.

**Proof:** Computing a row sum of Q in the *i*th row,

$$\sum_{j=1}^{n} q_{ij} = q_{ii} + \sum_{j=1, j \neq i}^{n} q_{ij} > 1 - (n-2)\delta - (1-\sigma_0) = \sigma_0 - (n-2)\delta$$

And clearly if  $\delta < \sigma/(n-2)$  then this quantity is positive. A nearly identical argument shows that the column sums are all positive.  $\Box$ 

**Corollary 2.1** Given a transport network  $\Gamma$ ,  $\exists \delta$  such that if  $\forall p \in V$ ,  $\|\kappa_p\| < \delta$  then there is a solution to the forward problem, and this solution is unique.

### 2.2 The Discrete Inverse Problem

Given  $\psi_{-}$  and assuming that the forward problem has a unique solution, we define  $\psi_{+} = \phi|_{in(V_B)}$ . The Albedo operator is then the linear map

$$\mathcal{A}:\psi_{-}\longmapsto\psi_{+}.$$

The inverse problem is to recover information about  $\sigma$  and  $\kappa$  from  $\mathcal{A}$ .

### References

 Plemen Stefanov, Gunther Uhlmann, "Optical Tomography in two dimensions", 2002. Preprint available at www.math.purdue.edu/~ stefanov