

1. Prove the following basic facts about infinitesimal rigidity.
 - (a) *Replacement Lemma*: Let $G = \langle V, E \rangle$ be a d -dimensional framework, and let G' be an induced subframework on k joints v_1, \dots, v_k of G . Assume further that G is infinitesimally rigid. Show that if G' is replaced by a new subframework G'' on joints v_1, \dots, v_k that is infinitesimally rigid as a framework in the affine space spanned by v_1, \dots, v_k , then the modified framework, $\tilde{G} = (G \setminus G') \cup G''$, is infinitesimally rigid in the d -space.
 - (b) *Cone Lemma*: Let $G = \langle V, E \rangle$ be a framework in \mathbb{R}^{d+1} such that $H := \text{Aff}(V)$ is a hyperplane in \mathbb{R}^{d+1} . For $u \in \mathbb{R}^{d+1} \setminus H$ define $G^*\{u\} := \langle V', E' \rangle$, where $V' = V \cup \{u\}$ and $E' = E \cup \{uv : v \in V\}$ (i.e., $G^*\{u\}$ is a cone over G with apex u). Show that G is infinitesimally rigid in H if and only if $G^*\{u\}$ is infinitesimally rigid in \mathbb{R}^{d+1} .
Hint for part (b): what is the relationship between the stress spaces of G and G^* ?
2.
 - (a) Show that if to a d -dimensional infinitesimally rigid framework with more than d joints a new joint $v \in \mathbb{R}^d$ is added together with d bars incident with v that span \mathbb{R}^d , then the new framework is also infinitesimally rigid.
 - (b) Show that a 1-dimensional framework with all joints distinct is infinitesimally rigid if and only if the underlying graph is connected. (**Hint**: start with a tree.)
 - (c) A framework is called a *triangulated polygon* if its underlying graph can be drawn in a plane as a convex n -gon ($n \geq 3$) with a maximal set of non-crossing edges inside it.
 Show that any framework $G = \langle V, E \rangle$ in the plane which is a triangulated polygon with no triangle of bars collinear is infinitesimally rigid, but deleting any bar from G makes it infinitesimally flexible.
3. Let $G = ([n], E)$ be a graph on n vertices (considered as an abstract graph). A map $\psi : [n] \rightarrow \mathbb{R}^3$ is called a *3-embedding* of G into \mathbb{R}^3 . We identify the set of all 3-embeddings of G with \mathbb{R}^{3n} via $\psi \mapsto (v_1, \dots, v_n) = (\psi(1), \dots, \psi(n)) \in \mathbb{R}^3 \times \dots \times \mathbb{R}^3 \cong \mathbb{R}^{3n}$. Each 3-embedding ψ of G defines a 3-dimensional framework whose joints are $\psi(1), \dots, \psi(n)$ and whose bars are the elements of E . A 3-embedding of G into \mathbb{R}^3 is *infinitesimally rigid* (*flexible*, resp.) if the corresponding framework is infinitesimally rigid (*flexible*, resp.).

Prove the following result due to Gluck (1974): the set of infinitesimally rigid 3-embeddings of the graph of a 3-dimensional simplicial polytope with n vertices is open and dense in \mathbb{R}^{3n} .

Directions: Show first that a 3-embedding ψ (whose joints affinely span \mathbb{R}^3) is infinitesimally flexible if and only if the stress matrix $\mathcal{R}(\psi)$ of the corresponding framework satisfies the following polynomial equation: $\sum_B \det(B)^2 = 0$, where the sum is over all $(3n-6) \times (3n-6)$ submatrices of A . (**Hint**: How many edges does G have? What can you say about the rank of A ?) Conclude that the set of infinitesimally flexible 3-embeddings of G is an algebraic variety, and hence its complement in \mathbb{R}^{3n} is either empty or is open and dense. Why is the complement non-empty?