

Your Name

Your Signature

Student ID #

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	1.	2.	3.	4.	5.	Form	Bonus	Σ
Points								
Possible	20	16	6	6	12	3	(6)	63

- No books are allowed. You may use a calculator.
- Place a box around to each question.
- If you need more room, use the back of each page and indicate to the grader how to find the logic order of your answer.
- Raise your hand if you have questions or need more paper.
- For TRUE/FALSE problems, you just need to cross the right box. For each correct answer, you will get 1 point, for each incorrect answer, -1 point is added. For no answer you will get zero points. In each subsection of the TRUE/FALSE part, you can never get less than zero points.
- In order to receive points for an accurate form, solutions to systems must be written as a set, vectors need to be underscored to distinguish them from scalars and between equivalent matrices there is no equality sign but an arrow.

Do not open the test until everyone has a copy and the start of the test is announced.

GOOD LUCK!

1.)(20 points) For each correct answer in the TRUE/FALSE part, you will get 1 point, for each incorrect answer, there will be one point subtracted, i.e. you get -1 point. For no answer, you get 0 points. You can not get less than 0 points out of one subproblem

(a)	Cross the right box for the statements about linear systems.	
	A homogeneous system with 5 variables and 3 equations always has infinitely many solutions.	<input type="checkbox"/> TRUE <input type="checkbox"/> FALSE
	A linear system with 5 variables and 3 equations always has infinitely many solutions.	<input type="checkbox"/> TRUE <input type="checkbox"/> FALSE
	If a linear system of the form $A\mathbf{x} = \mathbf{b}$, with A an (n, m) -matrix and \mathbf{b} a vector in \mathbb{R}^n , has a solution, then this solution can be written as a vector in \mathbb{R}^m .	<input type="checkbox"/> TRUE <input type="checkbox"/> FALSE
	Let \mathbf{u}_i be vectors in \mathbb{R}^n . Then the linear system with augmented matrix $[\mathbf{u}_1 \ \mathbf{u}_2 \ \dots \ \mathbf{u}_n \mathbf{u}_2 + \mathbf{u}_3]$ has $[0, 1, 1, \dots, 0]^t$ as a solution.	<input type="checkbox"/> TRUE <input type="checkbox"/> FALSE
	A homogeneous system is always consistent.	<input type="checkbox"/> TRUE <input type="checkbox"/> FALSE
	The trivial solution is always a solution to a linear system.	<input type="checkbox"/> TRUE <input type="checkbox"/> FALSE
	If $A\mathbf{x} = \mathbf{0}$ has only one solution, this must be the trivial solution.	<input type="checkbox"/> TRUE <input type="checkbox"/> FALSE
(b)	Cross the right box for the statements about linear independence and span.	
	$\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\} \subseteq \mathbb{R}^3$ spans \mathbb{R}^3 .	<input type="checkbox"/> TRUE <input type="checkbox"/> FALSE
	$\text{span}\{\mathbf{u}_1, \mathbf{u}_2\} = \text{span}\{\mathbf{u}_1 + \mathbf{u}_2, \mathbf{u}_1 - \mathbf{u}_2\}$	<input type="checkbox"/> TRUE <input type="checkbox"/> FALSE
	If \mathbf{u}_1 and \mathbf{u}_2 are linearly dependent, then there exists a scalar $c \in \mathbb{R}$ such that $\mathbf{u}_1 = c\mathbf{u}_2$ or $\mathbf{u}_2 = c\mathbf{u}_1$.	<input type="checkbox"/> TRUE <input type="checkbox"/> FALSE
	If $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ spans \mathbb{R}^3 , then so does $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$, for any vector $\mathbf{u}_4 \in \mathbb{R}^3$.	<input type="checkbox"/> TRUE <input type="checkbox"/> FALSE
(c)	Cross the right box for the statements about linear systems and linear independence.	
	If A is an (n, m) -matrix and \mathbf{b} a vector in \mathbb{R}^n and the columns of A are linearly independent, then the linear system $A\mathbf{x} = \mathbf{b}$ cannot have free variables.	<input type="checkbox"/> TRUE <input type="checkbox"/> FALSE
	A set of one vector is always linearly independent.	<input type="checkbox"/> TRUE <input type="checkbox"/> FALSE
	If $\mathbf{u}_1, \mathbf{u}_2$, and \mathbf{u}_3 are pairwise linearly independent, then $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is also linearly independent.	<input type="checkbox"/> TRUE <input type="checkbox"/> FALSE
	A homogeneous system with 3 variables and 3 equations has exactly one solution.	<input type="checkbox"/> TRUE <input type="checkbox"/> FALSE
(d)	Cross the right box for the statements about linear homomorphisms	
	If A is an (n, m) -matrix, then the linear homomorphism that maps a vector \mathbf{u} to $A\mathbf{u}$ has \mathbb{R}^m as domain and \mathbb{R}^n as codomain.	<input type="checkbox"/> TRUE <input type="checkbox"/> FALSE
	Any linear homomorphism maps the zero vector of the domain to the zero vector of the codomain.	<input type="checkbox"/> TRUE <input type="checkbox"/> FALSE
	Let T be a homomorphism. Then T is surjective if and only if the zero vector of the domain is the only vector that is mapped to the zero vector of the codomain.	<input type="checkbox"/> TRUE <input type="checkbox"/> FALSE
	A linear homomorphism $T : \mathbb{R}^{12} \rightarrow \mathbb{R}^7$ cannot be injective, but it can be surjective.	<input type="checkbox"/> TRUE <input type="checkbox"/> FALSE
	The function that sends every vector of \mathbb{R}^n to the zero vector of \mathbb{R}^m is a linear homomorphism.	<input type="checkbox"/> TRUE <input type="checkbox"/> FALSE

2.(1+3+2+4+1+1+1+3) Consider the following linear system:

$$\begin{aligned}2x_1 + 3x_2 - x_3 &= -2 \\4x_1 + 5x_2 - 3x_3 &= -2 \\-x_1 + 3x_2 + 5x_3 &= -8\end{aligned}$$

(a) Is this an inhomogeneous or a homogeneous system?

(b) Before actually solving the system, what are the possible numbers of solutions?

(c) What is the corresponding augmented matrix?

(d) Perform the Gauss algorithm to put this matrix into echelon form.

(e) Identify the leading variables.

(f) Are there free variables? If so, identify them.

(g) Based on your answer in (f), what is the number of solutions to that system?

(h) Solve the system. Write the solution in vector form (i.e. $\mathbf{x} = \mathbf{v} + s\mathbf{w}$, where you need to specify \mathbf{v} and \mathbf{w}). Write a proper solution set with declaring all possible parameters.

3.(4+2)

(a) Determine h , so that the following vectors span \mathbb{R}^3 :

$$\begin{bmatrix} 1 \\ -3 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ h \end{bmatrix}, \begin{bmatrix} -3 \\ 1 \\ 2 \end{bmatrix}$$

(b) If you choose some h so that the three vectors do span \mathbb{R}^3 , apply the Big Theorem and conclude the right statement about linear independence of these vectors.

4.(3+3)

(a) Write down the precise definition of ‘Linear Independence’ of $\{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_m\} \subseteq \mathbb{R}^n$. The definition must be written in whole sentences and must include the expressions ‘linear independent, equation, solution, only’.

(b) Let \mathbf{u} be a vector in \mathbb{R}^k and let A be an (m, n) -matrix. How must k be chosen so that the matrix vector product $A\mathbf{u}$ is defined? In which Euclidean space does $A\mathbf{u}$ lie?

5.(3+4+3+2) Consider the following linear homomorphism (keep an eye on the order of the vector coefficients in the image):

$$T : \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} \rightarrow \begin{bmatrix} 2u_3 - u_1 + 2u_2 \\ u_1 + u_2 \\ 3u_1 - 5u_2 - 3u_3 \end{bmatrix}.$$

(a) Find the corresponding matrix A , such that $T(\mathbf{x}) = A\mathbf{x}$ for all $\mathbf{x} \in \mathbb{R}^3$.

(b) Find the kernel of T . (The answer is a set of vector(s)!)

(c) Based on your answer in (b), is T injective? Justify your answer.

(d) Find the image of the vector

$$\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$$

under T .