

Class Notes, Math 554, Autumn 2012

Lecture XXI: The Gram-Schmidt Process and the QR factorization; Least Squares

The Gram-Schmidt algorithm started on the columns of a matrix A will yield the QR factorization.

Proposition 1. Given $A \in \mathcal{M}_{m,n}(\mathbb{C})$, $m \geq n$, there exists a unitary matrix $Q \in \mathcal{M}_m(\mathbb{C})$ and an upper triangular matrix $R \in \mathcal{M}_{m,n}(\mathbb{C})$ such that $A = QR$. (Note that for a rectangular matrix to be upper triangular it means that all entries with indices (i, j) , $i > j$ are 0.)

Proof. Suppose first that the columns of A are independent. The first n columns of Q , \tilde{Q} , will be obtained as a result of the Gram-Schmidt process on A . The same process also yields an upper triangular matrix \tilde{R} which is square (n times n).

Denote $Q = [\tilde{Q}, Q']$ a completion of \tilde{Q} to full orthonormal basis and by $R = \begin{bmatrix} \tilde{R} \\ 0 \end{bmatrix}$ the completion of R to $m \times n$ by adding $m - n$ rows of zeros.

Then $A = QR$.

Now, if the columns of A are dependent, one can continue the Gram-Schmidt process by setting appropriate q s to 0. For example, if a_k is a linear combination of the previous columns, which will be discovered as p_k will be 0, set $a_k = 0$ and also all $r_{kj} = 0$ — for $j \geq k$, and continue. The result will once again be a matrix \tilde{Q} with orthogonal columns, some of which are unit-length and some which are 0, as well as an upper triangular matrix \tilde{R} with some zero rows. Eliminate all zero columns and correspondingly zero rows from \tilde{Q} and \tilde{R} ; complete $Q = [\tilde{Q}, Q']$ to a full unitary matrix, “padd” \tilde{R} with 0 rows to get R , and once again $A = QR$. \square

Corollary 1. From the Gram-Schmidt process followed by a potential “pruning” of zero columns and rows, one can obtain the “condensed” QR factorization $A = \tilde{Q}\tilde{R}$, where $\tilde{Q} \in \mathcal{M}_{m,r}$ and $\tilde{R} \in \mathcal{M}_{r,n}$, the former having orthonormal columns, and the latter being upper triangular. The parameter r here can take the place of either n (if no pruning) or the rank of A (if pruning)

Remark 1. The following are easily seen to be true:

- We can choose R to have non-negative diagonal entries.
- If A is full rank, R can in fact be chosen to have positive diagonal entries. In this case the condensed QR factorization is unique.
- If A is full rank, the only non-uniqueness in the condensed QR form derives from the possibility to attach phases to the columns of \tilde{Q} . In other words, letting $D = \text{diag}(e^{i\theta_1}, \dots, e^{i\theta_n})$ be a generic notation for diagonal matrices of phases, for any two factorizations $Q_1 R_1 = Q_2 R_2$ of A , there exists a D such that $Q_1 = Q_2 D^*$ and $R_1 = D R_2$.

Remark 2. If we replace \mathbb{C} with \mathbb{R} , then Q becomes orthogonal rather than unitary, and R is real. All the rest holds.

One last thing that needs to be mentioned: Modified Gram-Schmidt (MGS) is relatively fast and stable. There are, however, more stable algorithms (and arguably better, computationally) for calculating QR; the two most important ones are the Householder reflector one (mentioned in the homework), and the Givens rotation one.

0.1 Using QR to solve Least Squares

A good part of classical numerical linear algebra (NLA) is concerned with solving the equation $Ax = b$ (... the joke amongst NLA people being that the rest of it is solving $Ax = \lambda x$.) Nevertheless, as we know, if $b \notin \mathcal{R}(A)$, no such solution exists. What can one do then? The answer is to change the question: rather than *solve*, focus on *approximate*.

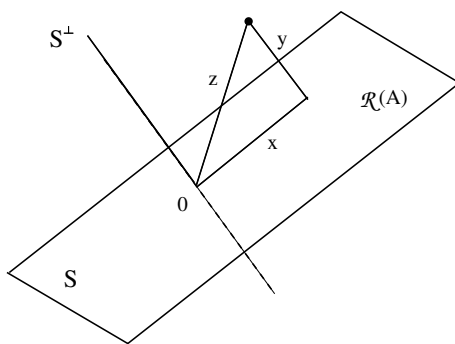
The “Least Squares” approximation problem is to minimize $\|Ax - b\|_2$, or equivalently, $\|b - Ax\|_2$, for given A and b (naturally, if $Ax = b$ does have solutions, then the minimization problem reverts to finding a/the solution). Equivalently, and more simply, we choose to minimize the square of this quantity, namely $\|Ax - b\|_2^2$.

Generally speaking, the reason for choosing the 2-norm is because it has an associated inner product, which makes things a lot less complicated, by transforming the problem into a geometry one: finding the projection of b onto $\mathcal{R}(A)$. This is illustrated by the following (not very hard) theorem.

Theorem 1. (The Projection Theorem, finite dimensional version) *Let V be an inner-product space, and $S \in V$ be a finite dimensional subspace. Then*

- 1) $V = S \oplus S^\perp$; that is, $\forall z \in V, \exists! x \in S, y \in S^\perp$, such that $z = x + y$. Incidentally, $x = P_S z$, $y = P_{S^\perp} z = (I - P_S)z$.
- 2) Given $z \in V$, the x in 1) is the unique element of S which satisfies $z - x \in S^\perp$.
- 3) Given $z \in V$, the x in 1) is the unique element of V realizing the minimum $\min_{s \in S} \|z - s\|_2^2$. The norm here is the one induced by the inner product.

Proof. The proof is in the picture.



- 1) Let $\{\phi_1, \dots, \phi_k\}$ be an orthonormal basis for S . Let $x = \sum_{i=1}^k \langle \phi_i, z \rangle \phi_i$, and let $y = z - x$. Then trivially $x \in S$, and

$$\langle \phi_i, y \rangle = \langle \phi_i, z \rangle - \langle \phi_i, x \rangle = 0,$$

so $y \in S^\perp$. Uniqueness for both x and y follows from the fact that $S \cap S^\perp = \{0\}$.

2) This is a restatement of 1).

3) Note that for $s \in S$, $z - s = x - s + y$, and since $x - s \in S$ and $y \in S^\perp$, we can write by the Pythagorean Theorem

$$\|z - s\|_2^2 = \|x - s\|_2^2 + \|y\|_2^2,$$

so clearly the LHS is minimized when $x = s$.

□

0.1.1 Solving Least Squares with QR

We start with this, because it is the most widely used algorithm for solving Least Squares. Recall that we want to minimize $\|b - Ax\|_2^2$ for some matrix $A \in \mathcal{M}_{m,n}$ and vector $b \in \mathbb{C}^n$.

Assume wlog $\text{rank}(A) = n$, write $A = QR$, the full QR decomposition of A , and let $A = \tilde{Q}\tilde{R}$ be the condensed QR decomposition of A (so that \tilde{R} has no zero rows, and \tilde{Q} has orthonormal columns), and rearrange $Q = [\tilde{Q}, Q']$, $R = \begin{bmatrix} \tilde{R} \\ 0 \end{bmatrix}$.

(If A is not full rank, one can still do the condensed decomposition of A , find a “solution” x' , and then “padd” it appropriately with zeros.)

Write

$$\|b - Ax\|_2^2 = \|QRx - b\|_2^2 = \|Q^*(QRx - b)\|_2^2,$$

since the 2-norm is invariant under unitary multiplication, and thus

$$\|b - Ax\|_2^2 = \|Rx - Q^*b\|_2^2 = \left\| \begin{bmatrix} \tilde{R}x - \tilde{Q}^*b \\ (Q')^*b \end{bmatrix} \right\|_2^2 = \|\tilde{R}x - \tilde{Q}^*b\|_2^2 + \|(Q')^*b\|_2^2.$$

Thus the minimization problem is transformed into finding the minimum of $\|\tilde{R}x - \tilde{Q}^*b\|_2^2$, but, since we can choose \tilde{Q} so that \tilde{R} has all positive entries on the diagonal, \tilde{R} is invertible, and $\tilde{R}x = \tilde{Q}^*b$ is solvable.

Thus, the minimum is obtained uniquely at the point for which $\tilde{R}x = \tilde{Q}^*b$.

Note that we only need matrix multiplication and computing QR to solve; we will see later why this is important.