## Lecture 11-8: Roots and root systems

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We continue our discussion of roots from last time. Let G be a connected algebraic group with maximal torus $T$ and let $W=N_{G}(T) / Z_{G}(T)$ be the Weyl group of $T$. Also let $B$ be a Borel subgroup of $G$.

## Proposition 7.1.5, p 115

Assume that $G$ is non-solvable and $\operatorname{dim} T=1$. Then $W$ has order 2 and $\operatorname{dim} G / B=1$.

## Proof.

First note that $W$ has order at most 2 , since it acts faithfully by automorphisms on $X=X^{*}(T) \cong \mathbb{Z}$ and $\mathbb{Z}$ has only two automorphisms. Now fix an isomorphism $\lambda: T \rightarrow \mathrm{G}_{m}$. Let $B$ be a Borel subgroup containing $T$. Let $\phi: G \rightarrow G L(V), v \in V$ be a representation and a vector in it with the properties of Theorem 5.5.3 for $G$ and $B$; we may assume that $V$ is spanned by the images $\phi(x) \vee$ as $x$ runs through $G$. Then $\phi$ defines an isomorphism from $G / B$ onto a closed subvariety $Y=G . \mathbf{k} v$ of $\mathbb{P} V$; we identify $G / B$ with this closed subvariety. Choose a basis $e_{1}, \ldots, e_{n}$ of $V$ consisting of weight vectors for the induced representation $\rho$ of $G_{m}$ on it, so that we have $\rho(a)=a^{m_{i}} e_{i}$ for $a \in \mathbf{k}^{*}, 1 \leq i \leq n$.

## Proof.

(continued) Assume that the indices are arranged so that $m_{1} \geq \ldots \geq m_{n}$. Write a point $x^{*} \in Y$ in homogeneous coordinates as ( $x_{1}, \ldots, x_{n}$ ). If $i, j$ are respectively the largest and smallest indices with $x_{i}, x_{j} \neq 0$, then an easy argument shows that $\mathbf{k} e_{i}, \mathbf{k} e_{j} \in Y$, where $e_{i}, e_{j}$ are the ith and $j$ th unit coordinate vectors; the morphism $\mathrm{G}_{m} \rightarrow \mathbf{P} V$ arising from the action of $T$ extends in two ways to a map from $A^{1}$ to $\mathbf{P} V$, with the extra point in its image lying in $Y$ in both cases. You can think of $\mathbf{k} e_{i}$ as $\lim _{a \rightarrow \infty} \phi(a)(\mathbf{k} x)$, while $\mathbf{k} e_{j}=\lim _{a \rightarrow 0} \phi(a)(\mathbf{k} x)$. Running over all the points of $Y$, we conclude that $T$ has at least two fixed points in $G / B$, and order of $W$ is exactly 2 .

## Proof.

(continued) Letting $i, j$ be the indices arising in the last paragraph, so that $\mathbf{k} e_{i}, \mathbf{k} e_{j}$ are fixed points of $T$ in $G / B$, we find that the points in $Y$ with jth coordinate 0 form a closed $T$-stable subset $\Sigma$ which is nonempty. If any component of $\Sigma$ had dimension at least 1 , then the above argument would show that that component would include at least two fixed points of $T$, together with the one $\mathbf{k} e_{j}$ that it already has, a contradiction; so $\Sigma$ is finite. The $j$ th coordinate function $f$ on a suitable open neighborhood of $e_{i}$ takes the value 0 there and $f^{-1}(0)$ is finite. The second assertion now follows from Corollary 5.2.7, since the dimension of $G / B$ cannot be 0 .

Returning now to the general case (so that the rank of $G$ is arbitrary), let $\alpha \in P^{\prime}$; we know that $W_{\alpha}=W\left(G_{\alpha}\right) \subset W$ has order 2 . Choose $n_{\alpha} \in N_{G_{\alpha}}(T), n \notin Z_{G_{\alpha}}(T)$ and let $s_{\alpha}$ be the image of $n_{\alpha}$ in $W$. Denote by $X$ the group hom $(X, \mathbb{Z})$ of cocharacters of $X=X^{*} G$; this group is also isomorphic to $\mathbb{Z}^{n}$ and there is a nondegenerate pairing $\langle\cdot, \cdot\rangle$ between $X$ and $\check{X}$. Identify $X, \check{X}$ with subgroups of $V=\mathbb{R} \otimes X, \check{V}=\mathbb{R} \otimes \check{X}$, with $\langle\cdot, \cdot\rangle$ again denoting the pairing between $V$ and $\check{V}$. The action of $W$ on $X$ naturally extends to a linear action on $V$.

Following p .116 in the text, we now introduce a positive definite symmetric bilinear form ( $\cdot, \cdot$ ) on $V$ that is invariant under $W$ : starting with any symmetric positive definite bilinear form $f$ on $V$, replace $f(x, y)$ by $(x, y)=\sum_{w \in W} f(w \cdot x, w \cdot y)$. The $s_{\alpha}$ are then reflections in the Euclidean space $V$ : given $\alpha, s_{\alpha}$ fixes the hyperplane orthogonal to $\alpha$ and sends $\alpha$ to its negative, whence $s_{\alpha}(v)=v-\frac{2(v, \alpha)}{(\alpha, \alpha)} \alpha$. Identify $\check{V}$ with the dual of $V$, or with $V$ itself, using the form $(\cdot, \cdot)$, Using this idenitification set $\check{\alpha}=\frac{2 \alpha}{(\alpha, \alpha)} \in \check{V}$ and call $\check{\alpha}$ the coroot of $\alpha$. Then $\left.s_{\alpha}(v)=v-\langle v, \check{\alpha}\rangle \alpha,\langle\alpha, \check{\alpha}\rangle=26\right)$. The Weyl group $W$ turns out to be generated by the reflections $s_{\alpha}$ as $\alpha$ runs over $P^{\prime}$ (Theorem 7.1.9, p. 116).

The upshot is that we can attach to $G$ a root datum (7.4.1, p. 124). This consists of the quadruple $(X, R, \check{X}, \check{R})$, where $X, \check{X}$ are free abelian groups of finite rank, in duality by a pairing $\langle\cdot, \cdot\rangle$ taking values in $\mathbb{Z}, R$ (denoted earlier by $P^{\prime}$ ) and $\check{R}$ are finite subsets of $X$ and $\check{X}$, respectively, equipped with a bijection $\alpha \mapsto \check{\alpha}$ from $R$ to $\check{R}$. Defining $s_{\alpha}(x)=x-\langle x, \check{\alpha}\rangle \alpha, s_{\check{\alpha}}(y)=y-\langle\alpha, y\rangle \check{\alpha}$ for $\alpha \in R, x \in X, y \in \check{X}$, we have the key properties that $\langle\alpha, \check{\alpha}\rangle=2$ for $\alpha \in R$ and $s_{\alpha} R=R, s_{\check{\alpha}} \check{R}=\check{R}$ (properties (RD1) and (RD2) on p. 124). Here of course $X$ is the character group of a maximal torus of $G, R$ the set of its roots, $\check{X}$ the cocharacter group, and the remaining notations are as defined above. The root datum is independent of the choice of maximal torus $T$ since any two such are conjugate.

We identify the root data $(X, R, \check{X}, \check{R}),(Y, S, \check{Y}, \check{S})$ whenever there is a linear isomorphism $\phi: X \rightarrow Y$ such that $\phi$ maps $\check{X}$ onto $\check{Y}, R$ onto $S, \check{R}$ onto $\check{S}$, and $\check{\alpha}(\beta)=(\phi \alpha)(\phi \beta)$ for all $\alpha, \beta \in R$; notice that we are not requiring that the positive definite form $(\cdot, \cdot)$ introduced above on $\mathbb{R} \otimes X$ be preserved by $\phi$. The root data $(X, R, \check{X}, \check{R})$ arising from algebraic groups have the further property of being reduced (see p. 125), meaning that $c \alpha \notin R$ whenever $\alpha \in R$ and $c \in \mathbf{k}$ is different from $\pm 1$; we will prove this later. If for example $X$ and $\check{X}$ both have rank one, so that each of these identifies with $\mathbb{Z}$, then it is easy to check that there are just two reduced root data up to isomorphism, one with roots $\pm 2$ and coroots $\pm 1$, the other with roots $\pm 1$ and coroots $\pm 2$. These data correspond to the groups $S L_{2}(\mathbf{k})$ and $P S L_{2}(\mathbf{k})$, respectively.

Letting $Q$ be the subgroup of $X$ generated by $R$ and denoting $\mathbb{R} \otimes Q$ by $V$, regarded as a Euclidean space equipped with the usual dot product, we see that $R$ satisfies the axioms of a root system; that is, (RS1) $R$ is finite, does not contain 0 , and spans $V$; (RS2) if $\alpha \in R$ then the reflection $s_{\alpha}$ stabilizes $R$, where $s_{\alpha}(\beta)=\beta-\frac{2(\beta, \alpha)}{(\alpha, \alpha)} \alpha$; (RS3) If $\alpha \in R$ then $\frac{2(\beta, \alpha)}{(\alpha, \alpha)} \in \mathbb{Z}$. (The last condition is sometimes called the crystallographic condition.). Root systems arising from reduced root data are also called reduced. The coroot $\check{\alpha}$ is defined to be $\frac{2 \alpha}{(\alpha, \alpha)}$ for $\alpha \in R$.

We now return to the salt mines for little longer, proving two more facts about non-solvable groups of rank one; we will then go beyond the text by sketching the classification of root systems and root data, which is purely combinatorial. For now let $G$ be non-solvable of rank one. Fix a Borel subgroup $B$ containing a maximal torus $T$, let $U=B_{u}$ be its unipotent radical and let $n \in N_{G}(T)$ represent the nontrivial element of the Weyl group $W$, so that $n t n^{-1}=t^{-1}$ for $t \in T$ and $n^{2} \in Z_{G}(T)$.

## Lemma 7.2.2, p. 117

- $G$ is the disjoint union of $B$ and UnB.
- $R(G)=\left(U \cap n U n^{-1}\right)^{0}$, where $R(G)$ is the solvable radical of $G$. - $\operatorname{dim} U / U \cap n U n^{-1}=1$.


## Proof.

Let $x \in G / B$ be the coset $B$. Then $n . x, x$ are the two distinct fixed points of $T$ in $G / B$; since $n^{-1} B n \neq B$ we have Un. $x \neq\{n . x\}$. We have seen that $\operatorname{dim} G / B=1$; it follows that the complement of Un.x is a finite set $S$. Since the torus $T$ normalizes $U$, it must permute this set $S$, whence it fixes all of its points. It follows that $S \subset\{x, n . x\}$. Since $x \notin U n . x, n . x \in U n . x$ we conclude that Un. $x=G / B-\{x\}$; the first assertion follows.

## Proof.

(continued) Since $U \cap n U n^{-1}$ is the isotropy group of $n . x$ in $U$, part (iii) follows from part (i) and Theorem 5.3.2 (ii). Since the normalizer of a proper closed connected subgroup of a unipotent group always has larger dimension than the subgroup, it must be that $\left(U \cap n U n^{-1}\right)^{0}$ is normal in $U$; since this group is also normalized by $T$ and $n$, it is normal in $G$. Part (ii) follows, since $R(G)$ cannot contain a torus.

