

I. Required problems.

1. (a) Show that the image of a Lie group homomorphism is a Lie subgroup.
 (b) Show that the images of one-parameter subgroups in a Lie group G are precisely the connected Lie subgroups of dimension less than or equal to 1.
 (c) If $H \subset G$ is the image of a one-parameter subgroup, show that H is Lie isomorphic to one of the following: the trivial group $\{e\}$, \mathbb{R} , or \mathbb{S}^1 .
2. Prove that there is exactly one nonabelian 2-dimensional Lie algebra up to isomorphism.
3. Let A and B be the following elements of $\mathfrak{gl}(2, \mathbb{R})$:

$$A = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}; \quad B = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}.$$

Compute the one-parameter subgroups of $\mathrm{GL}(2, \mathbb{R})$ generated by A and B .

4. (a) Suppose $A \in \mathrm{GL}(n, \mathbb{R})$ is of the form e^B for some $B \in \mathfrak{gl}(n, \mathbb{R})$. Show that A has a square root, i.e., a matrix $C \in \mathrm{GL}(n, \mathbb{R})$ such that $C^2 = A$.
 (b) Let

$$A = \begin{pmatrix} -1 & 0 \\ 0 & -2 \end{pmatrix}.$$

Show that the exponential map $\exp: \mathfrak{gl}(2, \mathbb{R}) \rightarrow \mathrm{GL}(2, \mathbb{R})$ is not surjective, by showing that A is not in its image.

II. Optional problems.

5. Let $\{\mathbf{i}, \mathbf{j}, \mathbf{k}\}$ denote the standard basis of \mathbb{R}^3 , and let $\mathbb{H} = \mathbb{R} \times \mathbb{R}^3$, with basis $\{1, \mathbf{i}, \mathbf{j}, \mathbf{k}\}$. Define a bilinear multiplication $\mathbb{H} \times \mathbb{H} \rightarrow \mathbb{H}$ by setting

$$\begin{aligned} 1q &= q1 = q \text{ for all } q \in \mathbb{H}, \\ \mathbf{ij} &= -\mathbf{ji} = \mathbf{k}, \\ \mathbf{jk} &= -\mathbf{kj} = \mathbf{i}, \\ \mathbf{ki} &= -\mathbf{ik} = \mathbf{j}, \\ \mathbf{i}^2 &= \mathbf{j}^2 = \mathbf{k}^2 = -1, \end{aligned}$$

and extending bilinearly. With this multiplication, \mathbb{H} is called the ring of *quaternions*.

- (a) Show that quaternionic multiplication is associative.

- (b) Show that the set \mathcal{S} of unit quaternions (with respect to the Euclidean metric) is a Lie group under quaternionic multiplication, and is Lie isomorphic to $SU(2)$.
 - (c) For any point $q \in \mathbb{H}$, show that the quaternions $\mathbf{i}q$, $\mathbf{j}q$, and $\mathbf{k}q$ are orthogonal to q . Use this to define a left-invariant frame on \mathcal{S} , and show that it corresponds under the isomorphism of (b) to the one defined in Example 9.6(c).
6. Look up the Cayley numbers, and use them to prove that \mathbb{S}^7 is parallelizable by mimicking as much as you can of Problem 4. Why do the unit Cayley numbers not form a Lie group?