#### NAME \_\_\_\_\_

Do all problems. No calculators. Points per problem listed on the back page.

### **Problem 1: Solving a linear equation**

(a) Solve Ax = y (if the equation is consistent) and write the general solution x in (vector) parametric form.

(b) Write a basis for the null space of A. **Basis** = \_\_\_\_\_

(c) What is the dimension of the range of A? **Dimension** = \_\_\_\_\_

(d) Is y in the span of the row vectors of A? Yes? No?

# Problem 2: Conclusions from echelon form.

In each case, we start with a matrix A and vector and tell what one will get by reducing the augmented matrix of the system Ax = y to echelon form. Answer the questions in each case using this information.

Α	у	Echelon form of augmented matrix
		of $Ax = y$ .
1 1 1 1	0	1 1 1 1 0
$A = 3 \ 3 \ 3 \ 2$	y = 1	0 0 0 -1 1
4 4 4 1	3	0 0 0 0 0

Page 3	
--------	--

Write the general solution for Ax = y in (vector) parametric form <b>Solution:</b>
What is the dimension of the null space of A? <b>Dimension =</b>
Write down a basis for the null space of A. <b>Basis</b> =
Is y in the range of A? Yes? No?
What is the dimension of the range of A? <b>Dimension</b> =
Write down a basis of the range of A. <b>Basis</b> =
Are the columns of A independent? Yes? No?

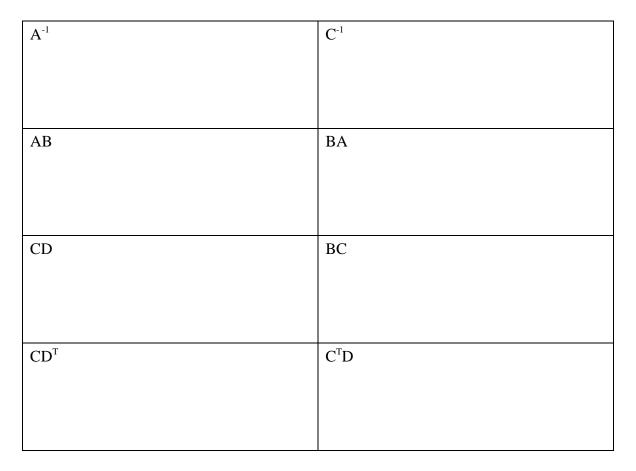
В	Z	Echelon form of augmented matrix			
		of $Bx = z$ .			
1 2	1	1 2 0			
2 4	1	0 0 1			
$B = \frac{1}{3} \frac{1}{6}$	z = 1	0 0 1 0 0 0			
4 8	1				
Write the general solution for $Bx = z$ in (vector) parametric form					
Solution:					
What is the dimension of the null sp	ace of B? Dim	ension =			
Write down a basis for the null spac	e of B <b>Basis =</b>				
while down a busis for the num space	<b>c</b> of <b>D</b> . <b>D</b> usis –				
Is y in the range of B? Yes? No?					
is y in the range of B? <b>Tes:</b> No:					
What is the dimension of the new set	f D 9 <b>D:</b>				
What is the dimension of the range of	DI B? Dimensio	)n =			
Write down a basis of the range of E	3. <b>Basis</b> =				
Are the columns of B independent?	Yes? No?				
	1				
С	Reduced row	echelon form of C.			
1 0 0	1 0 0				
C = 1  2  2	0 1 1				
1 0 0	0 0 0				
Is C invertible? Yes? No?	I				
	Ves? No?				
Are the columns of C independent? Yes? No?					
Write down a basis for the null space of C.					

# **Problem 3: Compute AB**

Compute the stated matrix products (if defined) for these matrices.

$$A = \begin{bmatrix} 1 & -1 \\ 2 & 1 \end{bmatrix}, B = \begin{bmatrix} 1 & 0 & 2 & 1 \\ 0 & 1 & -1 & 3 \end{bmatrix}, C = \begin{bmatrix} 2 & 2 \\ 1 \\ 3 \end{bmatrix}, D = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$$

Compute each of the following matrix products or other matrices (if defined):



### **Problem 4: Transpose and product**

Suppose M is a 4 x 3 matrix whose columns M1, M2, M3 are orthogonal and have lengths |M1| = 2, |M2| = 3, |M3| = 4. Tell what are the entries in the product M<sup>T</sup>M, as much and as precisely as possible from this information.

 $\mathbf{M}^{\mathrm{T}}\mathbf{M} =$ 

# Problem 5: Find the eigenvalues and eigenvectors

Find the eigenvalues and eigenvectors of matrix  $M = \begin{pmatrix} 0 & -2 \\ 2 & -4 \end{pmatrix}$ .

If possible, diagonalize M, i.e., write M = PDQ, where D is diagonal.

P =\_\_\_\_\_ D = \_\_\_\_\_ Q = \_\_\_\_\_

### Problem 6: Given the eigenvalues find the eigenvectors

	7	4	16
Given that <b>1 and 3 are the eigenvalues</b> of the matrix C =	2	5	8, find the
	-2	-2	-5
eigenvectors of this matrix.			

If possible, diagonalize C, i.e., write C = PDQ, where D is diagonal. You DO NOT need to compute the inverse of a matrix. If a matrix is the inverse of a known matrix, just write it as the inverse.

P =\_\_\_\_\_ D = \_\_\_\_\_ Q = \_\_\_\_\_

# **Problem 7: Compute orthogonal projections**

(a) Compute m = the projection of h on span(u). (The formula should be computed numerically, but you need not simplify fractions, etc., in your answer.)

(b) Compute g = **the projection of h on span(u, v).** (The formula should be computed numerically, but you need not simplify fractions, etc., in your answer.)

(c) In general, if X and Y are orthogonal vectors with |X| = 5 and |Y| = 12, compute, if possible with this information, |X-Y|.

|X-Y|=\_\_\_\_\_

#### Problem 8: Matrix of rotation by 120 degrees

(a) If T is the linear transformation of  $R^2$  that rotates the plane by 120 degrees. What is the matrix A of this transformation?

Hint:  $\cos 120 \text{ degrees} = -1/2$ ;  $\sin 120 \text{ degrees} = \frac{f_3}{2}$ .

(b) What is the matrix B of the inverse of T?

(c) Is the matrix A an orthogonal matrix? **Yes? No?** Show why.

(d) Is the matrix 2A an orthogonal matrix? **Yes? No?** Show why.

### **Problem 9: Least squares solution**

(a) Let A =  $\begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & and let y = 2 \\ 1 & 1 & 3 \end{bmatrix}$ . Then find the least squares "solution" of Ax = y.

Least squares solution = \_\_\_\_\_

(b) If u is the least squares solution of Ax = y, how is the vector Au related to y and A? Tell what this relation is supposed to be and check that it is true in this case.

Problem	Points Possible	Score
1	25	
2	50	
3	20	
4	10	
5	20	
6	20	
7	20	
8	15	
9	20	
Total	200	

Please leave this space for the grader.