

# Lecture 07

## Modeling Examples

## Review:

- General Solution to  $y' + p(t)y = f(t)$

$$y(t) = \underbrace{e^{-P(t)} \int e^{P(t)} f(t) dt}_{y_p(t)} + \underbrace{C e^{-P(t)}}_{y_h(t)}$$

where  $P(t) = \int p(t) dt$ .

- Special Case:  $y' + ky = e^{bt}$   $b \neq k$

Try  $y_p(t) = A e^{kt}$ :  $(b+k)A e^{kt} = e^{kt}$

$\Rightarrow A = \frac{1}{b+k}$  So  $y(t) = \frac{1}{b+k} e^{kt} + C e^{-kt}$

### Examples.

- Gen. Soln to  $y' + 5y = e^{7t}$   $y = \frac{e^{7t}}{7+5} + C e^{-5t}$

- Gen. Soln to  $y' + 5y = P$   $y = \frac{P}{5} + C e^{-5t}$

- Gen. Soln to  $y' + 5y = e^{-5t}$

Try  $y_p(t) = A t e^{-5t}$   $(A t e^{-5t})' + 5(A t e^{-5t})$   
 $= A e^{-5t} = e^{-5t} \Rightarrow A=1$

Gen. Soln:  $y(t) = t e^{-5t} + C e^{-5t}$

Example 3.  $y' + 3y = \cos(\omega t)$

Try  $y_p(t) = A \cos(\omega t) + B \sin(\omega t)$

Then  $y_p' + 3y_p =$

$$\begin{aligned} & (-\omega A \sin(\omega t) + \omega B \cos(\omega t)) + 3(A \cos(\omega t) + B \sin(\omega t)) \\ &= (3A + \omega B) \cos(\omega t) + (3B - \omega A) \sin(\omega t) = \cos(\omega t) \end{aligned}$$

$$\text{So } \begin{cases} 3A + \omega B = 1 \\ -\omega A + 3B = 0 \end{cases} \Rightarrow A = \frac{3}{9 + \omega^2} \quad B = \frac{\omega}{9 + \omega^2}$$

$$\text{So } y(t) = \frac{3}{9 + \omega^2} \cos(\omega t) + \frac{\omega}{9 + \omega^2} \sin(\omega t) + C e^{-3t}$$

$$= \frac{1}{\sqrt{9 + \omega^2}} \cos(\omega t - \phi) + C e^{-3t}, \quad \tan \phi = \frac{\omega}{3}$$

Example.  $\frac{dy}{dt} + ky = \cos(\omega t)$

E x ample.

$$\frac{dy}{dt} + ky = \cos(\omega t)$$

$$y(t) = y_p(t) + C e^{-kt}$$

Try  $y_p(t) = A \cos(\omega t) + B \sin(\omega t)$

Then

$$\begin{aligned} y_p'(t) + k y_p(t) &= \omega(-A \sin(\omega t) + B \cos(\omega t)) + \\ &+ k(A \cos(\omega t) + B \sin(\omega t)) \\ &= (\omega B + kA) \cos(\omega t) + \\ &(-\omega A + kB) \sin(\omega t) = \cos(\omega t) \end{aligned}$$

$$\Rightarrow A = \frac{k}{k^2 + \omega^2}, \quad B = \frac{\omega}{k^2 + \omega^2}$$

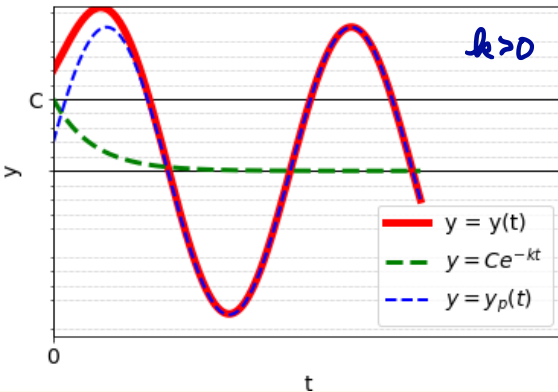
$$\text{So } y_p(t) = \frac{k}{k^2 + \omega^2} \cos(\omega t) + \frac{\omega}{k^2 + \omega^2} \sin(\omega t) = \frac{1}{\sqrt{k^2 + \omega^2}} \cos(\omega t - \varphi),$$

where  $\tan \varphi = \frac{\omega}{k}$ .

Consequently,

$$y(t) = \frac{1}{\sqrt{k^2 + \omega^2}} \cos(\omega t - \varphi) + C e^{-kt}$$

Steady  
State  
Soln.



transient

Note If  $\frac{dy}{dt} + ky = a_1 \cos(\omega_1 t) + a_2 \cos(\omega_2 t)$

then

$$y(t) = C e^{-kt} + \frac{a_1}{\sqrt{k^2 + \omega_1^2}} \cos(\omega_1 t - \varphi_1) + \frac{a_2}{\sqrt{k^2 + \omega_2^2}} \cos(\omega_2 t - \varphi_2)$$

where  $\begin{cases} \varphi_1 = \tan^{-1}(\omega_1/k) \\ \varphi_2 = \tan^{-1}(\omega_2/k) \end{cases}$

Example. Find a particular solution of

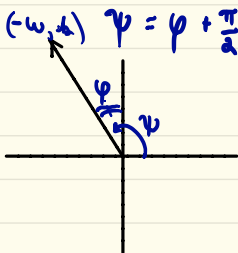
$$y' + ky = \sin(\omega t)$$

Soln. Try  $y_p = A \cos(\omega t) + B \sin(\omega t)$

$$\begin{aligned} \text{Then } y_p' + ky_p &= \omega(-A \sin(\omega t) + B \cos(\omega t)) \\ &\quad + k(A \cos(\omega t) + B \sin(\omega t)) \\ &= \sin(\omega t) \end{aligned}$$

$$\Rightarrow \begin{cases} -\omega A + kB = 1 \\ kA + \omega B = 0 \end{cases} \Rightarrow \begin{cases} A = \frac{-\omega}{k^2 + \omega^2} \\ B = \frac{k}{k^2 + \omega^2} \end{cases}$$

$$\text{So } y_p = \frac{-\omega}{k^2 + \omega^2} \cos(\omega t) + \frac{k}{k^2 + \omega^2} \sin(\omega t) = \frac{1}{\sqrt{k^2 + \omega^2}} \cos(\omega t - \varphi)$$



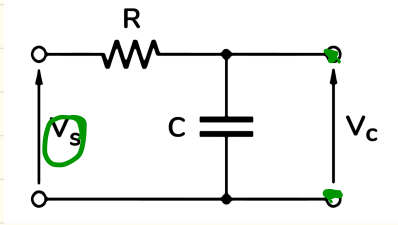
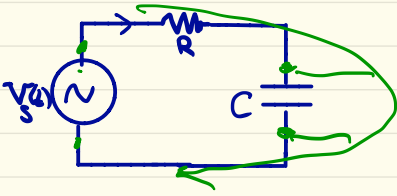
Recall

$$\cos(\alpha) = \sin(\alpha - \frac{\pi}{2})$$

$$\Rightarrow \frac{1}{\sqrt{k^2 + \omega^2}} \sin(\omega t - \varphi)$$

$$\tan \varphi = \frac{\omega}{k}$$

# Low pass filter



$$V_s(t) = RI + \frac{q}{C}$$

$$I = \frac{dq}{dt}$$

$$V_c = \frac{q}{C}$$

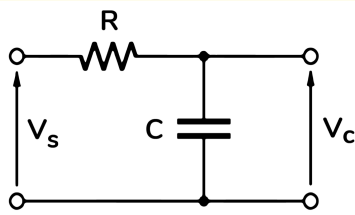
$$q = C \cdot V_c$$

$$V_s(t) = R \frac{dq}{dt} + \frac{q}{C}$$

$$V_s(t) = R \frac{d(CV_c)}{dt} + V_c$$

$$RC \frac{dV_c}{dt} + V_c = V_s(t)$$

$$\frac{dV_c}{dt} + \frac{1}{RC} V_c = \frac{1}{RC} V_s$$



$$\frac{dV_c}{dt} + \frac{1}{RC} V_c = \frac{1}{RC} V_s(t)$$

$$k = \frac{1}{RC}$$

$$\frac{1}{\sqrt{k^2 + \omega^2}} = \frac{RC}{\sqrt{1 + (RC\omega)^2}}$$

If  $V_s(t) = \cos(\omega t)$  then

$$V_c(t) = C e^{-t/RC} + \frac{1}{\sqrt{1 + (RC\omega)^2}} \cos(\omega t - \phi)$$

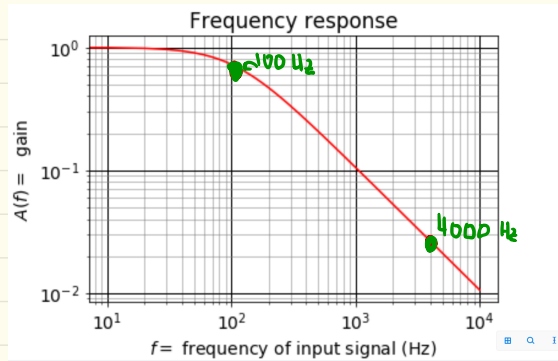
$$A(\omega) = \frac{1}{\sqrt{1 + (RC\omega)^2}} \text{ called "gain"}$$

Example.  $R = 150 \Omega$   
 $C = 10 \times 10^{-6} \text{ F}$

Input signal:

$$V_s(t) = \frac{2.5}{\sqrt{2}} \cos(\omega_1 t) + \frac{0.5}{\sqrt{2}} \cos(\omega_2 t)$$

$$f_1 = \omega_1 / 2\pi = 100 \text{ Hz}, f_2 = \omega_2 / 2\pi = 4000 \text{ Hz}$$



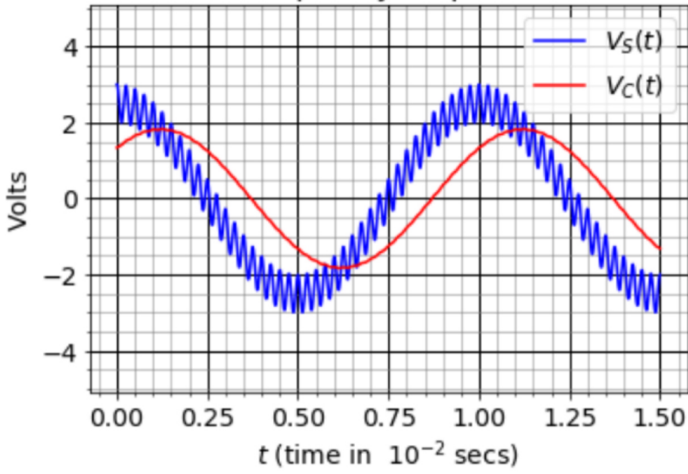
$$V_c(t) = C e^{-t/RC} + \left(\frac{2.5}{RC}\right) \frac{1}{\sqrt{k^2 + \omega_1^2}} \cos(\omega_1 t - \phi_1) + \left(\frac{0.5}{RC}\right) \frac{1}{\sqrt{k^2 + \omega_2^2}} \cos(\omega_2 t - \phi_2)$$

$$= C e^{-t/RC} + \frac{2.5}{\sqrt{1 + (RC\omega_1)^2}} \cos(\omega_1 t - \phi_1) + \frac{0.5}{\sqrt{1 + (RC\omega_2)^2}} \cos(\omega_2 t - \phi_2)$$

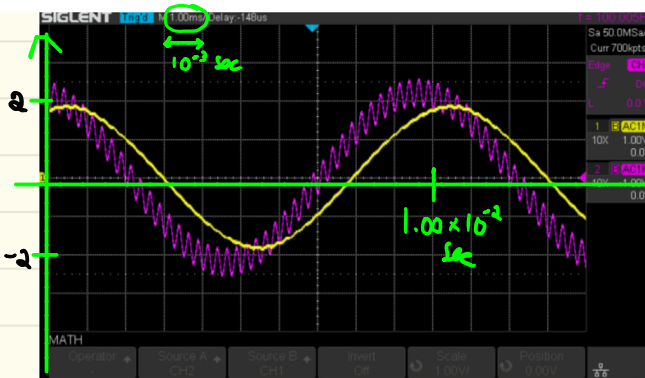
$$\approx 1.02 \cos(\omega_1 t - \phi_1) + (0.03) \cos(\omega_2 t - \phi_2)$$



# Frequency response



theoretical



observed

# Changing Units (Examples)

$e^{-\beta t}$

• Newton's Law of Cooling.

$$\frac{dT}{dt} + \beta T = \beta T_A$$

$t$ : time in seconds  
 $T$ : temperature (in degrees C)

units of  $\beta$ :  $\frac{1}{\text{Sec}}$   
 $\frac{1}{\beta}$  natural time scale.

"time constant"

Let  $\tau = \frac{1}{\beta} t = \frac{t}{(1/\beta)}$  (dimensionless)

$t = \tau \cdot (1/\beta)$  "time in multiples of  $1/\beta$ "

$$\frac{dT}{dt} = \frac{dT}{dt} \frac{dt}{d\tau} = \beta \frac{dT}{d\tau}$$

$$\text{So } \beta \frac{dT}{d\tau} + \beta T = \beta \frac{T_A}{\beta}$$

$$\frac{dT}{d\tau} + T = \frac{T_A}{\beta}$$

$$\frac{dT}{d\tau} + T = \frac{T_A}{\beta} \left( \frac{\tau}{\beta} \right)$$

• RC - circuit

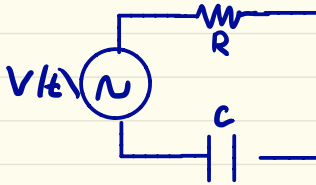
$$\frac{dV_C}{dt} + \frac{1}{RC} V_C = \frac{1}{RC} V(t)$$

RC is "time constant"

units of RC = seconds

Let  $\tau = t/RC$  or  $t = \tau \cdot RC$

$$\frac{dV_C}{dt} = \frac{d\tau}{dt} \frac{dV_C}{d\tau} = \frac{1}{RC} \frac{dV_C}{d\tau}$$



$$\frac{1}{RC} \frac{dV_C}{d\tau} + \frac{1}{RC} V_C = \frac{1}{RC} V(t)$$

or

$$t = \tau (RC)$$

$$\frac{dV_C}{d\tau} + V_C = V(\tau RC)$$

$$\frac{dT}{d\tau} + T = \frac{T_A}{\beta} \left( \frac{\tau}{\beta} \right)$$