

Convex Analysis and Optimization

FIRST HOMEWORK SET

(1) A mapping $\langle \cdot, \cdot \rangle : \mathbb{R}^n \mapsto \mathbb{R}^n$ is said to be an inner product on \mathbb{R}^n if for all $x, y, z \in \mathbb{R}^n$

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|-------|---|--------------|
| (i) | $\langle x, x \rangle \geq 0$ | Non-Negative |
| (ii) | $\langle x, x \rangle = 0 \Leftrightarrow x = 0$ | Positive |
| (iii) | $\langle x + y, z \rangle = \langle x, z \rangle + \langle y, z \rangle$ | Additive |
| (iv) | $\langle \alpha x, y \rangle = \alpha \langle x, y \rangle \quad \forall \alpha \in \mathbb{R}$ | Homogeneous |
| (v) | $\langle x, y \rangle = \langle y, x \rangle$ | Symmetric |

Two vectors $x, y \in \mathbb{R}^n$ are said to be orthogonal in the inner product $\langle \cdot, \cdot \rangle$ if $\langle x, y \rangle = 0$

Unless otherwise specified, we use the notation $\langle x, y \rangle$ to designate the usual Euclidean inner product:

$$\langle x, y \rangle = \sum_{i=1}^n x_i y_i .$$

(a) Let $\langle x, y \rangle$ be the Euclidean inner product on \mathbb{R}^n . Given $A \in \mathbb{R}^{n \times n}$, show that $A = 0$ if and only if

$$\langle x, Ay \rangle = 0 \quad \forall x, y \in \mathbb{R}^n .$$

(b) Let $H \in \mathbb{R}^{n \times n}$ be symmetric and positive definite (i.e. $H = H^T$ and $x^T H x > 0 \quad \forall x \in \mathbb{R}^n \setminus \{0\}$). Show that the bi-linear form given by

$$\langle x, y \rangle_H = x^T H y \quad \forall x, y \in \mathbb{R}^n$$

defines an inner product on \mathbb{R}^n .

(c) Every inner product defines a transformation on the space of linear operators called the *adjoint*. For the Euclidean inner product on \mathbb{R}^n , this is just the usual transpose. Given a linear transformation $M : \mathbb{R}^n \mapsto \mathbb{R}^n$, the adjoint is defined by the relation

$$\langle y, Mx \rangle = \langle M^* y, x \rangle, \quad \text{for all } x, y \in \mathbb{R}^n .$$

The inner product given above, $\langle \cdot, \cdot \rangle_H$, also defines an adjoint mapping which we can denote by M^{T_H} . Show that

$$M^{T_H} = H^{-1} M^T H .$$

(d) The matrix $P \in \mathbb{R}^{n \times n}$ is said to a projection if $P^2 = P$. Clearly, if P is a projection, then so is $I - P$. The subspace $P\mathbb{R}^n = \text{Ran}(P)$ is called the subspace that P projects onto. A projection is said to be orthogonal with respect to a given inner product $\langle \cdot, \cdot \rangle$ on \mathbb{R}^n if and only if

$$\langle (I - P)x, Py \rangle = 0 \quad \forall x, y \in \mathbb{R}^n ,$$

that is, the subspaces $\text{Ran}(P)$ and $\text{Ran}(I - P)$ are orthogonal in the inner product $\langle \cdot, \cdot \rangle$. Show that the projection P is orthogonal with respect to the inner product $\langle \cdot, \cdot \rangle_H$ (defined above), where $H \in \mathbb{R}^{n \times n}$ is symmetric and positive definite, if and only if

$$P = H^{-1} P^T H .$$

(2) Consider the minimization problem

$$\mathcal{P} : \quad \begin{array}{ll} \text{minimize} & f(x) \\ \text{subject to} & Ax = b , \end{array}$$

where $f : \mathbb{R}^n \mapsto \mathbb{R}$ is assumed to be twice continuously differentiable, $A \in \mathbb{R}^{m \times n}$ has full rank with $m \leq n$, and $b \in \mathbb{R}^m$. Set

$$P := I - A^T(AA^T)^{-1}A .$$

(a) Show that P is well-defined, that is, show that the matrix AA^T is non-singular.

(b) Show that P is the *orthogonal projector* onto the nullspace of A . That is, show that P is an orthogonal projector ($P^2 = P$ and $P = P^T$) and $\text{Ran}(P) = \text{Nul}(A)$.

(c) Set $h(z) = f(x_0 + Pz)$ where x_0 is any point satisfying $Ax_0 = b$. Compute both $\nabla h(z)$ and $\nabla^2 h(z)$.

(d) Show that if \bar{z} solves $\hat{\mathcal{P}} : \min\{h(z) : z \in \mathbb{R}^n\}$, then $\bar{x} = x_0 + P\bar{z}$ solves \mathcal{P} . Conversely, show that if \bar{x} solves \mathcal{P} , then there exists \bar{z} solving $\hat{\mathcal{P}}$ such that $\bar{x} = x_0 + P\bar{z}$.

- (e) The set of first-order stationary points for the problem $\hat{\mathcal{P}}$ is the set of points $\mathcal{S}_h = \{z \mid \nabla h(z) = 0\}$. We define the set of first-order stationary points for \mathcal{P} to be $\mathcal{S}_f = \{x_0 + Pz \mid z \in \mathcal{S}_h\}$. Show that

$$\mathcal{S}_f = \{x \mid P\nabla f(x) = 0, Ax = b\} = \{x \mid Ax = b, \nabla f(x) \perp \text{Nul}(A)\} .$$

- (3) Let $H \in \mathbb{R}_s^{n \times n}$, $u \in \mathbb{R}^n$, and $\alpha \in \mathbb{R}$ where $\mathbb{R}_s^{n \times n}$ is the linear space of all real symmetric $n \times n$ matrices. Recall that H is said to be *positive definite* if $x^T H x > 0$ for all $x \in \mathbb{R}^n$ with $x \neq 0$. Moreover, H is said to be *positive semi-definite* if $x^T H x \geq 0$ for all $x \in \mathbb{R}^n$. We consider the block matrix

$$\hat{H} := \begin{bmatrix} H & u \\ u^T & \alpha \end{bmatrix} .$$

- (a) Show that \hat{H} is positive semi-definite if and only if H is positive semi-definite and there exists a vector $z \in \mathbb{R}^n$ such that $u = Hz$ and $\alpha \geq z^T H z$.
 (b) Show that \hat{H} is positive definite if and only if H is positive definite and $\alpha > u^T H^{-1} u$.
 (c) Let $A \in \mathbb{R}^{m \times n}$, $b \in \mathbb{R}^m$, $c \in \mathbb{R}^n$, and $\delta \in \mathbb{R}$. Use either Part (a) or Part (b) to show that $x \in \mathbb{R}^n$ is a solution to the quadratic inequality

$$(Ax + b)^T (Ax + b) \leq c^T x + \delta$$

if and only if the block matrix

$$\begin{bmatrix} I & (Ax + b) \\ (Ax + b)^T & (c^T x + \delta) \end{bmatrix}$$

is positive semi-definite.

- (d) Suppose H is positive definite. Show that

$$\begin{bmatrix} H & u \\ 0 & (\alpha - u^T H^{-1} u) \end{bmatrix} = \begin{bmatrix} I & 0 \\ (-H^{-1} u)^T & 1 \end{bmatrix} \begin{bmatrix} H & u \\ u^T & \alpha \end{bmatrix} .$$

- (e) Recall that the k th *principal minor* of a matrix $B \in \mathbb{R}^{n \times n}$ is the determinant of the upper left-hand corner $k \times k$ -submatrix of B for $1 \leq k \leq n$. Use an induction argument and Parts (b) and (d) above to show that H is positive definite if and only if every principal minor of H is positive.

Note: Your argument **must** use either Part (a) or Part (b) above.

Hint: $\det(AB) = \det(A)\det(B)$, and the determinant of an upper or lower block triangular matrix is the product of the determinants of the diagonal blocks.

- (4) Let $A \in \mathbb{R}^{m \times n}$, $c \in \mathbb{R}^n$, $a \in \mathbb{R}^m$, $\delta > 0$, and $H \in \mathbb{R}^{n \times n}$ with H symmetric positive definite. Consider the problem

$$\begin{aligned} \mathcal{P} \quad & \min_{x \in \mathbb{R}^n} c^T x \\ & \text{subject to} \quad Ax = a \\ & \quad \quad \quad \|x_0 - x\|_H \leq \delta \end{aligned}$$

where $x_0 \in \mathbb{R}^n$ satisfies $Ax_0 = a$,

$$\|z\|_H = (z^T H z)^{1/2} = [\langle z, z \rangle_H]^{1/2} ,$$

and the inner product $\langle \cdot, \cdot \rangle_H$ is defined in part (b) of problem 1 above.

- (a) Suppose $H = LL^T$ for some non-singular matrix $L \in \mathbb{R}^{n \times n}$, e.g. $L = H^{1/2}$. If Q is the orthogonal projector onto the null-space of AL^{-T} in the usual (or Euclidean) inner product, show that the operator P given by

$$P = L^{-T} Q L^T$$

is the orthogonal projector onto the null-space of A with respect to the inner product $\langle \cdot, \cdot \rangle_H$.

- (b) Show that

$$\bar{x} = x_0 - \delta \|PH^{-1}c\|_H^{-1} PH^{-1}c$$

solves \mathcal{P} where P is as given in part (a) above.

Hint: It may be helpful to first reduce the problem to one of the form

$$\begin{aligned} \min \quad & \hat{c}^T w \\ \text{subject to} \quad & \hat{A}w = 0 \\ & \|w\|_2^2 \leq \delta^2 . \end{aligned}$$

It is also helpful to apply results relating least-squares to orthogonal projection.