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# Linear Analysis

## Lecture 9

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## Power Series on $\mathcal{B}(V)$

Let  $f(z)$  be analytic on the disk  $\{|z| < R\} \subset \mathbb{C}$ , with power series

$$f(z) = \sum_{k=0}^{\infty} a_k z^k$$

and radius of convergence at least  $R$ . If  $L \in \mathcal{B}(V)$  and  $\|L\| < R$ , then the series

$$\sum_{k=0}^{\infty} a_k L^k$$

converges absolutely, and thus converges to an element of  $\mathcal{B}(V)$  which we call  $f(L)$ .

It is easy to check that usual operational properties hold, for example

$$(fg)(L) = f(L)g(L) = g(L)f(L) .$$

**Caution:** Always remember that operators do not commute in general. For example,

$$e^{L+M} \neq e^L e^M \quad \text{in general,}$$

although if  $L$  and  $M$  commute (i.e.  $LM = ML$ ), then

$$e^{L+M} = e^L e^M .$$

## Calculus on $\mathcal{B}(V)$ : Differentiation

Let  $L(t)$  be a 1-parameter family of operators in  $\mathcal{B}(V)$ ,  $t \in (a, b)$ . Since  $\mathcal{B}(V)$  is a metric space, continuity of  $L(t)$  in  $t$  is well defined.

We say that  $L(t)$  is *differentiable* at  $t = t_0 \in (a, b)$  if

$$L'(t_0) = \lim_{t \rightarrow t_0} \frac{L(t) - L(t_0)}{t - t_0}$$

exists in the norm on  $\mathcal{B}(V)$ .

For example, it is easily checked that for  $L \in \mathcal{B}(V)$ ,  $e^{tL}$  is differentiable in  $t$  for all  $t \in \mathbb{R}$ , and

$$\frac{d}{dt} e^{tL} = L e^{tL} = e^{tL} L .$$

## Calculus on $\mathcal{B}(V)$ : Differentiation

Similarly consider families of operators in  $\mathcal{B}(V)$  depending on several real or complex parameters. A family  $L(z)$  where

$$z = x + iy \in \Omega^{\text{open}} \subset \mathbb{C} \quad (x, y \in \mathbb{R})$$

is said to be holomorphic in  $\Omega$  if the partial derivatives

$$\frac{\partial}{\partial x} L(z), \quad \frac{\partial}{\partial y} L(z)$$

exist, are continuous in  $\Omega$ , and satisfy the Cauchy-Riemann equations

$$\left( \frac{\partial}{\partial x} + i \frac{\partial}{\partial y} \right) L(z) = 0 \quad \text{on } \Omega.$$

This is equivalent to the assumption that in a neighborhood of each point  $z_0 \in \Omega$ ,  $L(z)$  is given by the  $\mathcal{B}(V)$ -norm convergent power series

$$L(z) = \sum_{k=0}^{\infty} \frac{1}{k!} (z - z_0)^k \left( \frac{d}{dz} \right)^k L(z_0).$$

## Calculus on $\mathcal{B}(V)$ : Integration

If  $L(t)$  depends continuously on  $t \in [a, b]$ , then it can be shown using the same estimates as for  $\mathbb{F}$ -valued functions (and the uniform continuity of  $L(t)$  since  $[a, b]$  is compact) that the Riemann sums

$$\frac{b-a}{N} \sum_{k=0}^{n-1} L\left(a + \frac{k}{N}(b-a)\right)$$

converge in  $\mathcal{B}(V)$ -norm (recall  $V$  is a Banach space) as  $n \rightarrow \infty$  to an operator in  $\mathcal{B}(V)$ , denoted

$$\int_a^b L(t) dt .$$

More general Riemann sums than just the left-hand “rectangular rule” with equally spaced points can be used.

Many results from standard calculus carry over, including

$$\left\| \int_a^b L(t) dt \right\| \leq \int_a^b \|L(t)\| dt$$

which follows from

$$\left\| \frac{b-a}{N} \sum_{k=0}^{N-1} L\left(a + \frac{k}{N}(b-a)\right) \right\| \leq \frac{b-a}{N} \sum_{k=0}^{N-1} \left\| L\left(a + \frac{k}{N}(b-a)\right) \right\| .$$

By parameterizing paths in  $\mathbb{C}$ , one can define line integrals of holomorphic families of operators. We will discuss such constructions further as we need them.

# Operators in Finite Dimensions

## *Transposes and Adjoints*

$$A \in \mathbb{C}^{m \times n}$$

$$A^T \in \mathbb{C}^{n \times m} \quad \text{the transpose of } A: (A_{ij} = (A^T)_{ji})$$

$$A^H = \bar{A}^T \quad \text{the conjugate-transpose (or Hermitian transpose) of } A$$

One often writes  $A^* = A^H$ . But there is a subtlety here, which is related to the identification of a linear operator with its representation as a matrix, that we must be careful about.

Recall that an inner product on  $\mathbb{C}^n$  can be represented as a matrix multiply, e.g. for the Euclidean inner product

$$\langle x, y \rangle = y^H x$$

For  $A \in \mathbb{C}^{n \times n}$ ,

$$\langle Ax, y \rangle = \langle x, A^H y \rangle$$

since

$$y^H Ax = (A^H y)^H x$$

## Caution About $A^H$ and $A^*$

$A^*$  is used with two different meanings (particularly when  $\mathbb{F}=\mathbb{C}$ ).

$$L \in \mathcal{B}(V, W) \implies L^* \in \mathcal{B}(W^*, V^*)$$

In finite dim., one can choose bases of  $V$  and  $W$  to encode the action of  $L$  as left matrix multiplication on column vectors associated with the bases components. Denote such a matrix as  $T$ .

Then the action of  $L^*$  on  $W^*$  can be encoded using the dual bases *using the same matrix*  $T$ . But now the action is represented as *right* multiply by  $T$  on row vectors of components in the dual basis ( $a=bT$ ).

On the other hand, in the presence of an inner product, the definition

$$\langle Lv, w \rangle = \langle v, L^* w \rangle$$

identifies  $L^*$  with left-multiplication by the conjugate-transpose matrix.

These two definitions are related by the identification

$$V \cong V^*$$

induced by the inner product:

$$w \in V \iff \langle \cdot, w \rangle = w^* \in V^* .$$

But the conjugation in this identification gives rise to a different representation of  $L^*$ . The first is a natural representation obtained through composition, and the second is through the inner product.

# Norms on Matrices

Commonly used norms on  $\mathbb{C}^{m \times n}$ .

$$\|A\|_1 = \sum_{ij} |a_{ij}| \quad (\text{the } \ell^1\text{-norm on } A \text{ as if it were in } \mathbb{C}^{n^2})$$

$$\|A\|_\infty = \max_{i,j} |a_{ij}| \quad (\text{the } \ell^\infty\text{-norm on } A \text{ as if it were in } \mathbb{C}^{n^2})$$

$$\|A\|_2 = \left( \sum_{i,j} |a_{ij}|^2 \right)^{\frac{1}{2}} \quad (\text{the } \ell^2\text{-norm on } A \text{ as if it were in } \mathbb{C}^{n^2})$$

$\|A\|_2$  is called the Hilbert-Schmidt norm of  $A$ , or the Frobenius norm of  $A$ , and is often denoted  $\|A\|_F$ . It is also called the Euclidean norm on  $\mathbb{C}^{m \times n}$ . The associated inner product is  $\langle A, B \rangle = \text{tr } B^H A$ .

We also have  $p$ -norms for matrices: let  $1 \leq p \leq \infty$ ,

$$\| \|A\| \|_p = \max_{\|x\|_p=1} \|Ax\|_p \quad \left( = \max_{\|x\|_p \leq 1} \|Ax\|_p = \max_{x \neq 0} (\|Ax\|_p / \|x\|_p) \right).$$

In particular,

$$\| \|A\| \|_1 = \max_{1 \leq j \leq n} \sum_{i=1}^m |a_{ij}| \quad (\text{max column sum})$$

$$\| \|A\| \|_\infty = \max_{1 \leq i \leq m} \sum_{j=1}^n |a_{ij}| \quad (\text{max row sum})$$

$\| \|A\| \|_2$  is the spectral norm. We study it in detail later.



# Consistent Matrix Norms

## Definitions

- Let  $\mu : \mathbb{C}^{m \times n} \rightarrow \mathbb{R}$ ,  $\nu : \mathbb{C}^{n \times k} \rightarrow \mathbb{R}$ ,  $\rho : \mathbb{C}^{m \times k} \rightarrow \mathbb{R}$  be norms. We say that  $\mu, \nu, \rho$  are **consistent** if  $\forall A \in \mathbb{C}^{m \times n}$  and  $\forall B \in \mathbb{C}^{n \times k}$ ,

$$\rho(AB) \leq \mu(A)\nu(B)$$

- A norm on  $\mathbb{F}^{n \times n}$  is called consistent if it is consistent with itself, i.e., the definition above with  $m = n = k$  and  $\rho = \mu = \nu$ . So by definition a norm on  $\mathbb{F}^{n \times n}$  is consistent iff it is submultiplicative.
- A collection  $\{\nu_{m,n} : m \geq 1, n \geq 1\}$ , where  $\nu_{m,n} : \mathbb{F}^{m \times n} \rightarrow \mathbb{R}$  is a norm on  $\mathbb{F}^{m \times n}$ , is called a **family of matrix norms**.
- A family  $\{\nu_{m,n} : m \geq 1, n \geq 1\}$  of matrix norms is called **consistent** if

$$(\forall m, n, k \geq 1)(\forall A \in \mathbb{F}^{m \times n})(\forall B \in \mathbb{F}^{n \times k}) \\ \nu_{m,k}(AB) \leq \nu_{m,n}(A)\nu_{n,k}(B).$$

**Facts** Let  $\{\nu_{m,n}\}$  be a consistent family of matrix norms. Then

- (1)  $(\forall n \geq 1)$   $\nu_{n,n}$  is submultiplicative.
- (2)  $(\forall m, n \geq 1)$   $(\forall A \in \mathbb{F}^{m \times n})$   $\nu_{m,n}(A) \geq \mu_{m,n}(A)$ , where  $\mu_{m,n}$  is the operator norm on  $\mathbb{F}^{m \times n}$  induced by  $\nu_{n,1}$  and  $\nu_{m,1}$ .

# Examples of Consistent Matrix Norms

- (1) For  $m > 1$ , let  $\nu_{m,1}$  be any norm on  $\mathbb{F}^m$ , and  $\nu_{1,1}(x) = |x|$ . For  $m, n \geq 1$ , let  $\nu_{m,n}$  be the operator norm on  $\mathbb{F}^{m \times n}$  induced by  $\nu_{n,1}$  and  $\nu_{m,1}$ . Then  $\{\nu_{m,n}\}$  is a consistent family of matrix norms.

- (2) (maximum row sum norm) For  $m, n \geq 1$  and  $A \in \mathbb{F}^{m \times n}$ , let

$$\nu_{m,n}(A) = \max_{1 \leq i \leq m} \sum_{j=1}^n |a_{ij}|.$$

Then  $\nu_{n,1}$  is the  $\ell^\infty$ -norm on  $\mathbb{F}^n$ , and  $\nu_{m,n}(A)$  is the operator norm induced by the  $\ell^\infty$ -norms on  $\mathbb{F}^n$  and  $\mathbb{F}^m$ , which we denoted by  $\|A\|_\infty$ .

- (3) (maximum column sum norm) For  $m, n \geq 1$  and  $A \in \mathbb{F}^{m \times n}$ , let

$$\nu_{m,n}(A) = \max_{1 \leq j \leq n} \sum_{i=1}^m |a_{ij}|.$$

Then  $\nu_{n,1}$  is the  $\ell^1$ -norm on  $\mathbb{F}^n$ , and  $\nu_{m,n}(\cdot)$  is the operator norm induced by the  $\ell^1$ -norms on  $\mathbb{F}^n$  and  $\mathbb{F}^m$ , which we denoted by  $\|A\|_1$ .

- (4) ( $\ell^1$ -norm on  $\mathbb{F}^{m \times n}$  as if it were  $\mathbb{F}^{mn}$ ) For  $m, n \geq 1$  and  $A \in \mathbb{F}^{m \times n}$ , let

$$\nu_{m,n}(A) = \sum_{i=1}^m \sum_{j=1}^n |a_{ij}|.$$

Then  $\{\nu_{m,n}\}$  is a consistent family of matrix norms. We denoted  $\nu_{m,n}(A)$  by  $\|A\|_1$ . Also note that  $\|A\|_1 \geq \|A\|_1$  agrees with Fact (2) on the previous slide.

# The Frobenius or Hilbert-Schmidt Norm

( $\ell^2$ -norm on  $\mathbb{F}^{m \times n}$  as if it were  $\mathbb{F}^{mn}$ ) For  $m, n \geq 1$  and  $A \in \mathbb{F}^{m \times n}$ , let

$$\nu_{m,n}(A) = \sqrt{\sum_{i=1}^m \sum_{j=1}^n |a_{ij}|^2}.$$

Then  $\nu_{n,1}$  is the  $\ell^2$ -norm on  $\mathbb{F}^n$ . If  $A \in \mathbb{F}^{m \times n}$  and  $B \in \mathbb{F}^{n \times k}$ , then by the Schwarz inequality,

$$\begin{aligned}(\nu_{m,k}(AB))^2 &= \sum_{i=1}^m \sum_{j=1}^k \left| \sum_{\ell=1}^n a_{i\ell} b_{\ell j} \right|^2 \\ &\leq \sum_{i=1}^m \sum_{j=1}^k \left( \sum_{\ell=1}^n |a_{i\ell}|^2 \right) \left( \sum_{r=1}^n |b_{rj}|^2 \right) \\ &= (\nu_{m,n}(A) \nu_{n,k}(B))^2,\end{aligned}$$

so  $\{\nu_{m,n}\}$  is a consistent family of matrix norms.

This is **not** an operator norm: for  $n > 1$ ,  $\nu_{n,n}(I) = \sqrt{n}$  but the operator norm of  $I$  is always 1.

Denote  $\nu_{m,n}(A)$  by  $\|A\|_2$  (or, sometimes  $\|A\|_F$ ).

# The Frobenius or Hilbert-Schmidt Norm

For  $A \in \mathbb{F}^{m \times n}$  and  $x \in \mathbb{F}^n$ , we have

$$\|Ax\|_2 \leq \|A\|_2 \cdot \|x\|_2,$$

so for  $A \in \mathbb{F}^{m \times n}$  and  $B \in \mathbb{F}^{n \times k}$ ,

$$\|AB\|_2 \leq \|A\|_2 \cdot \|B\|_2.$$

Fact (2) above gives the important inequality

$$\|A\|_F \geq \|A\|_2 \quad \forall A \in \mathbb{F}^{m \times n}.$$

Thus the operator norm induced by the  $\ell^2$ -norms on  $\mathbb{F}^m$  and  $\mathbb{F}^n$  is dominated by the Frobenius norm.

# Condition Number and Error Sensitivity

Let  $A \in \mathbb{C}^{n \times n}$  be invertible. How sensitive is the solution to  $Ax = b$  to changes in  $b$  and  $A$ ? Let  $\|\cdot\|$  be a consistent matrix norm on  $\mathbb{C}^{n \times n}$ .

Suppose  $Ax = b$  and  $A\hat{x} = \hat{b}$ . How far is  $\hat{x}$  from  $x$ ?

$$e := x - \hat{x} = \text{the error vector}$$

$$\|e\| := \text{the error}$$

$$r := b - \hat{b} = \text{the residual vector}$$

$$\|r\| := \text{the residual}$$

$$\|e\|/\|x\| := \text{the relative error}$$

$$\|r\|/\|b\| := \text{the relative residual}$$

Then  $Ae = A(x - \hat{x}) = b - \hat{b} = r$ , so

$$\|e\| = \|A^{-1}r\| \leq \|A^{-1}\| \|r\| \quad \text{and} \quad \|b\| \leq \|A\| \|x\|$$

so

$$\|e\| \cdot \|b\| \leq \|A\| \cdot \|A^{-1}\| \cdot \|x\| \cdot \|r\|$$

which implies

$$\frac{\|e\|}{\|x\|} \leq \kappa(A) \frac{\|r\|}{\|b\|},$$

where  $\kappa(A) := \|A\| \cdot \|A^{-1}\|$  is the condition number of  $A$ .

## Condition Number and Error Sensitivity

$$\kappa(A) = \|A\| \cdot \|A^{-1}\| = \text{condition number of } A.$$

Note that for any operator norm

$$1 = \|I\| = \|AA^{-1}\| \leq \|A\| \|A^{-1}\| = \kappa(A).$$

A matrix is said to be perfectly conditioned if  $\kappa(A) = 1$ , and is said to be ill-conditioned if  $\kappa(A)$  is large.

If  $\hat{x}$  is the result of a numerical algorithm for solving  $Ax = b$  (with round-off error), then the error  $e = x - \hat{x}$  is not computable. However, the residual  $r = b - A\hat{x}$  is computable, so we obtain an upper bound on the relative error

$$\frac{\|e\|}{\|x\|} \leq \kappa(A) \frac{\|r\|}{\|b\|}.$$

In practice, we don't know  $\kappa(A)$  (although we may be able to estimate it), and this upper bound may be much larger than the actual relative error.

# Condition Number and Error Sensitivity

Now assume that both  $A$  and  $b$  are perturbed:

$$\hat{A} = A + E \quad \text{and} \quad \hat{b} = b - r$$

Obtain a bound on the relative error  $\|e\|/\|x\|$  where

$$e = x - \hat{x} \quad \text{with} \quad \hat{x} \text{ solving } \hat{A}\hat{x} = \hat{b}.$$

First use the Neumann Lemma to note that if

$$\|A^{-1}E\| \leq \|A^{-1}\| \|E\| < 1,$$

then

$$\begin{aligned} \|(A + E)^{-1}\| &= \|(I + A^{-1}E)^{-1}A^{-1}\| \\ &\leq \|(I + A^{-1}E)^{-1}\| \|A^{-1}\| \leq \frac{1}{1 - \|A^{-1}\| \|E\|} \|A^{-1}\|. \end{aligned}$$

Also,  $(A + E)x = b + Ex$  and  $(A + E)\hat{x} = \hat{b}$  so

$$e = x - \hat{x} = (A + E)^{-1}(Ex + r)$$

and so

$$\begin{aligned} \|e\| &\leq \|(A + E)^{-1}\| [\|E\| \|x\| + \|r\|] \\ &\leq \frac{1}{1 - \|A^{-1}\| \|E\|} \|A^{-1}\| \left[ \frac{\|E\|}{\|A\|} \|A\| \|x\| + \frac{\|r\|}{\|b\|} \|A\| \|x\| \right]. \end{aligned}$$

Therefore,

$$\frac{\|e\|}{\|x\|} \leq \frac{\kappa(A)}{1 - \kappa(A) \frac{\|E\|}{\|A\|}} \left[ \frac{\|E\|}{\|A\|} + \frac{\|r\|}{\|b\|} \right].$$