Math 554 Homework Set 8 Autumn 2014 Due Monday November 24

(1) (a) Let  $f : \mathbb{R} \times \mathbb{C}^n \to \mathbb{C}$  be continuous. Suppose  $x : \mathbb{R} \to \mathbb{C}$  is a solution of the  $n^{\text{th}}$ -order equation

(\*) 
$$x^{(n)} = f(t, x, x', \vdots, x^{(n-1)}),$$

i.e., for each  $t \in \mathbb{R}$ ,  $x^{(n)}(t)$  exists and  $x^{(n)}(t) = f(t, x(t), \dots, x^{(n-1)}(t))$ . Show that  $x \in C^n(\mathbb{R})$ .

(b) Define  $F : \mathbb{R} \times \mathbb{C}^n \to \mathbb{C}^n$  by  $F(t, y) = [y_2, y_3, \dots, y_n, f(t, y_1, \dots, y_n)]^T$  (so F is continuous). Suppose  $y : \mathbb{R} \to \mathbb{C}^n$  is a solution of the first-order system

$$(**)$$
  $y' = F(t, y),$ 

i.e., for each  $t \in \mathbb{R}$ , y'(t) exists and y'(t) = F(t, y(t)). Show that  $y \in C^1(\mathbb{R})$ , and moreover for  $1 \leq j \leq n, y_j \in C^{n-j+1}(\mathbb{R})$ .

(c) Show that if  $x \in C^n(\mathbb{R})$  is a solution of (\*), then  $y = [x, x', \dots, x^{(n-1)}]^T$  is a  $C^1$  solution of (\*\*). Moreover, if x satisfies the initial conditions

$$x^{(k)}(t_0) = x_0^k \qquad (0 \le k \le n-1),$$

then y satisfies the initial conditions  $y(t_0) = [x_0^0, \dots, x_0^{n-1}]^T$ .

- (d) Show that if y is a  $C^1$  solution of (\*\*), then  $x = y_1$  is a  $C^n$  solution of (\*). Moreover, if y satisfies the initial conditions  $y(t_0) = y_0$ , then x satisfies the initial conditions  $x^{(k)}(t_0) = (y_0)_{k+1}$   $(0 \le k \le n-1)$ .
- (e) Show that the first-order system corresponding to the linear  $n^{\text{th}}$ -order equation  $x^{(n)} + a_1(t)x^{(n-1)} + \cdots + a_n(t)x = b(t)$  is of the form y' = A(t)y + B(t) where  $A(t) \in \mathbb{C}^{n \times n}$  and  $B(t) \in \mathbb{C}^n$ , and identify A(t) and B(t).
- (2) Let  $A \in \mathbb{C}^{n \times n}$  have  $\rho(A) < 1$ .
  - (a) Show by example that A need not be a contraction with respect to the Euclidean metric.
  - (b) Show that there is an inner product on  $\mathbb{C}^n$  so that A is a contraction with respect to the norm induced by the inner product.
  - (c) Show that for any  $x \in \mathbb{C}^n$ ,  $A^k x \to 0$  as  $k \to \infty$ .
- (3) For each of th following IVP's, compute the Picard iterates and identify the solution to which they converge.
  - (a) x' = tx, x(0) = 1 (x scalar)
  - (b) x' = Ax,  $x(0) = x_0$  where  $A \in \mathbb{C}^{n \times n}$  is a constant matrix  $(x \in \mathbb{C}^n)$ .
- (4) (Gronwall's Inequality integral forms) Let  $\varphi$ ,  $\psi$ ,  $\alpha$  be real-valued continuous functions on the interval I = [a, b]. Suppose  $\alpha \ge 0$  on I, and that

$$\varphi(t) \le \psi(t) + \int_a^t \alpha(s)\varphi(s)ds \quad \forall t \in I.$$

(a) Show that

$$\varphi(t) \le \psi(t) + \int_a^t \exp\left(\int_s^t \alpha(r)dr\right) \alpha(s)\psi(s)ds \quad \forall t \in I \;.$$

Hint: Let  $u(t) = \int_a^t \alpha(s)\varphi(s)ds$  and show that  $u' - \alpha u \le \alpha \psi$ .

(b) Supposed that  $\psi(t) \equiv c$  (a constant). Show that

$$\varphi(t) \le c \exp\left(\int_a^t \alpha(s) ds\right) \quad \forall t \in I .$$

- (5) (Iterative Methods for Linear Systems)
  - (a) Fix  $M \in \mathbb{C}^{n \times n}$  and  $g \in \mathbb{C}^n$ . Given any  $x_0 \in \mathbb{C}^n$ , define the sequence  $\{x_k\}$  iteratively by  $x_{k+1} = Mx_k + g$ . Show that if  $\rho(M) < 1$ , then I M is invertible, and for any choice of  $x_0 \in \mathbb{C}^n$ ,  $x_k \to x_*$ , the unique solution of (I M)x = g.
  - (b) Suppose  $A \in \mathbb{C}^{n \times n}$  is invertible,  $b \in \mathbb{C}^n$  is given, and we want to solve the linear system Ax = b for  $x \in \mathbb{C}^n$ . A splitting method writes A as A = S T where S is invertible (and linear systems Sx = y are easily solved), and given  $x_0 \in \mathbb{C}^n$ , define  $\{x_k\}$  by  $Sx_{k+1} = Tx_k + b$ . Show that if  $\rho(S^{-1}T) < 1$ , then for any choice of  $x_0 \in \mathbb{C}^n$ ,  $x_k \to x_*$ , the unique solution of Ax = b.
  - (c) Suppose  $A \in \mathbb{C}^{n \times n}$  with nonzero diagonal entries. Write A = L + D + U, where L is strictly lower triangular, D is diagonal, and U is strictly upper triangular. The Jacobi iteration is the splitting method where S = D, T = -(L+U). The Gauss-Seidel iteration is the splitting method where S = D+L, T = -U. Show that if A is strictly (row) diagonally dominant (i.e., for  $1 \le i \le n$ ,  $|a_{ii}| > \sum_{1 \le j \le n, j \ne i} |a_{ij}|$ ), then A is invertible, and for any given  $x_0$ , the Jacobi iteration generates a sequence  $\{x_k\}$  which converges to the unique solution  $x_*$  of Ax = b.

(Hint: Show  $|||D^{-1}(L+U)|||_{\infty} < 1$  in the operator norm  $||| \cdot |||_{\infty}$  on  $\mathbb{C}^{n \times n}$  induced by the  $\ell^{\infty}$ -norm  $|| \cdot ||_{\infty}$  on  $\mathbb{C}^{n}$ .)

[Remark: It can be shown that if A is strictly (row) diagonally dominant, then the Gauss-Seidel iteration converges. As one would expect from the proof of the Contraction Mapping Fixed Point Theorem, the rate of convergence depends on  $\rho(S^{-1}T)$ . For some classes of matrices A, it can be shown that  $\rho_G = \rho_J^2$ , where  $\rho_G$  and  $\rho_J$  are  $\rho(S^{-1}T)$  for Gauss-Seidel an Jacobi, respectively, so Gauss-Seidel takes roughly half the number of iterations as Jacobi to achieve the same accuracy. With the goal of further decreasing  $\rho(S^{-1}T)$ , Gauss-Seidel has been generalized to the successive over-relaxation method (SOR): the iteration takes the form

$$(D+\omega L)x_{k+1} = D_{x_k} + \omega[b - (D+U)x_k]$$

where  $\omega$  (fixed) is called the relaxation parameter ( $\omega < 1$  is called under-relaxation,  $\omega > 1$  is called over-relaxation); the method was originally developed for matrices arising from discretizing elliptic PDE's where values of  $\omega > 1$  tend to give faster convergence, so the name SOR has stuck; Gauss-Seidel is SOR with  $\omega = 1$ . Dividing through by  $\omega$ , SOR is seen to be a splitting method

$$S_{\omega}x_{k+1} = T_{\omega}x_k + b,$$

where

$$S_{\omega} = \frac{1}{\omega}(D + \omega L)$$
 and  $T_{\omega} = \frac{1}{\omega}((1 - \omega)D - \omega U).$ 

The iteration matrix M (as in (a)) is

$$M_{\omega} = S_{\omega}^{-1} T_{\omega} = (D + \omega L)^{-1} ((1 - \omega)D - \omega U).$$

It can be shown that if  $A \in \mathbb{R}^{n \times n}$  is symmetric positive-definite, then  $\rho(M_{\omega}) < 1$  (and thus the SOR iteration converges) iff  $0 < \omega < 2$  (the Ostrowski-Reich Theorem). One direction (that  $0 < \omega < 2$  is necessary) is shown easily.]

(d) Suppose  $A \in \mathbb{C}^{n \times n}$  with nonzero diagonal elements,  $\omega \in \mathbb{R}$ , and

$$M_{\omega} = (D + \omega L)^{-1} ((1 - \omega)D - \omega U).$$

Show that  $\rho(M_{\omega}) \ge |\omega - 1|$  (and thus  $\rho(M_{\omega}) \ge 1$  for  $\omega \le 0$  and for  $\omega \ge 2$ ). (Hint: Use

det 
$$(D + \omega L)^{-1}$$
 = det  $D^{-1}$  and det  $((1 - \omega)D - \omega U)$  = det  $((1 - \omega)D)$ 

to show that det  $(M_{\omega}) = (1 - \omega)^n$ .)

- (e) Let  $A \in \mathbb{C}^{n \times n}$ . A matrix  $C \in \mathbb{C}^{n \times n}$  is called an *approximate inverse* for A if  $\rho(I-CA) < 1$ . Show that if C is an approximate inverse for A, then A is invertible, C is invertible, and for any given  $x_0 \in \mathbb{C}^n$ , the iteration  $x_{k+1} = x_k + C(b Ax_k)$  generates a sequence  $\{x_k\}$  which converges to the unique solution  $x_*$  of Ax = b. [Remark:  $r_k = b - Ax_k$  is called the residual at the  $k^{\text{th}}$  iteration.]
- (6) One-sided uniqueness theorem  $(n = 1, \mathbb{F} = \mathbb{R})$ 
  - (a) A real-valued function f(t, u) is said to satisfy a one-sided Lipschitz condition in u if

$$u_1 > u_2 \quad \Rightarrow \quad f(t, u_1) - f(t, u_2) \le L(u_2 - u_1) \quad \forall \ t \in \mathbb{R}.$$

Show that if f is continuous in t and u and satisfies a one-sided Lipschitz condition in u, then there is at most one solution to the IVP u' = f(t, u),  $u(t_0) = 0$ , for  $t \ge t_0$ .

(b) Let f(t, u) be a real-valued continuous function in t and u, and suppose that f is decreasing in u for all t, i.e.,  $u_2 > u_1$  implies that  $f(t, u_2) \le f(t, u_1)$ . Show that if u(t) and v(t) are both solutions to u' = f(t, u), then

 $|u(t) - v(t)| \le |u(s) - v(s)|$  whenever  $t \ge s$ .

Deduce uniqueness for the IVP u' = f(t, u),  $u(t_0) = 0$ , for  $t \ge t_0$ . Show, however, that uniqueness may fail for  $t < t_0$ .