

Math 408A

Convexity

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Convexity and optimality

Directional Derivatives and Convexity

The Subdifferential Inequality

Convexity and Optimality Conditions

Sublinear Functionals

Examples of Convex Functions

Convexity

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The function f is said to be strictly convex if for every two distinct points $x_1, x_2 \in \mathbb{R}^n$ and $\lambda \in [0, 1]$ we have

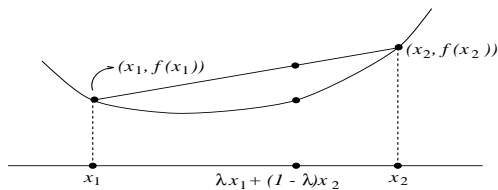
$$f(\lambda x_1 + (1 - \lambda)x_2) < \lambda f(x_1) + (1 - \lambda)f(x_2).$$

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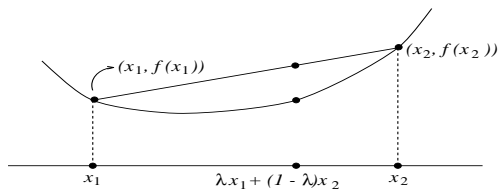
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That is, the set

$$\text{epi}(f) = \{(x, \mu) : f(x) \leq \mu\},$$

called the *epi-graph* of f , is a convex set.

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Examples of convex functions are

$$c^T x, \quad \|x\|, \quad x^T H x \quad \text{when } H \text{ is psd.}$$

Convexity and Optimality

Theorem: Let $f : \mathbb{R}^n \rightarrow \bar{\mathbb{R}}$ be convex. If $\bar{x} \in \mathbb{R}^n$ is a local minimum for f , then \bar{x} is a global minimum for f . If, in addition, f is strictly convex, then \bar{x} is the unique global minimizer.

Convexity and Optimality

Proof: Suppose $f(\hat{x}) < f(\bar{x})$. Let $\epsilon > 0$ be such that

$$f(\bar{x}) \leq f(x) \quad \text{whenever} \quad \|x - \bar{x}\| \leq \epsilon \quad \text{and} \quad \epsilon < 2\|\bar{x} - \hat{x}\| .$$

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Set $\lambda := \epsilon(2\|\bar{x} - \hat{x}\|)^{-1} < 1$ and $x_\lambda := \bar{x} + \lambda(\hat{x} - \bar{x})$.

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Then $\|x_\lambda - \bar{x}\| \leq \epsilon/2$ and

$$f(x_\lambda) \leq (1 - \lambda)f(\bar{x}) + \lambda f(\hat{x}) < f(\bar{x}).$$

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This contradicts the choice of ϵ and so no such \hat{x} exists.



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Lemma: *Let $f : \mathbb{R}^n \rightarrow \bar{\mathbb{R}}$ be convex (not necessarily differentiable).*



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Lemma: Let $f : \mathbb{R}^n \rightarrow \bar{\mathbb{R}}$ be convex (not necessarily differentiable).

1. Given $x, d \in \mathbb{R}^n$ the difference quotient

$$\frac{f(x + td) - f(x)}{t}$$

is a non-decreasing function of t on $(0, +\infty)$.

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2. For every $x, d \in \mathbb{R}^n$ the directional derivative $f'(x; d)$ always exists and is given by

$$f'(x; d) := \inf_{t>0} \frac{f(x + td) - f(x)}{t}.$$



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This infimum always exists and so $f'(x; d)$ always exists and is given by the infimum.



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Hence

$$\frac{f(x + t_1 d) - f(x)}{t_1} \leq \frac{f(x + t_2 d) - f(x)}{t_2}.$$

The Subdifferential Inequality

If $f : \mathbb{R}^n \rightarrow \mathbb{R}$ is convex, then for all $x \in \text{dom}(f)$ and $y \in \mathbb{R}^n$,

$$f'(x; (y - x)) = \inf_{t>0} \frac{f(x + t(y - x)) - f(x)}{t} .$$

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We will call this inequality the *subdifferential inequality*.

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This inequality states that the tangent plane to the graph of f lies entirely below the graph of f .

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(iii) \Rightarrow (i): Obvious.

Convexity and Optimality Conditions

Theorem: *Let $f : \mathbb{R}^n \rightarrow \mathbb{R}$ be convex and suppose that $\bar{x} \in \mathbb{R}^n$ is a point at which f is differentiable. Then \bar{x} is a global minimum of f if and only if $\nabla f(\bar{x}) = 0$.*

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- (3) $(\nabla f(x) - \nabla f(y))^T(x - y) \geq 0$ for all $x, y \in \mathbb{R}^n$.

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- (3) $(\nabla f(x) - \nabla f(y))^T(x - y) \geq 0$ for all $x, y \in \mathbb{R}^n$.

If f is twice differentiable then f is convex if and only if $\nabla^2 f(x)$ is positive semi-definite for all $x \in \mathbb{R}^n$.

$$f(y) \geq f(x) + \nabla f(x)^T (y - x) \quad \forall x, y \in \mathbb{R}^n \Rightarrow \\ (\nabla f(x) - \nabla f(y))^T (x - y) \geq 0 \quad \forall x, y \in \mathbb{R}^n$$

For all $x, y \in \mathbb{R}^n$, the subdifferential inequality gives

$$f(y) \geq f(x) + \nabla f(x)^T (y - x) \\ f(x) \geq f(y) + \nabla f(y)^T (x - y)$$

Adding these two inequalities and canceling like terms from each side gives

$$0 \geq \nabla f(x)^T (y - x) + \nabla f(y)^T (x - y)$$

or equivalently

$$0 \leq (\nabla f(x) - \nabla f(y))^T (x - y) .$$

$$\begin{aligned}(\nabla f(x) - \nabla f(y))^T(x - y) &\geq 0 \quad \forall x, y \in \mathbb{R}^n \implies \\ f(y) &\geq f(x) + \nabla f(x)^T(y - x) \quad \forall x, y \in \mathbb{R}^n\end{aligned}$$

Let $x, y \in \mathbb{R}^n$. By the MVT there exists $0 < \lambda < 1$ such that

$$f(y) - f(x) = \nabla f(x_\lambda)^T(y - x)$$

where $x_\lambda := \lambda y + (1 - \lambda)x$. Then

$$\begin{aligned}0 &\leq [\nabla f(x_\lambda) - \nabla f(x)]^T(x_\lambda - x) \\ &= \lambda[\nabla f(x_\lambda) - \nabla f(x)]^T(y - x) \\ &= \lambda[f(y) - f(x) - \nabla f(x)^T(y - x)].\end{aligned}$$

Hence $f(y) \geq f(x) + \nabla f(x)^T(y - x)$.

$$f(y) \geq f(x) + \nabla f(x)^T (y - x) \quad \forall x, y \in \mathbb{R}^n \Rightarrow f \text{ is convex}$$

Let $x, y \in \mathbb{R}^n$ and set

$$\alpha := \max_{\lambda \in [0,1]} \varphi(\lambda) := [f(\lambda y + (1 - \lambda)x) - (\lambda f(y) + (1 - \lambda)f(x))].$$

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$$0 = \varphi'(\lambda) = \nabla f(x_\lambda)^T (y - x) + f(x) - f(y)$$

where $x_\lambda = x + \lambda(y - x)$, or equivalently

$$\lambda(f(y) - f(x)) = -\nabla f(x_\lambda)^T (x - x_\lambda).$$

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$$\lambda(f(y) - f(x)) = -\nabla f(x_\lambda)^T (x - x_\lambda).$$

Hence, by the subdifferential inequality,

$$\begin{aligned} \alpha &= f(x_\lambda) - (f(x) + \lambda(f(y) - f(x))) \\ &= f(x_\lambda) + \nabla f(x_\lambda)^T (x - x_\lambda) - f(x) \\ &\leq 0 \end{aligned}$$

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If f is convex,

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or equivalently

$$\frac{1}{2} d^T \nabla^2 f(x) d + \frac{o(t^2)}{t^2} \geq 0.$$

f convex $\Rightarrow \nabla^2 f(x)$ PSD on \mathbb{R}^n

If f is convex,

$$f(x + td) \geq f(x) + t\nabla f(x)^T d \quad \forall t \in \mathbb{R}, x, d \in \mathbb{R}^n.$$

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Letting $t \rightarrow 0$ yields the inequality

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For $x, y \in \mathbb{R}^n$, the MVT implies there exists $\lambda \in (0, 1)$ such that

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Therefore, f is convex.

Checking for Positive Definiteness

Theorem: Let $H \in \mathbb{R}^{n \times n}$ be symmetric. We define the k th principal minor of H , denoted $\Delta_k(H)$, to be the determinant of the upper left-hand $k \times k$ submatrix of H . Then H is positive definite if and only if $\Delta_k(H) > 0$ for $k = 1, 2, \dots, n$.

Checking for Positive Definiteness

Example:

$$H = \begin{bmatrix} 1 & 1 & -1 \\ 1 & 5 & 1 \\ -1 & 1 & 4 \end{bmatrix}.$$

We have

$$\Delta_1(H) = 1, \quad \Delta_2(H) = \begin{vmatrix} 1 & 1 \\ 1 & 5 \end{vmatrix} = 4, \quad \Delta_3(H) = \det(H) = 8.$$

Therefore, H is positive definite.

Sublinear Functionals

Definition: Let $h : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$. We say that h is positively homogeneous if

$$h(\lambda x) = \lambda h(x) \quad \text{for all } x \in \mathbb{R} \text{ and } \lambda > 0.$$

We say that h is subadditive if

$$h(x + y) \leq h(x) + h(y) \quad \text{for all } x, y \in \mathbb{R}.$$

Finally, we say that h is sublinear if it is both subadditive and positively homogeneous.

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Note: Sublinear functionals can be thought of as a generalization of the notion of a norm. In particular, every norm is a sublinear functional.

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Lemma: *A function is sublinear if and only if its epigraph is a convex cone.*

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Thus, in particular, the function $f'(x; \cdot)$ is a convex function.

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Proof: (Positive Homogeneity) Let $x \in \text{dom}(f)$, $d \in \mathbb{R}^n$, and $\lambda > 0$. Then

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Examples of Convex Functions

Set $\mathbb{R}_{++}^n = \{x \in \mathbb{R}^n \mid 0 < x_i, i = 1, \dots, n\}$ and \mathbb{S}_{++}^n equal to the set on $n \times n$ symmetric positive definite matrices.

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