

Math 408A: Linear Algebra Review

Linear Algebra Review

Block Structured Matrices

Gaussian Elimination Matrices

Gauss-Jordan Elimination (Pivoting)

Matrices in $\mathbb{R}^{m \times n}$

$$A \in \mathbb{R}^{m \times n}$$

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$$

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columns

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$$A^T = \begin{bmatrix} a_{11} & a_{21} & \dots & a_{m1} \\ a_{12} & a_{22} & \dots & a_{m2} \\ \vdots & \vdots & \ddots & \vdots \\ a_{1n} & a_{2n} & \dots & a_{mn} \end{bmatrix}$$

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Matrix Vector Multiplication

A column space view of matrix vector multiplication.

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

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$$= x_1 \mathbf{a}_{\bullet 1} + x_2 \mathbf{a}_{\bullet 2} + \cdots + x_n \mathbf{a}_{\bullet n}$$

A linear combination of the columns.

The Range of a Matrix

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A Couple of Special Subspaces

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- ▶ The linear span of v_1, \dots, v_k :

$$\text{Span}(v_1, \dots, v_k) = \{y \mid y = \xi_1 v_1 + \xi_2 v_2 + \dots + \xi_k v_k, \xi_1, \dots, \xi_k \in \mathbb{R}\}$$

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Matrix Vector Multiplication

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The dot product of x with the rows of A .

The Null Space of a Matrix

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Fundamental Theorem of the Alternative:

$$\text{Nul}(A) = \text{Ran}(A^T)^\perp \quad \text{Ran}(A) = \text{Nul}(A^T)^\perp$$

Block Structured Matrices

$$A = \begin{bmatrix} 3 & -4 & 1 & 1 & 0 & 0 \\ 2 & 2 & 0 & 0 & 1 & 0 \\ -1 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 2 & 1 & 4 \\ 0 & 0 & 0 & 1 & 0 & 3 \end{bmatrix}$$

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where

$$B = \begin{bmatrix} 3 & -4 & 1 \\ 2 & 2 & 0 \\ -1 & 0 & 0 \end{bmatrix}, \quad C = \begin{bmatrix} 2 & 1 & 4 \\ 1 & 0 & 3 \end{bmatrix}$$

Multiplication of Block Structured Matrices

Consider the matrix product AM , where

$$A = \begin{bmatrix} 3 & -4 & 1 & 1 & 0 & 0 \\ 2 & 2 & 0 & 0 & 1 & 0 \\ -1 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 2 & 1 & 4 \\ 0 & 0 & 0 & 1 & 0 & 3 \end{bmatrix} \quad \text{and} \quad M = \begin{bmatrix} 1 & 2 \\ 0 & 4 \\ -1 & -1 \\ 2 & -1 \\ 4 & 3 \\ -2 & 0 \end{bmatrix}$$

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Can we exploit the structure of A ?

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$$\text{where } X = \begin{bmatrix} 1 & 2 \\ 0 & 4 \\ -1 & -1 \end{bmatrix}, \quad \text{and} \quad Y = \begin{bmatrix} 2 & -1 \\ 4 & 3 \\ -2 & 0 \end{bmatrix}.$$

Multiplication of Block Structured Matrices

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$$AM = \begin{bmatrix} B & I_{3 \times 3} \\ 0_{2 \times 3} & C \end{bmatrix} \begin{bmatrix} X \\ Y \end{bmatrix} = \begin{bmatrix} BX + Y \\ CY \end{bmatrix}$$

Multiplication of Block Structured Matrices

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Solving Systems of Linear equations

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Find all solutions $x \in \mathbb{R}^n$ to the system $Ax = b$.

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The set of solutions is either empty, a single point, or an infinite set.

If a solution $x_0 \in \mathbb{R}^n$ exists, then the set of solutions is given by

$$x_0 + \text{Nul}(A) .$$

Gaussian Elimination and the 3 Elementary Row Operations

We solve the system $Ax = b$ by transforming the augmented matrix

$$[A | b]$$

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1. Interchange any two rows.

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1. Interchange any two rows.
2. Multiply any row by a non-zero constant.

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Gaussian Elimination and the 3 Elementary Row Operations

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$$[A | b]$$

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These elementary row operations can be interpreted as multiplying the augmented matrix on the left by a special matrix.



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Multiplying any $4 \times n$ matrix on the left by the exchange matrix

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$$AN = \begin{bmatrix} a_{1\bullet}N \\ a_{2\bullet}N \\ \vdots \\ a_{m\bullet}N \end{bmatrix}$$

Gaussian Elimination Matrices

The key step in Gaussian elimination is to transform a vector of the form

$$\begin{bmatrix} a \\ \alpha \\ b \end{bmatrix},$$

where $a \in \mathbb{R}^k$, $0 \neq \alpha \in \mathbb{R}$, and $b \in \mathbb{R}^{n-k-1}$, into one of the form

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This can be accomplished by left matrix multiplication as follows.

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$$\begin{bmatrix} I_{k \times k} & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -\alpha^{-1}b & I_{(n-k-1) \times (n-k-1)} \end{bmatrix} \begin{bmatrix} a \\ \alpha \\ b \end{bmatrix}$$

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Note that a Gaussian elimination matrix and its inverse are both lower triangular matrices.

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(upper triangular) form.

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Gauss-Jordan Elimination, or Pivot Matrices

What happens in the following multiplication?

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