

(1) Show that the functions

$$f(x_1, x_2) = x_1^2 + x_2^3, \quad \text{and} \quad g(x_1, x_2) = x_1^2 + x_2^4$$

both have a critical point at  $(x_1, x_2) = (0, 0)$  and that their associated Hessians are positive semi-definite. Then show that  $(0, 0)$  is a local (global) minimizer for  $g$  and not for  $f$ .

**Solution**

Both  $f$  and  $g$  are completely separable, i.e. they are the sum of functions of the components and have the form  $h(x) = \sum_{i=1}^n h_i(x_i)$ . The origin is the unique critical point for both functions. However,

$$\nabla^2 f(x_1, x_2) = \begin{bmatrix} 2 & 0 \\ 0 & 6x_2 \end{bmatrix} \quad \nabla^2 g(x_1, x_2) = \begin{bmatrix} 2 & 0 \\ 0 & 12x_2^2 \end{bmatrix}.$$

Clearly,  $\nabla^2 f$  is not positive semi-definite for  $x_2 < 0$ , so  $f$  is not minimized at the origin, while  $\nabla^2 g$  is everywhere positive definite away from the origin and positive semidefinite at the origin. Thus,  $f$  has no local (global) optima, while the origin is a global minimizer of  $g$ .

(2) Find the local minimizers and maximizers for the following functions if they exist:

- (a)  $f(x) = x^2 + \cos x$
- (b)  $f(x_1, x_2) = x_1^2 - 4x_1 + 2x_2^2 + 7$
- (c)  $f(x_1, x_2) = e^{-(x_1^2 + x_2^2)}$
- (d)  $f(x_1, x_2, x_3) = (2x_1 - x_2)^2 + (x_2 - x_3)^2 + (x_3 - 1)^2$

**Solution**

- (a)  $x = 0$  is local (global) minimizer;
- (b)  $(x_1, x_2)^T = (2, 0)^T$  is local (global) minimizer;
- (c)  $(x_1, x_2) = (0, 0)$  is local (global) maximizer;
- (d)  $(x_1, x_2, x_3) = (\frac{1}{2}, 1, 1)$  is local (global) minimizer.

(3) Compute the directional derivative for each of the following functions at the origin.

- (a)  $f(x) = \max\{0, x\}$
- (b)  $f(x) = \max\{-x, 2x\}$
- (c)  $f(x_1, x_2) = |x_1| - |x_2|$

**Solution:**

(a)

$$f'(x; d) = \begin{cases} d & , x > 0 \text{ or } (x = 0 \text{ and } d > 0), \\ 0 & , x < 0 \text{ or } (x = 0 \text{ and } d \leq 0). \end{cases}$$

(b)

$$f'(x; d) = \begin{cases} 2d & , x > 0 \text{ or } (x = 0 \text{ and } d > 0), \\ -d & , x < 0 \text{ or } (x = 0 \text{ and } d \leq 0). \end{cases}$$

(c)

$$f'(x; d) = \begin{cases} d_1 - d_2 & , (x_1 > 0, x_2 > 0) \wedge (x_1 = 0, x_2 > 0, d_1 \geq 0) \wedge (x_1 > 0, x_2 = 0, d_2 \geq 0) \wedge (x_i = 0, d_i \geq 0, i = 1, 2), \\ d_1 + d_2 & , (x_1 > 0, x_2 < 0) \wedge (x_1 = 0, x_2 < 0, d_1 \geq 0) \wedge (x_1 > 0, x_2 = 0, d_2 \leq 0) \wedge (x_i = 0, d_i \geq 0, d_2 \leq 0), \\ -d_1 - d_2 & , (x_1 < 0, x_2 > 0) \wedge (x_1 = 0, x_2 > 0, d_1 \leq 0) \wedge (x_1 < 0, x_2 = 0, d_2 \geq 0) \wedge (x_i = 0, d_i \leq 0, d_2 \geq 0), \\ -d_1 + d_2 & , (x_1 < 0, x_2 < 0) \wedge (x_1 = 0, x_2 < 0, d_1 \leq 0) \wedge (x_1 > 0, x_2 = 0, d_2 \leq 0) \wedge (x_i = 0, d_i \leq 0, i = 1, 2). \end{cases}$$

(4) Show that the function  $f(x) := \frac{1}{2}(\max\{0, x\})^2$  is differentiable at the origin and give its derivative.

**Solution:** Simply note that  $f$  is differentiable at any point  $x \neq 0$  so  $f'(x) = 0$  for  $x > 0$  and  $f'(x) = x$  for  $x < 0$ . The only difficulty occurs at  $x = 0$ . In this case just observe that

$$0 = \lim_{\Delta x \downarrow 0} \frac{1}{2} \Delta x = \lim_{\Delta x \downarrow 0} \frac{f(\Delta x) - f(0)}{\Delta x}$$

and

$$0 = \lim_{\Delta x \uparrow 0} \frac{f(\Delta x) - f(0)}{\Delta x},$$

so that the derivative at  $x = 0$  is zero. Hence,  $f'(x) = \max\{0, x\}$ .(5) Let  $C \subset \mathbb{R}^n$  and  $x \in C$  and recall the definition of the tangent cone to  $C$  at  $x$ :

$$T_C(x) := \{u \mid \exists \{x^\nu\} \subset C, x^\nu \rightarrow x, t_\nu \downarrow 0, \text{ with } t_\nu^{-1}(x^\nu - x) \rightarrow u\}.$$

(a) Let  $\mathbb{B}_2 = \{u \mid \|u\|_2 \leq 1\}$ . Show that for all  $u \in \mathbb{B}_2$  with  $\|u\|_2 = 1$ ,

$$T_{\mathbb{B}_2}(u) = \{v \mid u^T v \leq 0\}.$$

**Solution:** Set  $c(x) := \|x\|_2^2 = \sum_{i=1}^n x_i^2$  so that  $\nabla c(x) = 2x$ . In this case the set  $C$  is  $\mathbb{B}_2 = \{x \mid c(x) \leq 1\}$ . Since this representation for  $\mathbb{B}_2$  satisfies the LICQ for all  $x \in \mathbb{B}_2 \setminus \{0\}$ , we know that for every  $u \in \mathbb{B}_2$  with  $\|u\|_2 = 1$  satisfies  $T_{\mathbb{B}_2}(u) = \{v \mid \langle u, v \rangle = \nabla c(u)^T v \leq 0\}$ .

(b) Consider the continuous function

$$f(x) := \begin{cases} -\sqrt{\|x\|_2^2 - 1} & , \text{ if } \|x\|_2 \geq 1, \text{ and} \\ 0 & , \text{ if } \|x\|_2 < 1. \end{cases}$$

Obviously,  $\mathbb{B}_2 = \operatorname{argmin} \{f(x) \mid x \in \mathbb{B}_2\}$ , since  $f$  is identically zero on  $\mathbb{B}_2$ . Let  $\|u\|_2 = 1 = \|v\|_2$  with  $u^T v = 0$  so that  $v \in T_{\mathbb{B}_2}(u)$ . Show that  $f'(u; v)$  exists with  $f'(u; v) = -1$ , where

$$f'(u; v) := \lim_{t \downarrow 0} \frac{f(u + tv) - f(u)}{t}.$$

**Solution:**  $f'(u; v) := \lim_{t \downarrow 0} \frac{-\sqrt{\|u+tv\|_2^2 - 1} + \sqrt{\|u\|_2^2 - 1}}{t} = \lim_{t \downarrow 0} \frac{-\sqrt{t\langle u, v \rangle + t^2\|v\|_2^2}}{t} = \lim_{t \downarrow 0} -\frac{|t|}{t} = -1.$

- (c) Let  $h : \mathbb{R}^n \rightarrow \mathbb{R}$  be continuously differentiable and let  $S \subset \mathbb{R}^n$ . Recall from Theorem 4.2 in Chapter 4 of the course notes that if  $\bar{x} \in \operatorname{argmin} \{h(x) \mid x \in S\}$ , then  $h'(\bar{x}; d) \geq 0$  for all  $d \in T_S(\bar{x})$ . Does this result contradict your finding in part (5b)? If not, why not?

**Solution:** On the surface it would appear that the optimization problem above violates the theorem since the theorem states that  $f'(x; d) \geq 0 \forall d \in T_\Omega(x)$  whenever  $x \in \operatorname{argmin} \{f(x) \mid x \in \Omega\}$ . However, the theorem requires that  $f$  be continuously differentiable at the point  $x$ . The function defined above is not differentiable on the boundary of the unit ball  $\mathbb{B}_2$ .

- (6) Show that the representation of the set  $\Omega := \{x \in \mathbb{R}^2 \mid -x_1^3 \leq x_2 \leq x_1^3\}$  is not regular at the origin. Can you suggest an alternative representation that is regular at the origin?

**Solution:**  $T_\Omega(0, 0) = \{0\} \times \mathbb{R}_+$  while

$$\{d \mid \nabla f_1(0, 0)^T d \leq 0 \text{ and } \nabla f_2(0, 0)^T d \leq 0\} = \{0\} \times \mathbb{R},$$

where  $f_1(x_1, x_2) = -(x_1^3 + x_2)$  and  $f_2(x_1, x_2) = x_2 - x_1^3$ .

- (7) Let  $\Omega$  be given the representation  $\Omega := \{x \in \mathbb{R}^2 \mid x_2 \leq 0, -x_2 \leq 0\}$  and consider the optimization problem  $\min \{x_1^2 \mid x \in \Omega\}$ . Show that the unique global minimizer of this problem satisfies the MFCQ but not the LICQ. Also, compute the set of KKT multipliers for this global solution.

**Solution:** Observe that  $\Omega = \{(x_1, x_2)^T \mid x_2 = 0\}$  so that  $(x_1, x_2)^T = (0, 0)^T$  is the global optimal solution. Let  $c_1(x) = x_2$  and  $c_2(x) = -x_2$  so that  $\nabla c_1(x) = (0, 1)^T$  and  $\nabla c_2(x) = (0, -1)^T$ . Since  $\nabla c_1(x)$  and  $\nabla c_2(x)$  are nowhere linearly independent, the LICQ cannot hold anywhere. On the other hand, the MFCQ is satisfied everywhere.

- (8) Locate all of the KKT points for the following problems. Can you show that these points are local solutions? Global solutions?

(a)

$$\begin{aligned} & \text{minimize} && e^{(x_1 - x_2)} \\ & \text{subject to} && e^{x_1} + e^{x_2} \leq 20 \\ & && 0 \leq x_1 \end{aligned}$$

**Solution:** This is convex problem so any local solution is a global solution. Obviously, we wish to make  $x_1$  as small as possible and  $x_2$  as big as possible. Hence, we must have  $x_1 = 0$  which gives the solution  $(x_1, x_2) = (0, \ln(20 - 1))$ . By plugging this solution into the KKT conditions, we obtain the multipliers  $(y_1, y_2) = (1, 2)/19$ .

(b)

$$\begin{aligned} & \text{minimize} && e^{(-x_1 + x_2)} \\ & \text{subject to} && e^{x_1} + e^{x_2} \leq 20 \\ & && 0 \leq x_1 \end{aligned}$$

**Solution:** Here we want to make  $x_1$  as big as possible and  $x_2$  as small as possible. By fixing  $x + 1$  at zero and sending  $x_2$  to  $-\infty$ , the constraints are satisfied and the objective goes to zero. Hence, no solution exists and the optimal value is 0.

(c)

$$\begin{aligned} & \text{minimize} && x_1^2 + x_2^2 - 4x_1 - 4x_2 \\ & \text{subject to} && x_1^2 \leq x_2 \\ & && x_1 + x_2 \leq 2 \end{aligned}$$

**Solution:** This is a convex optimization problem and so any KKT point will give global optimality. Check that  $(x_1, x_2) = (1, 1)$  and  $(y_1, y_2) = (0, 2)$  is a KKT pair for this problem.

(d)

$$\begin{aligned} & \text{minimize} && \frac{1}{2}\|x\|_2^2 \\ & \text{subject to} && Ax = b \end{aligned}$$

where  $b \in \mathbb{R}^m$  and  $A \in \mathbb{R}^{m \times n}$  satisfies  $\text{Nul}(A^T) = \{0\}$ .

**Solution:** This is a convex problem so  $\bar{x}$  is a solution if and only if there is a  $\bar{y}$  such that  $(\bar{x}, \bar{y})$  is a KKT pair for this problem. The Lagrangian is  $L(x, y) = \frac{1}{2}\|x\|_2^2 + y^T(b - Ax)$ . The KKT conditions are  $A\bar{x} = b$  and  $\bar{x} = A^T\bar{y}$ . Hence  $b = A\bar{x} = AA^T\bar{y}$ . Since  $\text{Nul}(A^T) = \{0\}$ ,  $\text{Nul}(AA^T) = \{0\}$  so that the matrix  $AA^T$  is invertible. Consequently,  $\bar{y} = (AA^T)^{-1}b$  and  $\bar{x} = A^T\bar{y} = A^T(AA^T)^{-1}b$ .

(9) Suppose  $\Omega = \{x; Ax \leq b, Ex = h\}$  where  $A \in \mathbb{R}^{m \times n}$ ,  $E \in \mathbb{R}^{k \times n}$ ,  $b \in \mathbb{R}^m$ , and  $h \in \mathbb{R}^k$ .

(a) Given  $x \in \Omega$ , show that

$$T_\Omega(x) = \{d : A_i d \leq 0 \text{ for } i \in I(x), Ed = 0\},$$

where  $A_i$  denotes the  $i$ th row of the matrix  $A$  and  $I(x) = \{i : A_i x = b_i\}$ .

**Solution:** It was shown in class (see page 3 of the course notes *Optimality Conditions for Constrained Problems*) that

(♠) 
$$T_\Omega(x) \subset \{d : A_i d \leq 0 \text{ for } i \in I(x), Ed = 0\},$$

so we need only show the reverse inclusion. Let  $x \in \Omega$  and  $d$  be an element of the set of the right hand side of (♠). Note that by continuity there is a  $\bar{t} > 0$  such that  $x + td \in \Omega$  for all  $0 \leq t \leq \bar{t}$ . Hence  $d \in T_\Omega(x)$ .

(b) Given  $x \in \Omega$ , show that every  $d \in T_\Omega(x)$  is a feasible direction for  $\Omega$  at  $x$ .

**Solution:** This is what we showed in the answer to the previous question.

(c) Note that parts (a) and (b) above show that

$$T_\Omega(x) = \bigcup_{\lambda > 0} \lambda(\Omega - x)$$

whenever  $\Omega$  is a convex polyhedral set. Why?

**Solution:** Because every polyhedral convex set can be given a representation

$$\Omega = \{x; Ax \leq b, Ex = h\}.$$