

# Linear Programming

## Lecture 6: The Simplex Algorithm Language, Notation, and Linear Algebra

Math Dept, University of Washington

Dictionaries for LPs in Standard Form

The Simplex Algorithm via Matrix Multiplication

The Block Structure of the Simplex Algorithm

Block Structure and Matrix Multiplication

The Block Structure of an Optimal Tableau

Block Structure and Duality

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# General Dictionaries

A dictionary for  $\mathcal{P}$  is any system of the form

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and such that the systems  $(D_I)$  and  $(D_B)$  have identical solution sets.

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- ▶ If feasible, then the basic solution is a BFS.
- ▶ A feasible dictionary is optimal if  $\hat{c}_j \leq 0$   $j \in N$ .

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First recall that

$$\begin{bmatrix} I_{s \times s} & -\alpha^{-1}a & 0 \\ 0 & \alpha^{-1} & 0 \\ 0 & -\alpha^{-1}b & I_{t \times t} \end{bmatrix} \begin{pmatrix} a \\ \alpha \\ b \end{pmatrix} = \begin{bmatrix} a - a \\ \alpha^{-1}\alpha \\ -b + b \end{bmatrix} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}.$$

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The elimination matrix and its inverse.

$$G = \begin{bmatrix} I_{s \times s} & -\alpha^{-1}a & 0 \\ 0 & \alpha^{-1} & 0 \\ 0 & -\alpha^{-1}b & I_{t \times t} \end{bmatrix} \quad G^{-1} = \begin{bmatrix} I & a & 0 \\ 0 & \alpha & 0 \\ 0 & b & I \end{bmatrix}$$

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The elimination matrices also have the following important property.

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Each simplex pivot can be realized as left multiplication of the simplex tableau by the appropriate Gaussian-Jordan pivot matrix.

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$$\left[ \begin{array}{cccccc|c} 1 & 4 & 2 & 1 & 0 & 0 & 11 \\ 3 & \textcircled{2} & 1 & 0 & 1 & 0 & 5 \\ 4 & 2 & 2 & 0 & 0 & 1 & 8 \\ \hline 4 & 5 & 3 & 0 & 0 & 0 & 0 \end{array} \right]$$

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$$\left[ \begin{array}{cccc} 1 & -2 & 0 & 0 \\ 0 & \frac{1}{2} & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & \frac{-5}{2} & 0 & 1 \end{array} \right] \left[ \begin{array}{cccccc|c} 1 & 4 & 2 & 1 & 0 & 0 & 11 \\ 3 & \textcircled{2} & 1 & 0 & 1 & 0 & 5 \\ 4 & 2 & 2 & 0 & 0 & 1 & 8 \\ \hline 4 & 5 & 3 & 0 & 0 & 0 & 0 \end{array} \right]$$

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# The Block Structure of the Simplex Algorithm

Let  $T_0$  be the initial tableau:

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$T_k$  is obtained from  $T_0$  by multiplying it on the left by a product of Gaussian pivot matrices  $G$ :

$$GT_0 = T_k,$$

where  $G$  is invertible.

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Let's investigate the structure of  $T_k$  by examining the consequence of this product in terms of the block structure of  $T_0$  and  $T_k$ .

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First we must decompose  $G$  into a block structure that is conformal to that of  $T_0$ :

$$G = \left[ \begin{array}{cc} M & u \\ v^T & \beta \end{array} \right],$$

where  $M \in \mathbb{R}^{m \times m}$ ,  $u, v \in \mathbb{R}^m$ , and  $\beta \in \mathbb{R}$ .

# Block Structure and Matrix Multiplication

$$\left[ \begin{array}{ccc|c} 0 & \hat{A} & R & \hat{b} \\ -1 & \hat{c}^T & -y^T & \hat{z} \end{array} \right] = T_k$$

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$$\begin{aligned} \left[ \begin{array}{ccc|c} 0 & \hat{A} & R & \hat{b} \\ -1 & \hat{c}^T & -y^T & \hat{z} \end{array} \right] &= T_k = GT_0 \\ &= \begin{bmatrix} M & u \\ v^T & \beta \end{bmatrix} \left[ \begin{array}{ccc|c} 0 & A & I & b \\ -1 & c^T & 0 & 0 \end{array} \right] \\ &= \left[ \begin{array}{ccc|c} -u & MA + uc^T & M & Mb \\ -\beta & v^T A + \beta c^T & v^T & v^T b \end{array} \right]. \end{aligned}$$



## Block Structure and Matrix Multiplication

$$\left[ \begin{array}{ccc|c} 0 & \hat{A} & R & \hat{b} \\ -1 & \hat{c}^T & -y^T & \hat{z} \end{array} \right] = \left[ \begin{array}{ccc|c} -u & MA + uc^T & M & Mb \\ -\beta & v^T A + \beta c^T & v^T & v^T b \end{array} \right]$$

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Equating terms on the left and right gives

$$u = 0$$

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Equating terms on the left and right gives

$$u = 0 \quad \beta = 1$$

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Equating terms on the left and right gives

$$\begin{aligned} u &= 0 & \beta &= 1 \\ M &= R \end{aligned}$$

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## The Block Structure of an Optimal Tableau

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In this case the optimal value =  $z = b^T y$  .

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**WEAK DUALITY THM.  $\Rightarrow$  Y SOLVES  $\mathcal{D}$  !!!**

# Plastic Cup Factory Reprised

$$\begin{array}{ll} \mathcal{P} & \text{maximize} \quad 25B + 20C \\ & \text{subject to} \quad 20B + 12C \leq 1800 \\ & \quad \quad \quad \frac{1}{15}B + \frac{1}{15}C \leq 8 \\ & \quad \quad \quad 0 \leq B, C \end{array}$$

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$$(B, C)^* = (45, 75),$$

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$$(B, C)^* = (45, 75), \quad (R, L)^* = \left( \frac{5}{8}, \frac{375}{2} \right), \quad z^* = 2625$$

## Another Duality Example

$$\begin{array}{ll} \mathcal{P} & \max \quad 4x_1 + 5x_2 + 3x_3 \\ & \text{s.t.} \quad x_1 + 4x_2 + 2x_3 \leq 11 \\ & \quad \quad 3x_1 + 2x_2 + x_3 \leq 5 \\ & \quad \quad 4x_1 + 2x_2 + 2x_3 \leq 8 \\ & \quad \quad 0 \leq x_1, x_2, x_3 \end{array}$$

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$$T_0 = \left[ \begin{array}{cccccc|c} 1 & 4 & 2 & 1 & 0 & 0 & 11 \\ 3 & 2 & 1 & 0 & 1 & 0 & 5 \\ 4 & 2 & 2 & 0 & 0 & 1 & 8 \\ \hline 4 & 5 & 3 & 0 & 0 & 0 & 0 \end{array} \right]$$

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$$x^* = (0, 1, 3), \quad y^* = (0, 2, 1/2), \quad z^* = 14$$



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$$T_{\text{opt}} = \left[ \begin{array}{cccccc|c} -5 & 0 & 0 & 1 & -2 & 0 & 1 \\ 1 & 1 & 0 & 0 & 1 & \frac{-1}{2} & 1 \\ 1 & 0 & 1 & 0 & -1 & 1 & 3 \\ \hline -4 & 0 & 0 & 0 & -2 & \frac{-1}{2} & -14 \end{array} \right]$$

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## Another Duality Example

$$T_{\text{opt}} = \left[ \begin{array}{cccccc|c} z & x_1 & x_2 & x_3 & x_4 & x_5 & x_6 & \\ 0 & -5 & 0 & 0 & 1 & -2 & 0 & 1 \\ 0 & 1 & 1 & 0 & 0 & 1 & \frac{-1}{2} & 1 \\ 0 & 1 & 0 & 1 & 0 & -1 & 1 & 3 \\ \hline -1 & -4 & 0 & 0 & 0 & -2 & \frac{-1}{2} & -14 \end{array} \right]$$

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$$T_{\text{opt}} = \left[ \begin{array}{cccccc|c} z & x_1 & x_2 & x_3 & x_4 & x_5 & x_6 & \\ 0 & -5 & 0 & 0 & 1 & -2 & 0 & 1 \\ 0 & 1 & 1 & 0 & 0 & 1 & \frac{-1}{2} & 1 \\ 0 & 1 & 0 & 1 & 0 & -1 & 1 & 3 \\ \hline -1 & -4 & 0 & 0 & 0 & -2 & \frac{-1}{2} & -14 \end{array} \right]$$

$$x^* = (0, 1, 3), \quad y^* = (0, 2, 1/2), \quad z^* = 14$$



## Another Duality Example

Check

$$\begin{array}{ll} \mathcal{P} & \max \quad 4x_1 + 5x_2 + 3x_3 \\ & \text{s.t.} \quad x_1 + 4x_2 + 2x_3 \leq 11 \\ & \quad \quad 3x_1 + 2x_2 + x_3 \leq 5 \\ & \quad \quad 4x_1 + 2x_2 + 2x_3 \leq 8 \\ & \quad \quad 0 \leq x_1, x_2, x_3 \end{array}$$

$$\begin{array}{ll} \mathcal{D} & \min \quad 11y_1 + 5y_2 + 8y_3 \\ & \text{s.t.} \quad y_1 + 3y_2 + 4y_3 \geq 4 \\ & \quad \quad 4y_1 + 2y_2 + 2y_3 \geq 5 \\ & \quad \quad 2y_1 + y_2 + 2y_3 \geq 3 \\ & \quad \quad 0 \leq y_1, y_2, y_3 \end{array}$$

$$x^* = (0, 1, 3), \quad y^* = (0, 2, 1/2), \quad z^* = 14$$

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We now focus on the details of the simplex algorithm to determine if and when it works.