

(A) 11-08-22 Review

Find a linear transformation T that has

$$\ker(T) = \text{span} \left[\begin{pmatrix} 1 \\ 0 \\ -2 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 3 \\ 2 \end{pmatrix} \right]$$

$$\ker(T_A) =$$

We find a matrix A such that $\ker(T_A) = \text{span} \left[\begin{pmatrix} 1 \\ 0 \\ -2 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 3 \\ 2 \end{pmatrix} \right]$

We can also choose A to be in echelon form.

$$N = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ -2 & 3 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} I_2 \\ M \end{bmatrix}, \quad M = \begin{bmatrix} -2 & 3 \\ 1 & 2 \end{bmatrix}$$

$$\text{Choose } A = [-M \quad I_2] \Rightarrow AN = [-M \quad I_2] \begin{bmatrix} I_2 \\ M \end{bmatrix} = -M + M = 0$$

and $AN = \left[A \begin{pmatrix} 1 \\ 0 \\ -2 \\ 1 \end{pmatrix}, A \begin{pmatrix} 0 \\ 1 \\ 3 \\ 2 \end{pmatrix} \right] = [0, 0]$

Finally, nullity, $A = 4 - \text{rank}(A) = 4 - 2 = 2$. $A \in \mathbb{R}^{2 \times 4}$

so $\begin{pmatrix} 1 \\ 0 \\ -2 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 3 \\ 2 \end{pmatrix}$ form a basis for $\text{Nul}(A)$.

(B) Find a linear transformation T that has

$$\ker(T) = \text{span} \left[\begin{pmatrix} -1 \\ 3 \\ 1 \\ 2 \end{pmatrix}, \begin{pmatrix} -3 \\ 10 \\ 2 \\ 1 \end{pmatrix} \right]$$

Method: Put $\begin{bmatrix} -1 & 3 & 1 & 2 \\ -3 & 10 & 2 & 1 \end{bmatrix}$ into reduced echelon form.

$$\begin{array}{cccc} 1 & -3 & -1 & -2 \\ 0 & 1 & -1 & -5 \end{array}$$

$$\begin{array}{cccc} 1 & 0 & -4 & -17 \\ 0 & 1 & -1 & -5 \end{array}$$

$$= [\mathbf{I} \ M^T]$$

$$\text{so } \text{span} \left[\begin{pmatrix} -1 \\ 3 \\ 1 \\ 2 \end{pmatrix}, \begin{pmatrix} -3 \\ 10 \\ 2 \\ 1 \end{pmatrix} \right] = \text{span} \left[\begin{pmatrix} 1 \\ 0 \\ -4 \\ -17 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -1 \\ -5 \end{pmatrix} \right] \Rightarrow \begin{bmatrix} \mathbf{I} \\ \mathbf{M} \end{bmatrix}$$

$$\text{so } A = \begin{bmatrix} -\mathbf{M} & \mathbf{I} \end{bmatrix} = \begin{bmatrix} 4 & 1 & 1 & 0 \\ 17 & 5 & 0 & 1 \end{bmatrix}$$

$$\text{check } \begin{bmatrix} 4 & 1 & 1 & 0 \\ 17 & 5 & 0 & 1 \end{bmatrix} \begin{pmatrix} -1 \\ 3 \\ 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{bmatrix} 4 & 1 & 1 & 0 \\ 17 & 5 & 0 & 1 \end{bmatrix} \begin{pmatrix} -3 \\ 10 \\ 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ -51 + 50 + 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$T = T_A$$

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Orthogonality

Recall from 3rd term calculus That for $u, v \in \mathbb{R}^n$

$$u \cdot v = \|u\| \|v\| \cos \Theta$$

where $\|u\| = (u_1^2 + u_2^2 + \dots + u_n^2)^{1/2}$, $\|v\| = (v_1^2 + v_2^2 + \dots + v_n^2)^{1/2}$

(Euclidean norm or magnitude of a vector)

Θ = The smallest angle between u and v ,

So $u \cdot v = 0 \iff u$ and v are perpendicular to each other

When $u \cdot v = 0$ we say that u and v are orthogonal to each other and write $u \perp v$.

$$\text{also } u \cdot v = u^T v = (u^T v)^T = v^T u$$

(99) Given $u^1, u^2, \dots, u^k \in \mathbb{R}^n$ define

$$\{u^1, u^2, \dots, u^k\}^\perp := \{v \in \mathbb{R}^n : u^i \cdot v = 0, i=1, 2, \dots, k\}$$

$$= \text{Nul}(\bar{U}^T)$$

$$\text{where } \bar{U} = [u^1 \ u^2 \ \dots \ u^k]$$

$$\text{since } \bar{U}^T v = \begin{bmatrix} (u^1)^T \\ (u^2)^T \\ \vdots \\ (u^k)^T \end{bmatrix} v = \begin{bmatrix} (u^1)^T v \\ (u^2)^T v \\ \vdots \\ (u^k)^T v \end{bmatrix} = \begin{bmatrix} u^1 \cdot v \\ u^2 \cdot v \\ \vdots \\ u^k \cdot v \end{bmatrix}$$

Therefore, $\{u^1, u^2, \dots, u^k\}^\perp$ is a subspace.

We call this subspace the subspace perpendicular or orthogonal to $\{u^1, u^2, \dots, u^k\}$.

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Theorem: $u^1, u^2, \dots, u^k \in \mathbb{R}^n$, Then

$$\{u^1, u^2, \dots, u^k\}^\perp = [\text{span}\{u^1, u^2, \dots, u^k\}]^\perp$$

That is, if $u^i \cdot v = 0 \quad i = 1, 2, \dots, k$, Then $u \cdot v = 0$
for all $u \in \text{span}\{u^1, u^2, \dots, u^k\}$

Proof: $u \in \text{span}\{u^1, u^2, \dots, u^k\} \Rightarrow u = \alpha_1 u^1 + \alpha_2 u^2 + \dots + \alpha_k u^k$

$$\begin{aligned} \text{so } u \cdot v &= u^T v = (u^T v)^T = v^T u \\ &= v^T [\alpha_1 u^1 + \alpha_2 u^2 + \dots + \alpha_k u^k] \\ &= \alpha_1 v^T u^1 + \alpha_2 v^T u^2 + \dots + \alpha_k v^T u^k \\ &= 0 \end{aligned}$$

$$\text{span}\{u^1, \dots, u^k\} = \text{Ran}(U) \quad U = [u^1 \ u^2 \ \dots \ u^k]$$

$$[\text{Ran}(U)]^\perp = [\text{span}\{u^1, \dots, u^k\}]^\perp = \text{Nul}(U^T)$$

(101) Theorem: Let $S \subset \mathbb{R}^n$ be a subspace. Then $[S^\perp]^\perp = S$.

Proof: $[S \subset [S^\perp]^\perp]$ Let $u \in S$, then $u \cdot v = 0 \ \forall v \in S^\perp$ so $u \in [S^\perp]^\perp$.

$[S^\perp]^\perp \subset S$ Let $u \in [S^\perp]^\perp$ so $u \cdot v = 0 \ \forall v \in S^\perp$.

Let $\{u^1, u^2, \dots, u^k\}$ be a basis for S ($\dim(S) = k$). $\bar{U} = [u^1, u^2, \dots, u^k]$

$$\begin{aligned} \text{Then } \text{Nul}(\bar{U}^T) &= \{v: \bar{U}^T v = 0\} = \left\{v: \begin{bmatrix} (u^1)^T \\ \vdots \\ (u^k)^T \end{bmatrix} v = 0\right\} = \{v: (u^i)^T v = 0\} \\ &= S^\perp. \end{aligned}$$

If $u \notin S$, $u \neq 0$, then $\{u, u^1, \dots, u^k\}$ are linearly independent.

Set $\hat{U} = [u \ u^1 \ \dots \ u^k]$ so $S^\perp \subset \text{Nul}(\hat{U}^T) \subset \text{Nul}(\bar{U}^T) = S^\perp$

$$\dim(S^\perp) = \dim(\text{Nul}(\bar{U}^T)) = n - \dim(\text{Ran}(\bar{U}^T)) = n - \dim(\text{Ran}(\bar{U})) = n - k$$

$$\dim(S^\perp) = \dim(\text{Nul}(\hat{U}^T)) = n - \dim(\text{Ran}(\hat{U}^T)) = n - \dim(\text{Ran}(\hat{U})) = n - (k+1)$$

This contradiction implies that $u \in S$ so $[S^\perp]^\perp \subset S$.

Consequently $S = [S^\perp]^\perp$.

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Theorem: [Four Fundamental Subspaces]Let $A \in \mathbb{R}^{n \times m}$. Then

$$\text{Nul}(A) = \text{Ran}(A^T)^\perp$$

and

$$\text{Ran}(A) = \text{Nul}(A^T)^\perp$$

Proof: $A = \begin{bmatrix} (u^1)^T \\ \vdots \\ (u^n)^T \end{bmatrix} \Rightarrow \text{Nul}(A) = \{u^1, \dots, u^n\}^\perp$

$$= \text{span}\{u^1, u^2, \dots, u^n\}^\perp$$

$$= \text{Ran}\{u^1, u^2, \dots, u^n\}^\perp$$

$$= (\text{Ran}(A^T))^\perp$$

Replace A by A^T to get

$$\text{Nul}(A^T) = \text{Ran}((A^T)^T)^\perp = \text{Ran}(A)^\perp$$

$$\text{so } \text{Nul}(A^T)^\perp = [\text{Ran}(A)^\perp]^\perp = \text{Ran}(A).$$

(103) 4.4 Change of Basis

Standard basis for $\mathbb{R}^n$, $e_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$, $e_2 = \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{pmatrix}$, ..., $e_n = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{pmatrix}$

Fact If $A \in \mathbb{R}^n$ is such that A^{-1} exists, then the columns of A necessarily form a basis for $\mathbb{R}^n$.

pf: A has n -columns that are linearly independent.
Since $\dim(\mathbb{R}^n) = n$, the columns of A must form a basis.

$$\mathcal{B}_n = \{e_1, \dots, e_n\}$$

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Does $B = \left\{ \begin{pmatrix} 1 \\ 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 4 \\ 5 \\ -1 \end{pmatrix} \right\}$ form a basis for $\mathbb{R}^3$?

$$\begin{array}{ccc|ccc} & u^1 & & & & \\ 1 & 2 & 4 & 1 & 0 & 0 \\ 3 & 0 & 5 & 0 & 1 & 0 \\ -2 & 1 & -1 & 0 & 0 & 1 \\ \hline 1 & 2 & 4 & 1 & 0 & 0 \\ 0 & -6 & -7 & -3 & 1 & 0 \\ 0 & 5 & 7 & 2 & 0 & 1 \\ \hline 1 & 2 & 4 & 1 & 0 & 0 \\ 0 & -1 & 0 & -1 & 1 & 1 \\ 0 & 0 & 7 & -3 & 5 & 6 \\ \hline 1 & 0 & 4 & -1 & 2 & 2 \\ 0 & 1 & 0 & 1 & -1 & -1 \\ 0 & 0 & 1 & -3/2 & 5/2 & 6/2 \\ \hline 1 & 0 & 0 & 5/2 & -6/2 & -16/2 \\ 0 & 1 & 0 & 1 & -1 & -1 \\ 0 & 0 & 1 & -3/2 & 5/2 & 6/2 \end{array}$$

$$\bar{U}^{-1} = \frac{1}{7} \begin{bmatrix} 5 & -6 & -16 \\ 7 & -7 & -7 \\ -3 & 5 & 6 \end{bmatrix}$$

Given $y \in \mathbb{R}^3$ find
 $x_1, x_2, x_3 \in \mathbb{R}$ such that

$$y = x_1 u^1 + x_2 u^2 + x_3 u^3$$

$$= [u^1 \ u^2 \ u^3] \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

$$= \bar{U} x$$

$$\Rightarrow x = \bar{U}^{-1} y$$

We call the components
of x the coordinates
of y in the basis B .

(105) ex: what are the coordinates of

$$[y]_{\mathcal{B}} = y \quad y = \begin{pmatrix} 2 \\ -1 \\ -1 \end{pmatrix} \quad \text{in the basis } \mathcal{B} = \left\{ \begin{pmatrix} 1 \\ 3 \\ -2 \end{pmatrix}, \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 4 \\ 5 \\ -1 \end{pmatrix} \right\}$$

$$x = U^{-1}y = \frac{1}{7} \begin{bmatrix} 5 & -6 & -10 \\ 7 & -7 & -7 \\ -3 & 5 & 6 \end{bmatrix} \begin{pmatrix} 2 \\ -1 \\ -1 \end{pmatrix} = \frac{1}{7} \begin{bmatrix} 10 & +6 & +10 \\ 14 & +7 & +7 \\ -6 & -5 & -6 \end{bmatrix}$$

$$= \frac{1}{7} \begin{pmatrix} 26 \\ 28 \\ -17 \end{pmatrix} = \begin{pmatrix} 26/7 \\ 4 \\ -17/7 \end{pmatrix}$$

$$\text{Notation: } [y]_{\mathcal{B}} = \begin{bmatrix} 26/7 \\ 4 \\ -17/7 \end{bmatrix} = U^{-1}y, \quad U = \begin{bmatrix} 1 & 2 & 4 \\ 3 & 0 & 5 \\ -2 & 1 & -1 \end{bmatrix}$$

↓
the vector that gives y in the $\mathcal{B}$ coordinates.

$$\underline{\text{Conversion:}} [y]_{\{e_1, e_2, e_3\}} = y$$