

# Lesson 8

Linear transformations

Null space , Range

Textbook: 2.1

Def: given two vector spaces  $V$  and  $W$  over  $F$

A function  $T: V \rightarrow W$  is a linear transformation iff

$$T(\lambda v) = \lambda T(v) \quad \forall \lambda \in F, \forall v \in V$$

$$T(v+w) = T(v) + T(w) \quad \forall v, w \in V$$

Ex  $T: P(\mathbb{R}) \rightarrow P(\mathbb{R})$

$$T(p) = p'$$

is a linear transformation since

Ex  $T: F^n \rightarrow F^n$

$$T(x_1, x_2, x_3, \dots) = (x_2, x_3, \dots)$$

Is a linear transformation since

$$T(k \{x_n\}) = T(\{kx_n\}) = (kx_2, kx_3, kx_4, \dots) = k T(\{x_n\})$$

$$T(\{x_n\} + \{y_n\}) = T(\{x_n + y_n\}) = (x_2 + y_2, x_3 + y_3, \dots) = (x_2, x_3, \dots)$$

$$+ (y_2, y_3, \dots) = T(\{x_n\}) + T(\{y_n\})$$

Ex  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  projection on  $y, z$  plane

$$T(x_1, x_2, x_3) = (0, x_2, x_3)$$

is a linear transformation

Ex  $T: \mathbb{F}^n \rightarrow \mathbb{F}^n$

$$T((x_1, x_2, x_n, \dots)) = (0, x_1, x_2, x_n, \dots) \text{ is a linear}$$

transformation

Ex  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  reflection

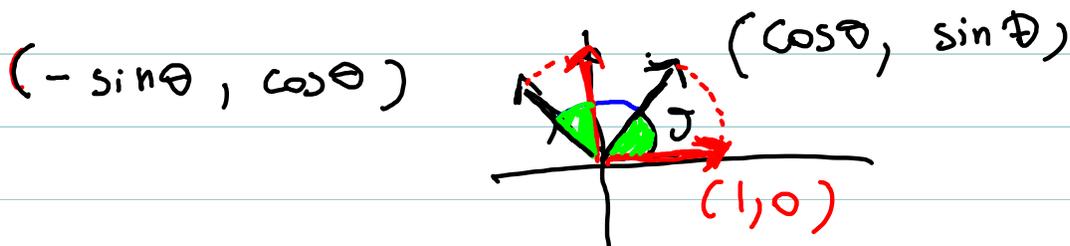
$$T((x, y)) = (-x, y)$$

Ex:  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  rotation

$$T((x, y)) = \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$T((1, 0)) = (\cos\theta, \sin\theta)$$

$$T((0, 1)) = (-\sin\theta, \cos\theta)$$



$$T: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

$$T(v) = Av \quad \text{where } A \in M_{m \times n}(\mathbb{R})$$

is a linear transformation  
since

$$T(kv) = A(kv) = k(Av) = kT(v)$$

$$T(v+w) = A(v+w) = Av + Aw = T(v) + T(w)$$

for all vectors  $v, w \in \mathbb{R}^n$  and  
scalars  $k \in \mathbb{R}$

Ex  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$

$T(x, y, z) = (x+1, 2y, z+x-y)$  NOT A LINEAR TRANSFORMATION

Th If  $T: V \rightarrow W$  is a linear transformation then  $T(0) = 0$

Def: Given  $T: V \rightarrow W$  The kernel of  $T$  (or null space)  $N(T)$  is the set  $\{v \in V / T(v) = 0\}$ . The range of  $T$ , denoted  $R(T)$  is the set  $\{w \in W / w = T(v) \text{ for some } v \text{ in } V\}$

Th:  $N(T) \subseteq V$ ,  $R(T) \subseteq W$

Th If  $V, W$  are vector spaces and  $B = \{v_1, v_2, \dots, v_n\}$  is a basis for  $V$  and  $T: V \rightarrow W$  is a linear transformation then  $R(T) = \text{Span}(T(v_1), \dots, T(v_n))$

Ex What are the null space and Range of

$$T: P(\mathbb{R}) \rightarrow P(\mathbb{R})$$

$$T(p) = p'$$

Ex  $T: F^\infty \rightarrow F^\infty$

$$T(x_1, x_2, \dots, x_n, \dots) = (x_2, x_3, \dots)$$

Quiz T F T  $V \rightarrow W$

$v_1 \dots v_m$  lin indep then

$T(v_1) T(v_2) \dots T(v_n)$  lin indep

F example  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$   
 $T(x, y) = (x, 0)$

$T(v_1) T(v_2) \dots T(v_n)$  lin indep

$v_1 v_2 \dots v_n$  lin indep

True

$$a_1 v_1 + a_2 v_2 + \dots + a_n v_n = 0$$
$$T(\quad) (\quad) (\quad) = 0$$