

Lesson 21

More about Generalized eigenvectors.

Th 1: Assume $T \in \mathcal{L}(V)$

$\dim V = n$, then

$$V = \mathcal{N}(T^n) \oplus \mathcal{R}(T^n)$$

..

Th 2: Assume $T \in \mathcal{L}(V)$, $\dim V = n$,
 $F = \mathbb{C}$, then the generalized eigenvectors
of T span V

Proof by induction on n

Th3: Let $T \in \mathcal{L}(V)$, $\dim V = n$
 $F = \mathbb{C}$ and let d_1, d_2, \dots, d_m
 be the distinct eigenvalues for T

Then :

① $V = K_{d_1} \oplus K_{d_2} \oplus \dots \oplus K_{d_m}$

② K_{d_l} is invariant for T
 for all $l = 1, \dots, m$

③ There is a basis B of V
 made of generalized eigenvectors of
 T such that T_B^B is a block matrix

$$T_B^B = \begin{bmatrix} A_1 & & & 0 \\ & A_2 & & \\ & & \dots & \\ 0 & & & A_m \end{bmatrix}$$

Each matrix A_l is a $n_l \times n_l$ matrix, where

n_l is the dimension of K_{d_l} $A_l = \begin{bmatrix} d_l & * & * \\ 0 & \ddots & \\ \vdots & & 0 & d_l \end{bmatrix}$

In particular T_B^B is upper triangular

Let's choose bases B_L for K_{λ_L} in the following way:

remember that

$$E_{\lambda_L} = N(T - \lambda_L I) \subset N(T - \lambda_L I)^2 \subset N(T - \lambda_L I)^3 \cdots \subset N(T - \lambda_L I)^{h_L} = N(T - \lambda_L I)^{h_L+1} = \cdots = N(T - \lambda_L I)^n$$

K_{λ_L}

$v_1 \cdots v_k$ basis for $N(T - \lambda_L I)$

$v_1 \cdots v_k, v_{k+1} \cdots v_{k+j_1}$ basis for $N(T - \lambda_L I)^2$

$v_1 \cdots v_k, v_{k+1} \cdots v_{k+j_1}, v_{k+j_1+1} \cdots v_{k+j_1+j_2}$ is a basis for $N(T - \lambda_L I)^3$

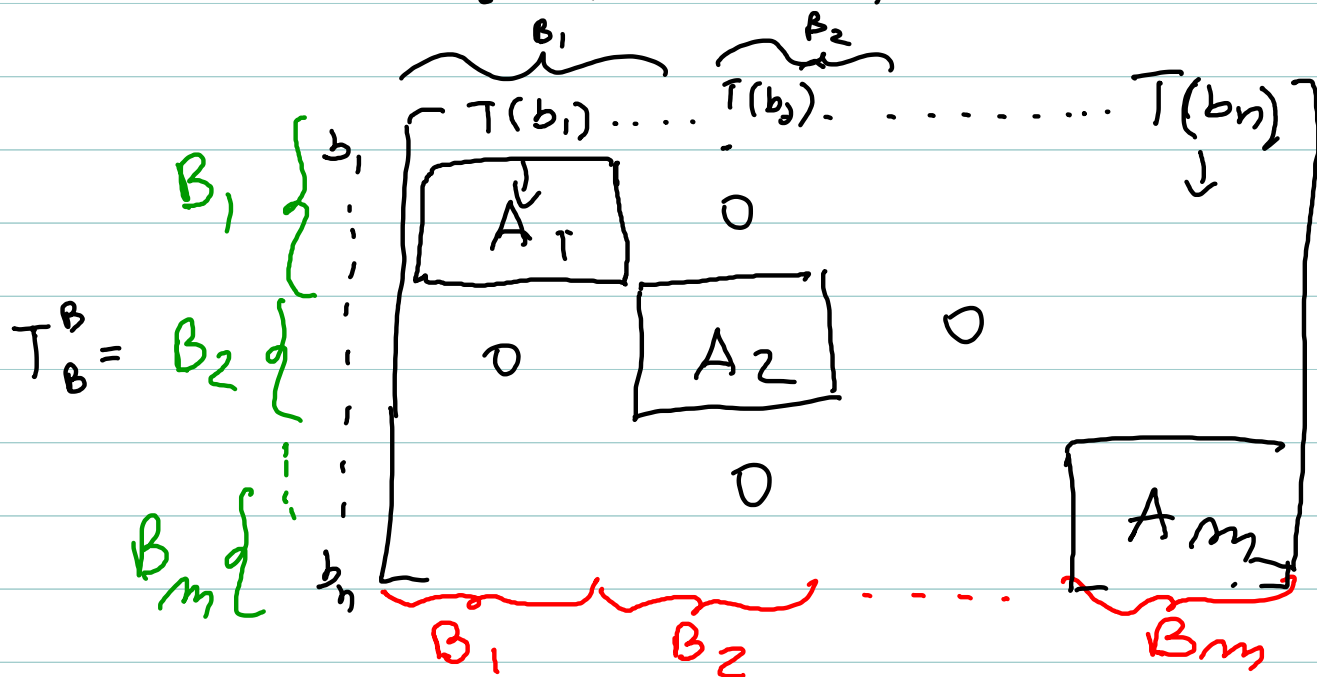
$\underbrace{v_1 \cdots v_k}_{B_1}, \underbrace{v_{k+1} \cdots v_{k+j_1}}_{B_2}, \underbrace{v_{k+j_1+1} \cdots v_{k+j_1+j_2}}_{B_3}, \dots, v_{n_L}$

is a basis for K_{λ_L}

$$B = \cup B_L$$

What does T_B^B look like?

Recall each K_{λ_L} is T invariant



What does A_L look like?

$$\begin{array}{c}
 \left. \begin{array}{c} v_1 \\ \vdots \\ v_k \\ v_{k+1} \\ \vdots \\ v_{n_L} \end{array} \right\} \left[\begin{array}{cccc}
 \overbrace{T(v_1)} & \cdots & \overbrace{T(v_k)} & \overbrace{T(v_{k+1})} & \overbrace{T(v_{k+2})} & \cdots & \overbrace{T(v_{n_L})} \\
 \lambda_L & & & * & & & x \\
 0 & \lambda_L & & x & & & x \\
 \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\
 \vdots & \vdots & \lambda_L & \lambda_L & & & x \\
 \vdots & \vdots & \vdots & 0 & & & \vdots \\
 \vdots & \vdots & \vdots & \vdots & \lambda_L & & \vdots \\
 \vdots & \vdots & \vdots & \vdots & \vdots & \lambda_L & \vdots \\
 \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \lambda_L
 \end{array} \right]
 \end{array}$$

$$T(v_1) = \lambda_L v_1 \cdots T(v_k) = \lambda_L v_k$$

$$T(v_{k+1}) = \underbrace{(T - \lambda_L I)}_{\in N(T - \lambda_L I)} v_{k+1} + \lambda_L v_{k+1}$$

$$T(v_{k+j_1+1}) = \underbrace{(T - \lambda_L I)}_{\in N(T - \lambda_L I)^2} v_{k+j_1+1} + \lambda_L I v_{k+j_1+1}$$

$$T(v_{n_L}) = \underbrace{(T - \lambda_L I)}_{\in N(T - \lambda_L I)^2} v_{n_L} + \lambda_L I v_{n_L}$$

n_{λ} is the dim of K_{λ}
 n_{λ} is the algebraic multiplicity
of λ

$n_{\lambda} \geq h_{\lambda}$ so $K_{\lambda} = N(T - \lambda I)^{h_{\lambda}}$

Th 4: : Let $T \in \mathcal{L}(V)$ $\dim V = n$

λ an eigen value of T with algebraic multiplicity m . Then $\dim(K_\lambda) = m$

$$\text{and } K_\lambda = \mathcal{N}(T - \lambda I)^m$$

Proof Consider the proof of the previous th where $\dim(K_{\lambda_i}) = n_i$ and all the vectors in the

chosen basis of K_{λ_i} are in $\mathcal{N}(T - \lambda_i)^{h_i}$. $n_i \geq h_i$ so

$$K_{\lambda_i} = \mathcal{N}(T - \lambda_i)^{n_i}. \quad T_B^B \text{ in}$$

the proof of the previous th.

has $n_i \lambda_i$ on the diagonal and it has characteristic polynomial

$$(x - \lambda_1)^{n_1} (x - \lambda_2)^{n_2} \dots (x - \lambda_m)^{n_m}$$

so $n_i =$ algebraic multiplicity of λ_i

Jordan canonical form

For a better chosen B

T_B^B has the form

$$\left[\begin{array}{cccc} \lambda_1 & * & & 0 \\ & \lambda_1 & * & \\ & & \ddots & \ddots \\ & & & \lambda_1 & * & \\ & & & & \lambda_2 & * \\ & & & & & \ddots \\ & & & & & & \lambda_2 & * \\ & & & & & & & \ddots \\ & & & & & & & & \lambda_m & * \\ & & & & & & & & & \lambda_m & * \\ & & & & & & & & & & 0 \end{array} \right]$$

* can be 0 or 1