

# Lesson 17

Invariant subspaces

Eigenvalues and eigenvectors.

read 5.1

Def: A linear transformation

$T: V \rightarrow V$  is called a

(linear) operator

Def: A linear transformation

$T: V \rightarrow \mathbb{F}$  is called

a (linear) functional

Def: A linear operator  $T$  on a finite dimensional vector space  $V$  is called diagonalizable if  $V$  has an ordered basis  $B$  s.t.  $T_B^B$  is a diagonal matrix

Def A  $n \times n$  matrix is called diagonalizable if  $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$   
 $Tx = Ax$   
is diagonalizable.

308 Connection

$A = T_E^E$  where  $E$  is the canonical basis

$$T_B^B = \begin{matrix} I_B & T_E^E & I_E^E \\ \parallel & \parallel & \parallel \\ & & B \end{matrix}$$

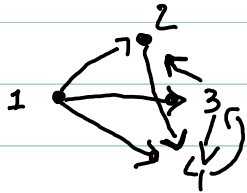
$$D = P^{-1} A P \quad \text{or}$$

$$P D P^{-1} = A$$

Useful to compute powers of  $A$

1 Million dollar eigenvector.

google algorithm to display web pages from a search.



We can think of web pages as vertices of a directed graph. The edges of the graph represent page links. We can represent this information using a matrix, where if a vertex has  $n$  outgoing edges, each vertex  $x$  is given a weight of  $1/n$ .

$$\begin{matrix} & \begin{matrix} 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \\ 4 \end{matrix} & \begin{pmatrix} 0 & 0 & 0 & 0 \\ 1/3 & 0 & 1/2 & 0 \\ 1/3 & 0 & 0 & 1 \\ 1/3 & 1 & 1/2 & 0 \end{pmatrix} \end{matrix} = A$$

Question: if I start from page 1, 2, 3, 4

with equal probability and I keep clicking at random one of the links I see on the page, after  $n$  steps what is the probability I am on page 4?

Answer involves computing powers of  $A$ .

Def: Suppose  $T \in \mathcal{L}(V)$  and  $U \subseteq V$ .  $U$  is invariant under  $T$  if  $T(U) \subseteq U$  i.e.  $v \in U \Rightarrow T(v) \in U$

Ex 1: Given  $T: V \rightarrow V$ ,  $N(T)$ ,  $R(T)$ ,  $V$ ,  $\{0\}$  are all invariant under  $T$ ,

Ex 2: for a fixed  $v \in V$

$W = \text{span} \{ T^n x \mid n \geq 0 \} = \text{span} \{ x, Tx, T^2x, \dots \}$

is invariant under  $T$

Note: if  $V = U_1 \oplus U_2 \oplus \dots \oplus U_n$  and  $T \in \mathcal{L}(V)$

and  $T(U_j) \subseteq U_j$  then in order

to understand  $T$  we just need to

understand  $T|_{U_j}: U_j \rightarrow U_j$  for  $j=1 \dots n$

The easiest situation is when each  $U_j$  has

dimension 1

Ex 3: Consider  $T: V \rightarrow V$

What are the  $\dim 1$  invariant subspaces?

$U = \text{span}(v)$   $T(v) \in \text{Span}(v) \Leftrightarrow T(v) = \lambda v$   
for some  $\lambda \in F$

Def: Given  $T \in \mathcal{L}(V)$  a non zero vector s.t.  
 $T(v) = \lambda v$  is called an eigenvector of  $T$   
 $\lambda$  is the associated eigenvalue

Ex 4: given  $T \in \mathcal{L}(P(\mathbb{R}))$   $T(p) = p'$

What are the eigenvalues and eigenvectors of  $T$ ?

If  $T(p) = p' = \lambda p$  then  $p$  and  $p'$  are polynomials  
of the same degree. This happens only if  $p = c$  and  $\lambda = 0$

Note if  $T \in \mathcal{L}(V)$  and  $\beta = \{v_1, v_2, \dots, v_n\}$

is a basis for  $V$  then  $T_\beta^\beta$  is diagonal iff

each  $v_i$  is an eigenvector for  $T$

in this case  $V = \text{span}(v_1) \oplus \text{span}(v_2) \oplus \dots \oplus \text{span}(v_n)$

Def: If  $A$  is an  $n \times n$  matrix eigenvectors  
eigenvalues of  $A$  are eigenvectors  
eigenvalues for  $L_A: \mathbb{R}^n \rightarrow \mathbb{R}^n$   $L_A(v) = Av$   
i.e.  $\lambda$  is an eigenvalue for  $A$  if there  
is a non zero vector  $v$  in  $\mathbb{R}^n$  st  
 $Av = \lambda v$ . Such a  $v$  is called an  
eigenvector for  $A$



Th 1: Given  $T \in \mathcal{L}(V)$ , where  $V$  is a finite dimensional vector space, the following are equivalent:

- 1)  $\lambda$  is an eigenvalue for  $T$
- 2)  $T - \lambda I$  is not injective:
- 3)  $T - \lambda I$  is not surjective
- 4)  $T - \lambda I$  is not invertible

Proof 1)  $\Leftrightarrow$  2)  $\lambda$  is an eigenvalue for  $T$  iff  $T(v) = \lambda v$  for some  $v \neq 0$ ,  $v \in V$  that is iff  $(T - \lambda I)v = 0$  iff  $N(T - \lambda I) \neq \{0\}$  iff  $T - \lambda I$  is not injective.

We already know 2) 3) 4) are equivalent (using  $\dim V = \dim N(T - \lambda I) + \dim R(T - \lambda I)$ )

Note: eigenvectors for  $\lambda$  are the non zero vectors in  $N(T - \lambda I)$

Thm If  $A$  is an  $n \times n$  matrix

$\lambda$  is an eigenvalue of  $A$  iff  $\det(A - \lambda I) = 0$

Proof assume  $v \neq 0$  and  $Av = \lambda v$

then  $(A - \lambda I)v = 0$  so  $A - \lambda I$  is

not invertible (308 stuff: columns

of  $A - \lambda I$  are dependent) so

$\det(A - \lambda I) = 0$

vice-versa if  $\det(A - \lambda I) = 0$

then  $A - \lambda I$  is singular and

therefore the system  $(A - \lambda I)x = 0$  has

infinitely many solutions so

there must be some  $v \neq 0$  s.t.

$(A - \lambda I)v = 0$  so  $Av = \lambda v$

Def  $\det(A - xI) = p(x)$

is called the characteristic polynomial

of  $A$

Example:

$$T: P_1(\mathbb{R}) \rightarrow P_1(\mathbb{R})$$

$$T(a+bx) = a+2b+3bx$$

Compute the eigenvalues of  $T$ :

① Choose some basis  $B$ :  $B = \{1, x\}$

$$\textcircled{2} \quad T_B^B = \begin{bmatrix} 1 & 2 \\ 0 & 3 \end{bmatrix}$$

③ Find the eigenvalues of  $B$ :

$$\det \begin{bmatrix} 1-\lambda & 2 \\ 0 & 3-\lambda \end{bmatrix} = (1-\lambda)(3-\lambda)$$

eigenvalues  $\lambda=1$ ,  $\lambda=3$

eigenvectors for  $\lambda=1$ : solve

$$\begin{bmatrix} 0 & 2 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \text{sol: } \{(x, 0) \mid x \in \mathbb{R}\}$$

if  $(1, 0)$  is eigenvector for  $T_B^B$

$p(x) = 1 + 0x$  is eigenvector for  $T$

eigenvectors for  $\lambda=3$  solve

$$\begin{bmatrix} -2 & 2 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

sol  $\{ (x, x) \mid x \in \mathbb{R} \}$

if  $(1, 1)$  is eigenvector for  $T_B^B$

$p(x) = 1 \cdot 1 + 1 \cdot x$  is eigenvector for  $T$